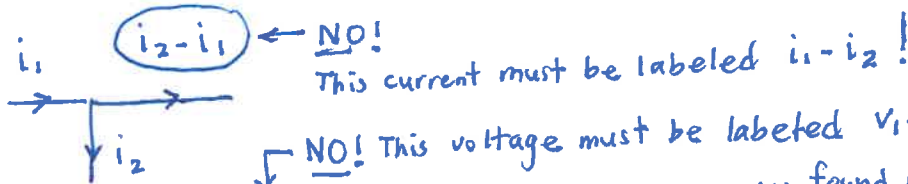
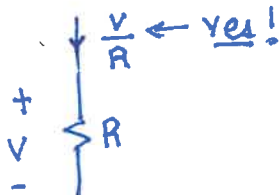
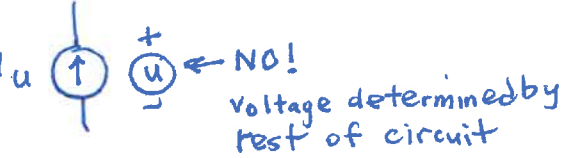
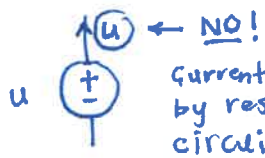


(Will)

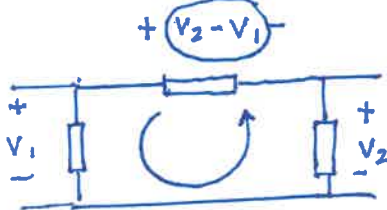
10

Errors that Can NOT be Tolerated!

Be Forewarned = These type of errors generally lead to a final grade of D or F!!!



NO! This voltage must be labeled $V_1 - V_2$... found by CCW KVL!



$\angle -1 + j1 \neq \tan^{-1}(\frac{1}{-1}) = -45^\circ$ NO!

$\angle -1 + j1 = \angle \begin{matrix} 1 \\ 1 \end{matrix} = 180^\circ - \tan^{-1}(\frac{1}{1}) = 180^\circ - 45^\circ = 135^\circ$ YES!

$\angle -\frac{1}{2} - j\frac{\sqrt{3}}{2} \neq \tan^{-1}(\frac{-\sqrt{3}/2}{-1/2}) = \tan^{-1}(\sqrt{3}) = 60^\circ$ NO!

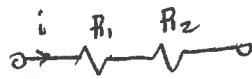
$\angle -\frac{1}{2} - j\frac{\sqrt{3}}{2} = \angle \begin{matrix} \sqrt{3}/2 \\ 1/2 \end{matrix} = 180^\circ + \tan^{-1}(\frac{\sqrt{3}/2}{1/2}) = -180^\circ + 60^\circ = -120^\circ$ YES!

$\frac{u}{s + \frac{1}{s}} \neq \frac{u}{s} + \frac{u}{\frac{1}{s}}$ (You MUST be able to do basic algebra!)

PLEASE
Don't
Ever
Make
Any of
These

Errors!!!
(PLEASE!!!)

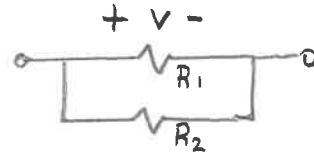
Please don't ever confuse the following=



$$R_{\text{series}} = R_1 + R_2$$

(same current i passes through R_1, R_2 & R_{series} !)

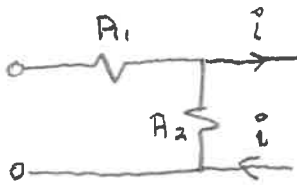
and



$$R_{\text{parallel}} = R_1 \parallel R_2 \triangleq \frac{R_1 R_2}{R_1 + R_2}$$

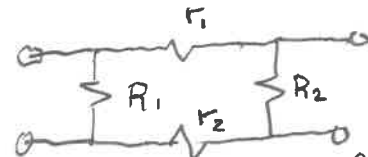
$$\text{or } \frac{1}{R_{\text{parallel}}} = \frac{1}{R_1} + \frac{1}{R_2}$$

(same voltage V is across $R_1, R_2, R_{\text{parallel}}$!)



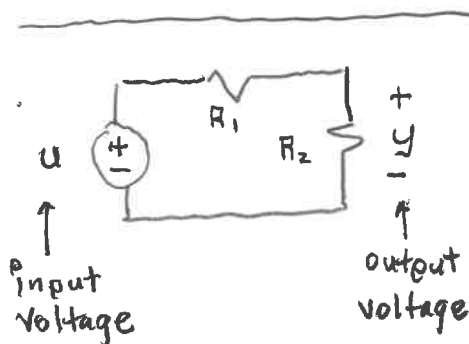
Here, R_1 & R_2 are in series
iff $i = 0$!!!

(so that same current passes through R_1 & R_2 !)

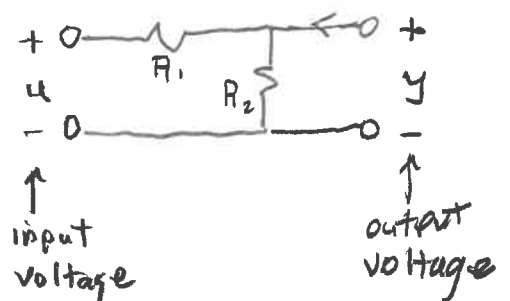
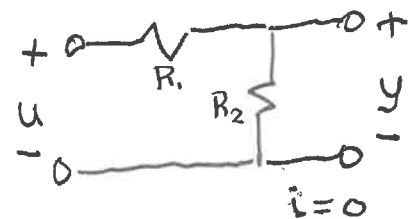


Here, R_1 & R_2 are in parallel
iff $i_1 = i_2 = 0$

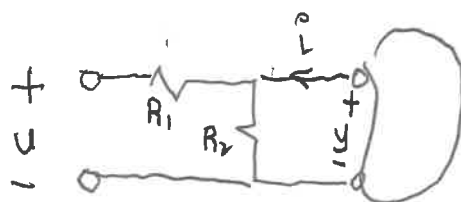
(so that same voltage appears across R_1 & R_2 !)



is equivalent to

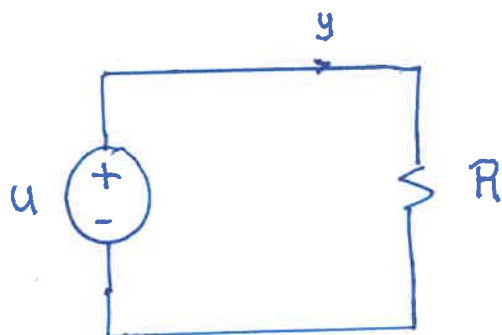


The above are NOT
the same as:



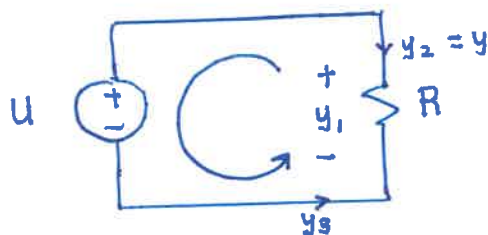
The are the same
iff $i = 0$!

Example 1 (1 Resistor!)



Relate y to u ($\neq R$)

solution:



Note: 1st we find y_1
then $y_2 = y_1$!

We can then also find $y_3 = -y$

$$y_1 = u \text{ by } \begin{matrix} \text{ccw} \\ \text{KVL} \end{matrix}$$

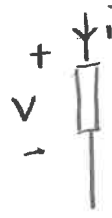
$$y_2 = y = \frac{y_1}{R} = \frac{u}{R}$$

$$y_3 = -y_2 = -\frac{u}{R} = -y$$



Note: The numbering of the variables y_1, y_2, y_3 has been selected to indicate the ordering of the logical steps to be taken toward solving for y !

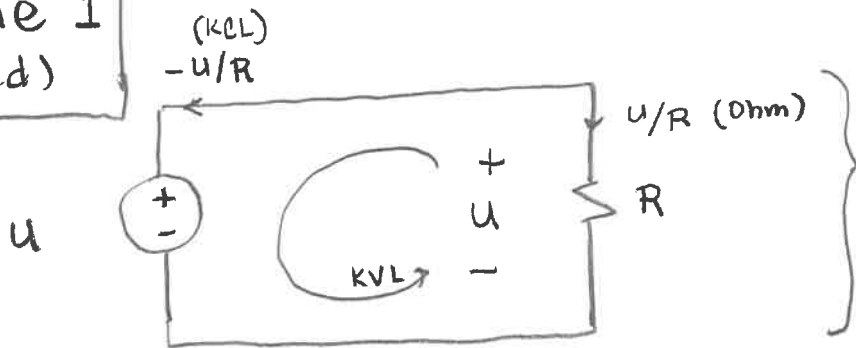
Power Concepts



$$P_{abs} \triangleq v i$$

$$P_{del} = -P_{abs}$$

Example 1 (continued)



This summarizes the analysis on the previous page.

$$P_{abs}^u = (u) \left(-\frac{u}{R}\right) = -\frac{u^2}{R} < 0$$

Negative P_{abs}^u means that u is actually delivering power

$$\text{i.e. } P_{del}^u = -P_{abs}^u = \frac{u^2}{R} > 0$$

$$P_{abs}^R = (u) \left(\frac{u}{R}\right) = \frac{u^2}{R} > 0$$

Note:

$$P_{del}^u = P_{abs}^R$$

Sum of absorbed powers within a cut is always zero!

$$P_{abs}^u + P_{abs}^R = 0$$

$$\left(-\frac{u^2}{R}\right) \quad \left(\frac{u^2}{R}\right)$$

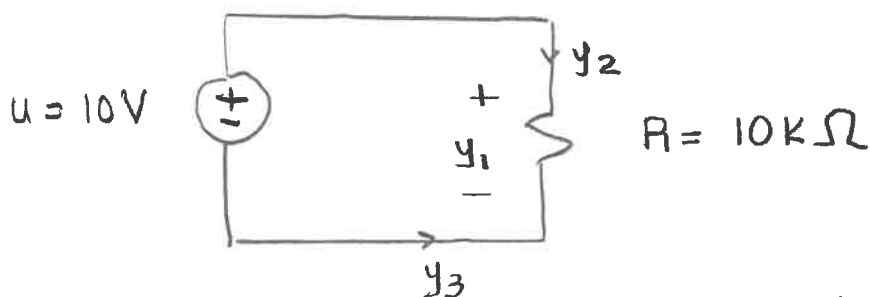
Power delivered by u is equal to power absorbed by R

Sum of delivered powers within a cut is always zero!

$$P_{del}^u + P_{del}^R = 0$$

$$\left(\frac{u^2}{R}\right) \quad \left(-\frac{u^2}{R}\right)$$

Problem 1



a) Determine y_1

b) Determine y_2

c) Determine y_3

d) Determine power absorbed p_R^{abs} by R.

e) Determine power delivered p_R^{del} by R.

f) Determine power absorbed p_u^{abs} by u.

g) Determine power delivered p_u^{del} by u.

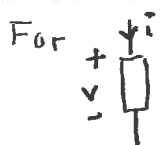
Note: Always specify your associated logic or reasoning!

Note: In this problem, y_2 represents "conventional" current flow!

How do the electrons flow in this problem?

In this course, we focus almost exclusively on conventional current flow \rightarrow not on electron current flow...

Some Basic Power Concepts



For

$$p_{abs} \triangleq v i$$

$$p_{del} \triangleq -p_{abs}$$

means

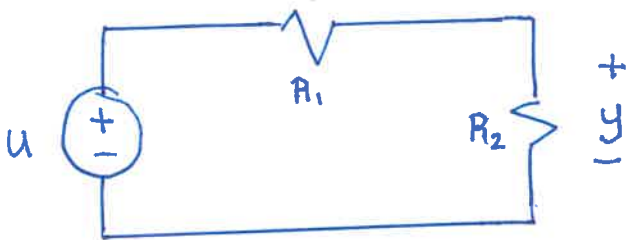
\triangleq "equals by definition"

Note:

conventional current flow is opposite electron current flow!

Example 2

(Voltage Divider)



Relate y to u
(3 R_1, R_2)

solutions:

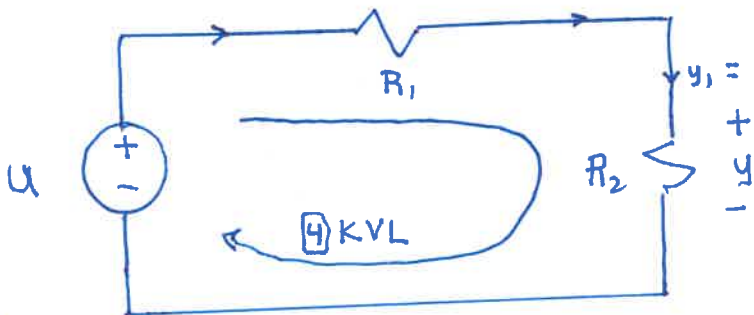
$$R_1 y_2 = R_1 \left(\frac{y}{R_2} \right)$$

Ohm \rightarrow II

 $+ y_3 -$

7 KCL

$$y_2 = y_1 = y/R_2$$



Note:

1st we find y_1

then y_2

then 43

then step 4 is

a KVL that

yields the

desired

equation

relating y

to R_1, R_2, \dots !

NOTE:

Don't ever
actually
write/create
the unnecessary
variables
 y_1, y_2, y_3 !

[4] KVL: $u = \underbrace{y_3}_{\text{ohm}} + y$

$$U = \frac{y_3}{R_1} + y$$

$$= \left(\frac{R_1}{R_2} + 1 \right) y$$

$$= \left(\frac{R_1 + R_2}{R_2} \right) y$$

(algebra) \Rightarrow

$$y = \left(\frac{R_2}{R_1 + R_2} \right) u \Rightarrow$$

$$I = y_2 = y_1 = y/R_2$$

$$i = \frac{u}{R_1 + R_2} = \frac{u}{R_{\text{series}}}$$

$$\Rightarrow y_3 = R, i \Rightarrow$$

$$y_3 = \left(\frac{R_1}{R_1 + R_2} \right) u$$

$$R_{\text{series}} = R_1 + R_2$$

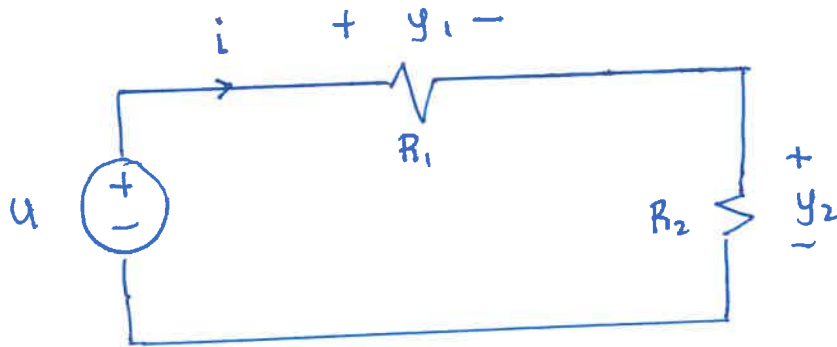


PLEASE!

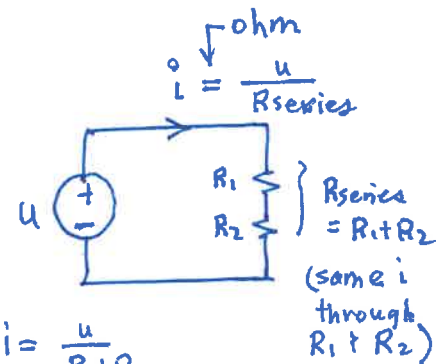
Doing so
causes
GREAT
Harm

Example 2 (Voltage Divider Summary)

Relate y_1, y_2, i
to u (R_1, R_2)

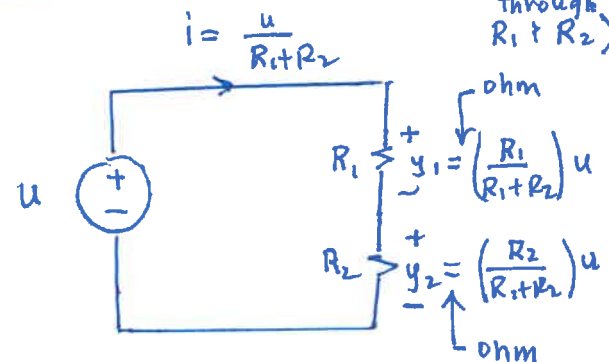


$$i = \frac{u}{R_{\text{series}}} = \frac{u}{R_1 + R_2}$$



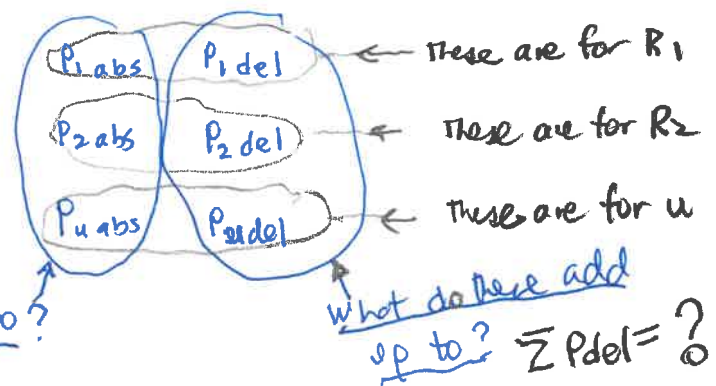
ohm
 $y_1 = R_1 i \Rightarrow y_1 = \left(\frac{R_1}{R_1 + R_2} \right) u$

ohm
 $y_2 = R_2 i \Rightarrow y_2 = \left(\frac{R_2}{R_1 + R_2} \right) u$



Problem 2

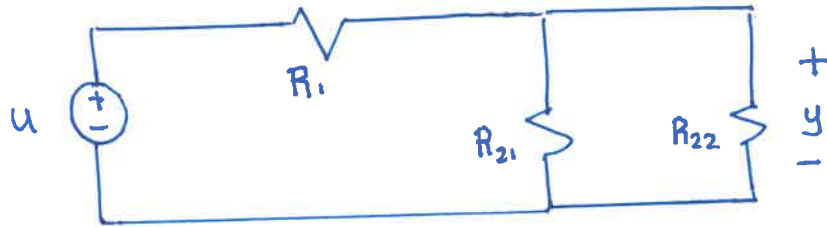
Find power absorbed & delivered by each component of circuit:



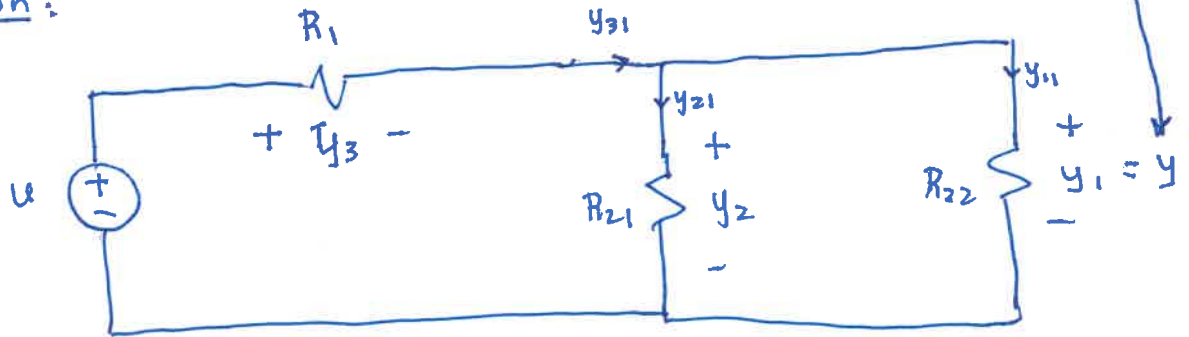
Example 3

(Voltage Divider + 1 Extra Resistor)

Relate y to u
($\rightarrow R_1, R_{21}, R_{22}$)

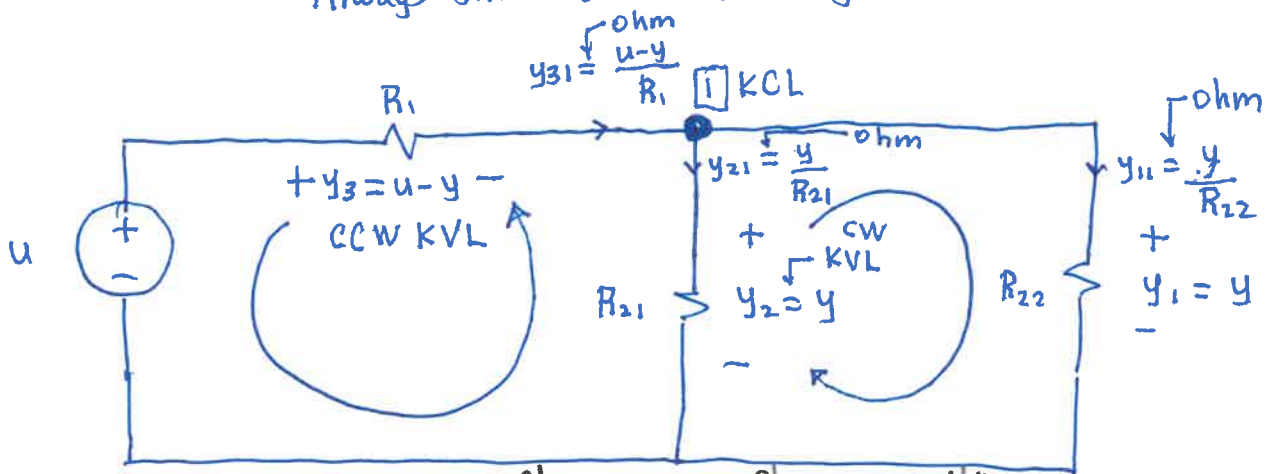


solution:

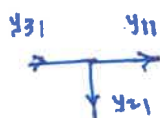


Note: the variable numbering $y_1, y_{11}, y_2, y_{21}, y_3, y_{31}$ has been selected to indicate the logical steps toward finding y !

Always show all work in your circuit:



[1] KCL =
(+ohm)

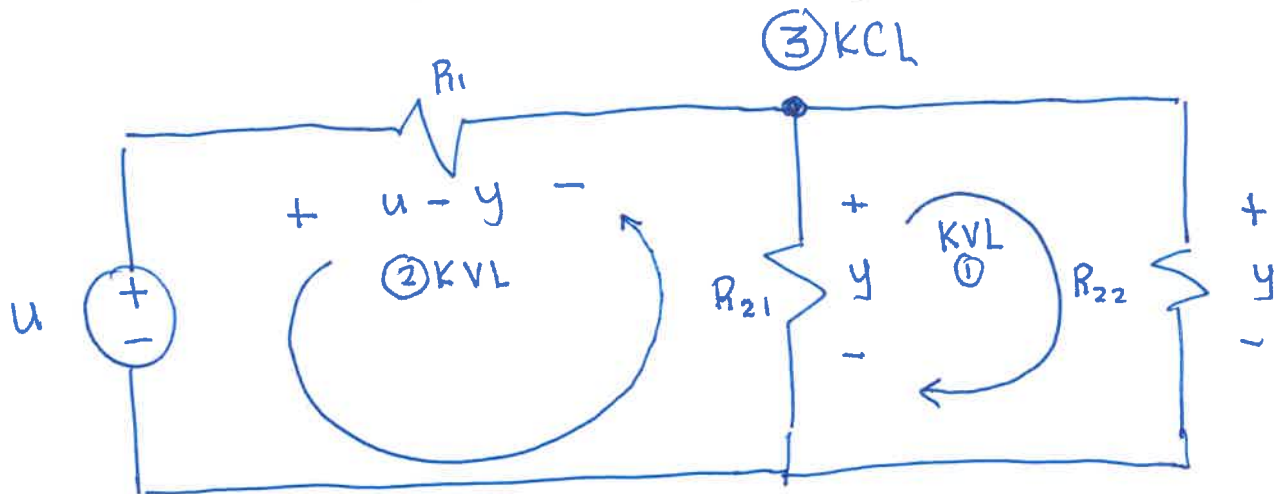


$$\frac{u-y}{R_1} = \frac{y}{R_{21}} + \frac{y}{R_{22}}$$

← Desired equation relating y to u
($\rightarrow R_1, R_{21}, R_{22}$)

Example 3

the above
Here is how ~~it~~ should look like ^(all) like your homework:
~~the above~~



$$\textcircled{3} \text{ KCL: } \left(\frac{u-y}{R_1} \right) = \left(\frac{y}{R_{21}} \right) + \left(\frac{y}{R_{22}} \right)$$

(ohm) KCL ohm ohm

always place a box around
eq relating y to u !

algebra:

\Rightarrow

$$\frac{u}{R_1} = y \left[\frac{1}{R_1} + \frac{1}{R_{21}} + \frac{1}{R_{22}} \right]$$

$$= \frac{u}{R_1} + y \left[\frac{1}{R_{21}} + \frac{1}{R_{22}} \right]$$

R_{21} & R_{22} are said to be in parallel

$$\frac{1}{R_2} = \frac{1}{R_{21}} + \frac{1}{R_{22}} \Rightarrow R_2 = R_{21} \parallel R_{22}$$

since the same voltage y appears across each!

$$R_2 = R_{21} \parallel R_{22} = \frac{R_{21} R_{22}}{R_{21} + R_{22}}$$

Example 3

$$\frac{1}{R_2} = \frac{1}{R_{21}} + \frac{1}{R_{22}}$$

more algebra
 \Rightarrow

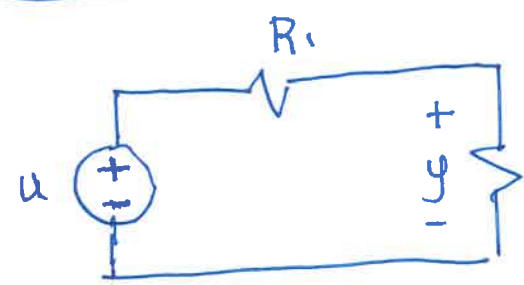
$$\frac{u}{R_1} = \frac{y}{R_1} + \frac{y}{R_2}$$

where

$$R_2 = R_{21} \parallel R_{22} = \frac{R_{21} R_{22}}{R_{21} + R_{22}}$$

Now we are back to Example 2 with

VERY CRITICAL OBSERVATION!



$$R_2 \triangleq (R_{21} \parallel R_{22})$$

solving for y
 \Rightarrow

$$\frac{u}{R_1} = y \left[\frac{1}{R_1} + \frac{1}{R_2} \right]$$

$$u = y \left[1 + \frac{R_1}{R_2} \right] = y \left[\frac{R_1 + R_2}{R_2} \right]$$

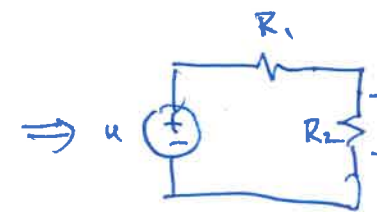
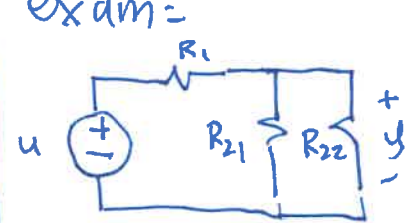
$$\Rightarrow y = \left[\frac{R_2}{R_1 + R_2} \right] u$$

PLEASE LEARN THIS!

$$R_2 \triangleq R_{21} \parallel R_{22} \triangleq \frac{R_{21} R_{22}}{R_{21} + R_{22}} \quad (\text{ASAP})$$

Summary:

Here is how all of the above should look like on an exam:



$$y = \left(\frac{R_2}{R_1 + R_2} \right) u$$

$$R_2 \triangleq (R_{21} \parallel R_{22}) \triangleq \frac{R_{21} R_{22}}{R_{21} + R_{22}}$$

This was MUCH Faster!

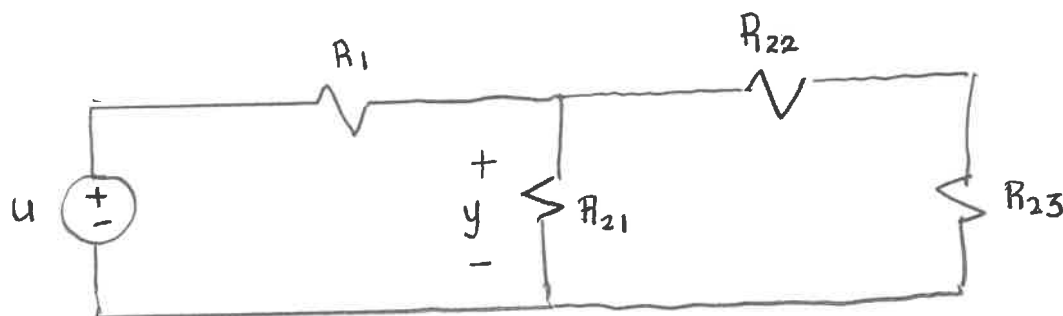
Cool ???



Problem 3

100

Relate y to u as specified below:



a) Relate y to u by using series-parallel concepts to make above circuit look like a voltage divider.

b) Relate y to u by using KVL, Ohm, KCL to propagate y rightward.

(You are NOT permitted to introduce any other new variables!

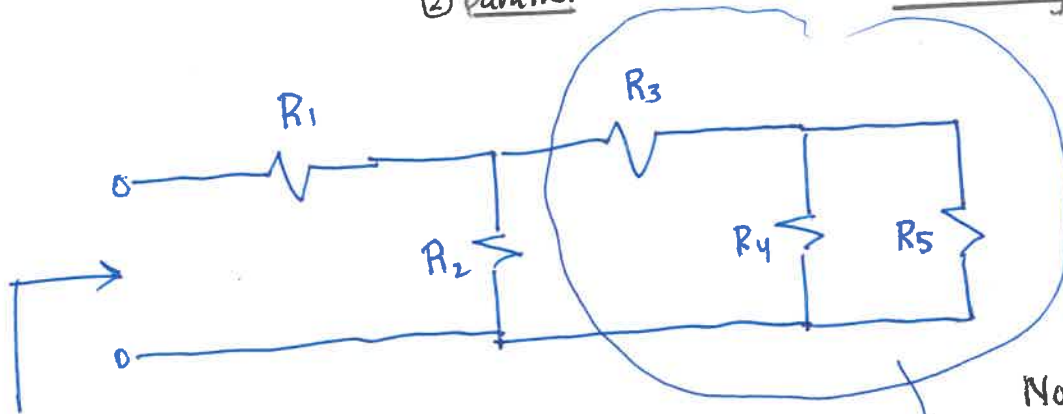
You MUST use y & u (& the R's))

Example 4

Finding the Equivalent Resistance

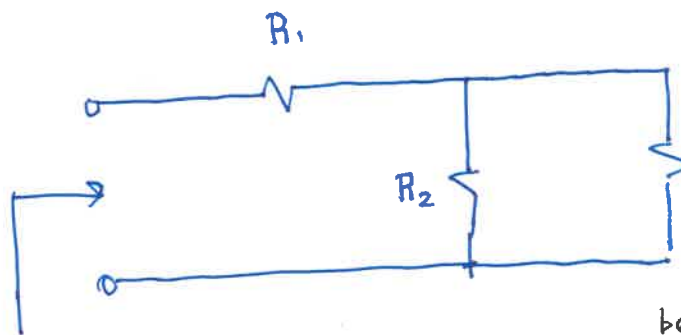
110

Recall: 2 devices are in ① series iff they have the same current through them
 ② parallel iff " " " " voltage across "



$R_{eq} = ?$

solution:



$$R_{eq} = R_1 + R_2 \parallel R$$

because they have the same current through them!

because they have the same voltage across them!

Note:

- 1) R_4 & R_5 are in parallel
- 2) R_3 is in series with $R_4 \parallel R_5$
- 3) R_2 is in parallel with $R = [R_3 + (R_4 \parallel R_5)]$
- 4) R_1 is in series with $R_2 \parallel R$

because they have the same current through them!

$$R_{eq} = R_1 + R_2 \parallel [R_3 + (R_4 \parallel R_5)]$$

where

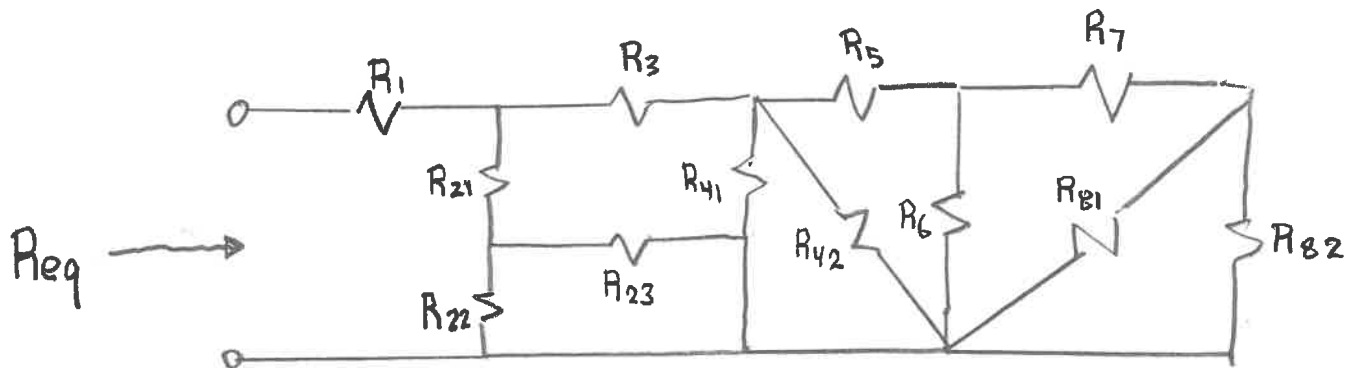
$$A \parallel B = \frac{AB}{A+B}$$

or $\frac{A+B}{AB} = \frac{1}{A \parallel B}$

or $\frac{1}{A} + \frac{1}{B} = \frac{1}{A \parallel B}$

Problem 4

Find R_{eq}



Hints = R_{81} & R_{82} are in parallel

R_{41} & R_{42} " " "

R_{22} & R_{23} " " "

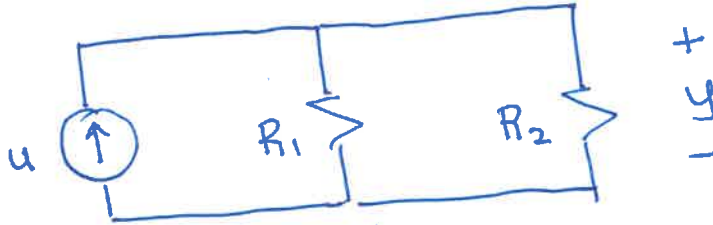
Hint: Redraw circuit several times
so that you can clearly show
how resistors combine!

Example 5

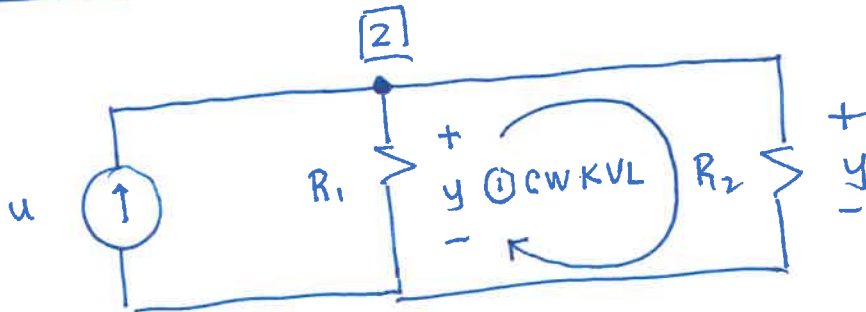
(Current Divider)

130

Relate y to u
($\exists R_1, R_2$)



solution:



[2] KCL:
(+ohm)

$$u = \left(\frac{y}{R_1} \right) + \left(\frac{y}{R_2} \right)$$

$$= y \left[\frac{1}{R_1} + \frac{1}{R_2} \right]$$

you do the algebra

$\frac{1}{R_{parallel}}$

Note: R_1 & R_2 are said to be in parallel since

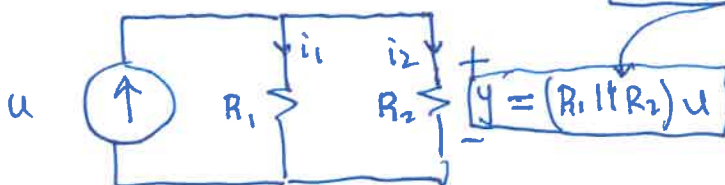
same voltage y appears across each!

current Divider Formulae

PLEASE LEARN THIS ASAP!

Concise Summary:

$$\Rightarrow R_{parallel} = R_1 \parallel R_2 = \frac{R_1 R_2}{R_1 + R_2}$$

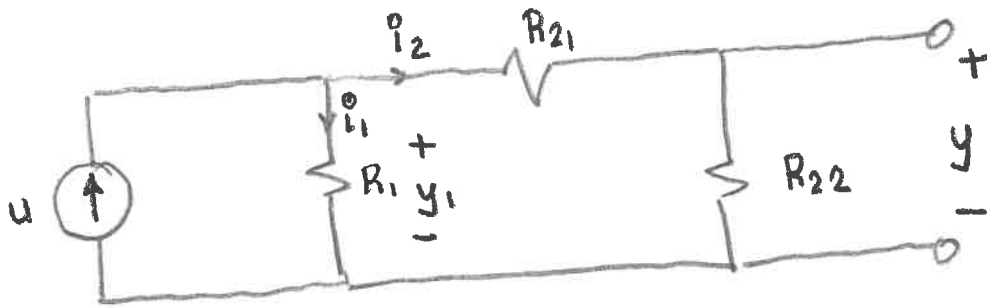


$$i_1 = \frac{y}{R_1} = \left(\frac{R_2}{R_1 + R_2} \right) u$$

$$i_2 = \frac{y}{R_2} = \left(\frac{R_1}{R_1 + R_2} \right) u$$

Problem 5

(Current Divider + 1 Extra Resistor)



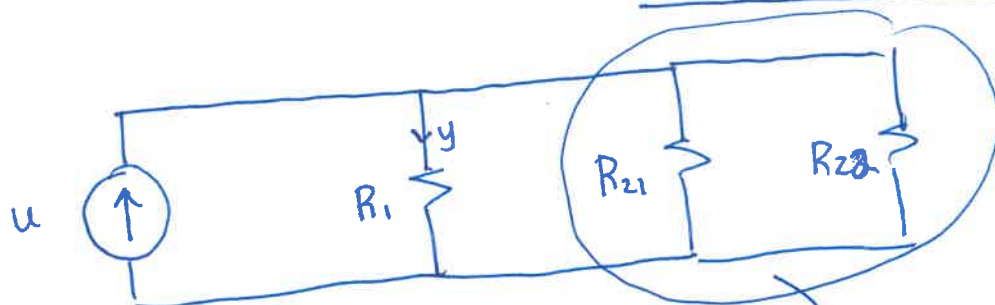
- a) Relate i_1 to u (R_1, R_{21}, R_{22}) without introducing another variable.
- b) " y_1 " " " " " " " "
- c) " i_2 " " " " " " " "
- d) " y " " " " " " " "

Note: The above are 4 separate problems!!!!
For each, draw a clean circuit & only use the variable specified (in addition to u, R_1, R_{21}, R_{22})

i.e. use KVL, KCL, & Ohm to propagate the specified variable around the circuit so that you can get an equation that relates the variable to u & the resistors. Then solve the equation for the variable of interest.

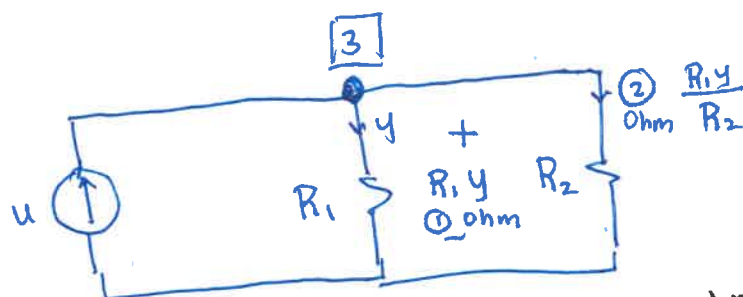
Example 6

(Current Divider with 1 extra Resistor)

Relate y to u ($\hat{R}_1, R_{21}, R_{22}$)solution:

R_{21} & R_{22} are in parallel
(since they have same voltage across them!)

$$R_2 \triangleq R_{21} \parallel R_{22} \\ \triangleq \frac{R_{21} R_{22}}{R_{21} + R_{22}}$$

NOTE:

This is circuit
in Example 5!

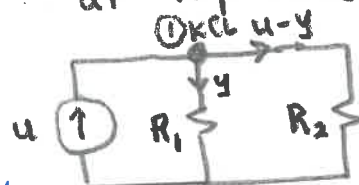
$$\begin{aligned} \text{[3] KCL} &= u = (y) + \left(\frac{R_1 y}{R_2} \right) \\ &= y \left[1 + \frac{R_1}{R_2} \right] \\ &= y \left[\frac{R_1 + R_2}{R_2} \right] \end{aligned}$$

$$y = \left(\frac{R_2}{R_1 + R_2} \right) u$$

Note: This is current i_1 in Example 5!

VERY Strong (MUST DO!!!)
Suggestion:

Redo this
with step (1)
being a KCL
at top node:

Note:

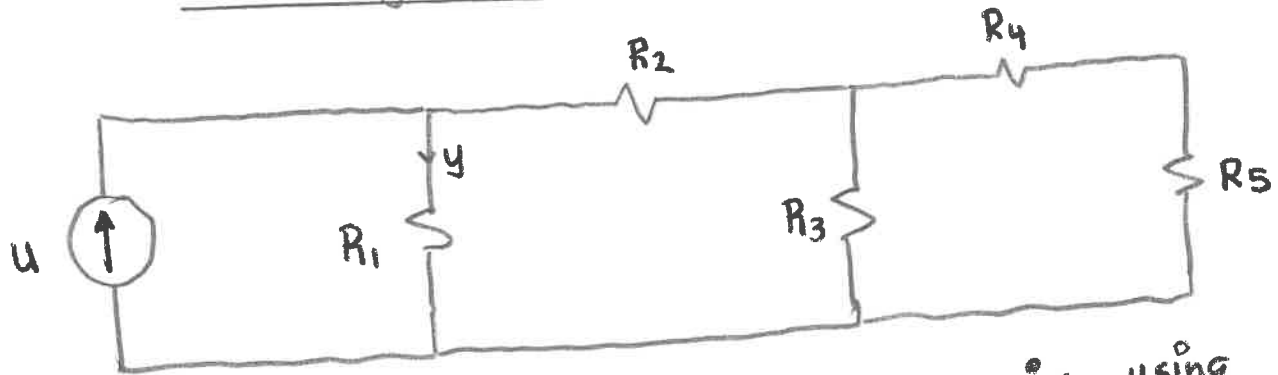
A KVL in right loop
will yield same result!

Problem 6

(Current Divider with Extra Resistors)

160

Relate y to u (3 resistors in circuit)



- a) Do by showing that $y = \left[\frac{\hat{R}_2}{R_1 + \hat{R}_2} \right] u$
- i.e. using series-parallel concepts to make cct look like current divider
- where $\hat{R}_2 \triangleq R_2 + [R_3 \parallel (R_4 + R_5)]$ in Example 5!

- b) Now relate y to u by using KCL, Ohm, KVL to propagate y rightward through the circuit
- (This is VERY IMPORTANT!)

Note = (1) You MUST show that the answer from (a) & that from (b) are identical!

(2) While (a) is MUCH easier & faster, the methods of (b) are MORE FUNDAMENTAL & hence MORE IMPORTANT TO MASTER!

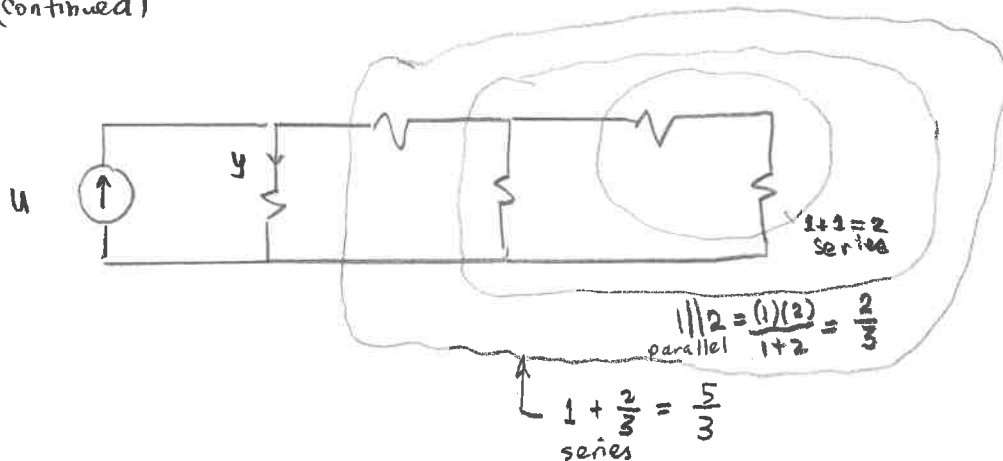
(3) By properly organizing your steps in (b), you can derive the nice, clean, elegant result stated in (a).

Example 6

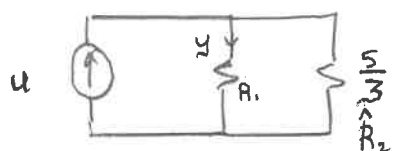
(Problem 6 with All $R_i = 1$)

161

(continued)



← using series-parallel concepts



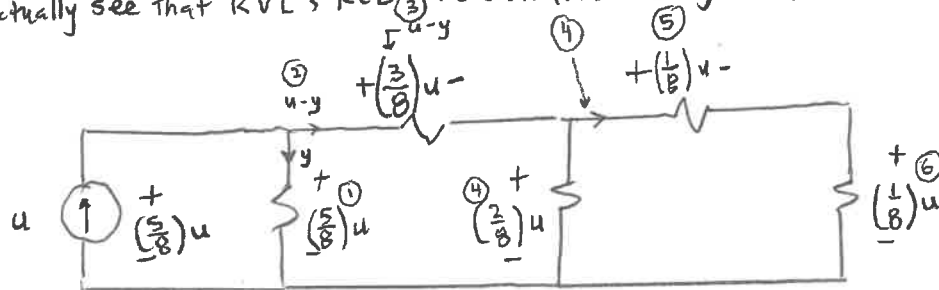
Current Division
Example 5

$$y = \left(\frac{\hat{R}_2}{R_1 + \hat{R}_2} \right) u = \left(\frac{\frac{5}{3}}{1 + \frac{5}{3}} \right) u$$

$$y = \left(\frac{5}{8} \right) u$$

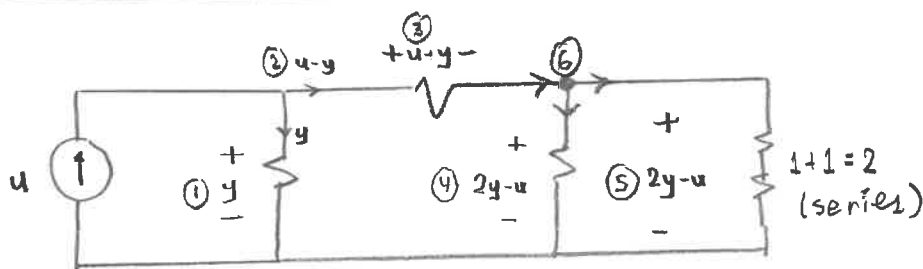
Compute all v's, i's in original circuit =

(to actually see that KVL & KCL are satisfied everywhere)



Note: KVL is satisfied within each loop & KCL is satisfied at each node!

KVL, KCL, Ohm with all $R_i = 1$



$$\begin{aligned} \textcircled{6} \text{ KCL} &= \left(\frac{u-y}{1} \right) = \left(\frac{2y-u}{1} \right) + \left(\frac{2y-u}{2} \right) \Rightarrow 2u-2y = 4y-2u+2y-u \\ &\Rightarrow 5u = 8y \\ &\Rightarrow y = \left(\frac{5}{8} \right) u \quad \checkmark \end{aligned}$$



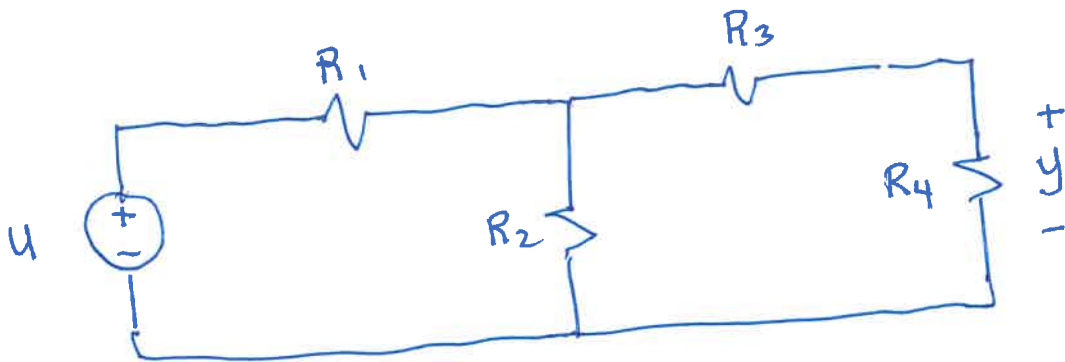
Note:

It is always useful to redo examples/problems with all $R_i = 1$ so that you can significantly elevate/strengthen your circuit strategizing!

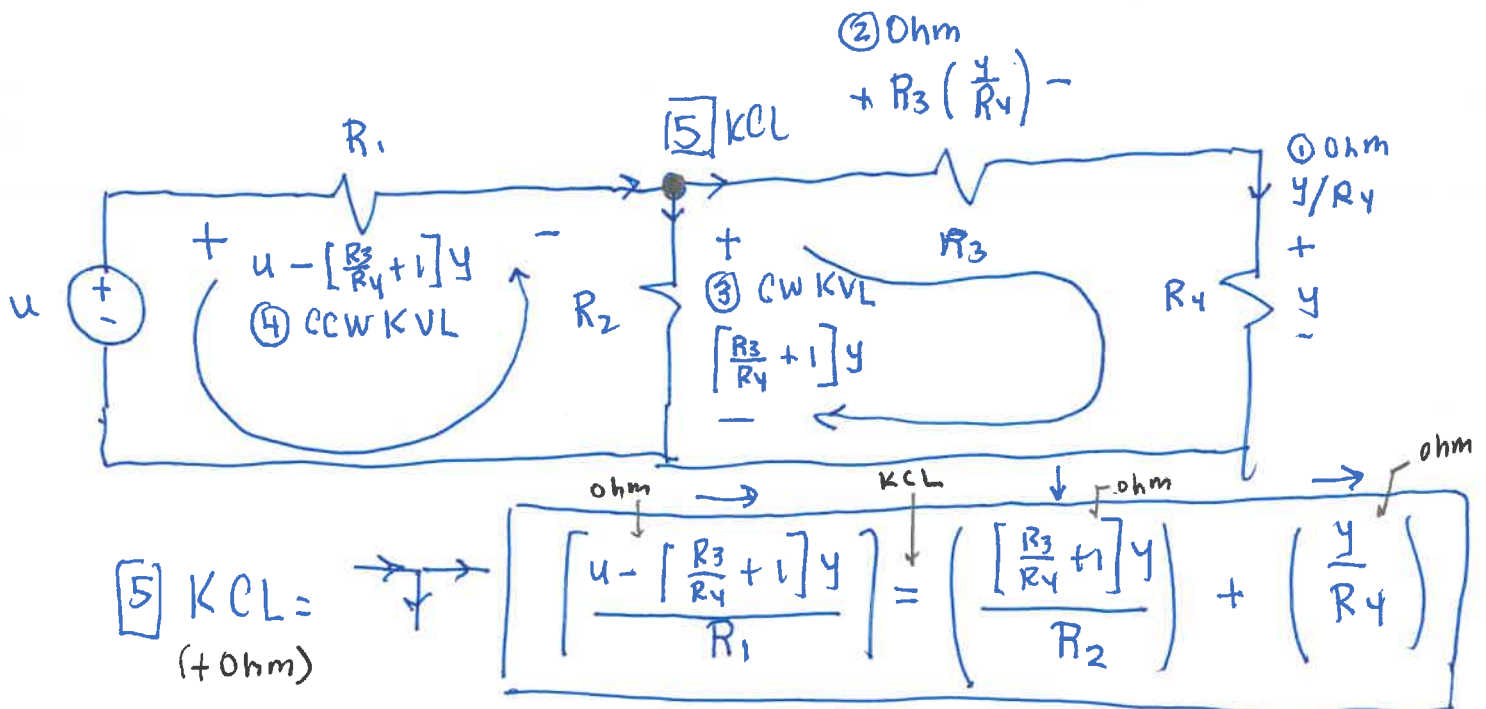
Example 7

(Propagating y leftward)a) Relate y to u

170



Solution: (always show all work on your circuit!)



Always box in your eq relating y to u !!!

algebra:

$$\frac{u}{R_1} = y \left[\frac{\frac{R_3}{R_4} + 1}{R_1} + \frac{\frac{R_3}{R_4} + 1}{R_2} + \frac{1}{R_4} \right]$$

$$y = \frac{1}{R_1} \left[\frac{1}{\frac{R_3}{R_4} + 1} + \frac{1}{\frac{R_3}{R_4} + 1} + \frac{1}{R_4} \right] u$$

if $R_3 = R_4$

$$= \frac{1}{R} \left[\frac{1}{\frac{3}{2} + \frac{3}{2} + 1} \right] u = \frac{1}{5} u \quad \text{for } R_3 = R_4$$

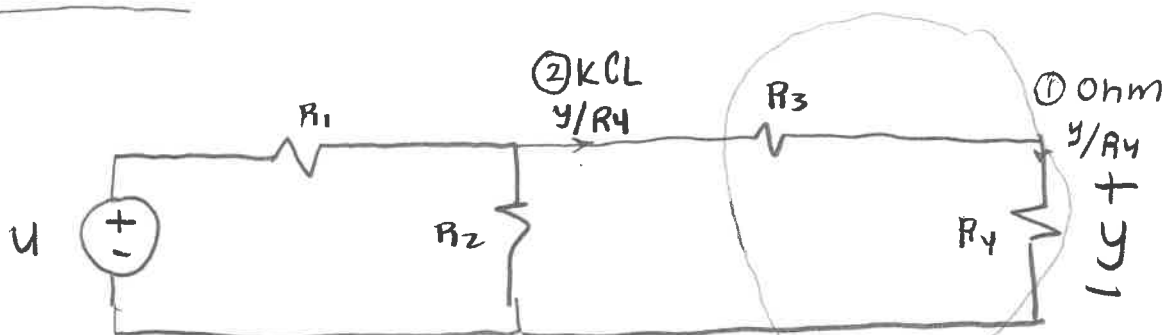
Example 7

171

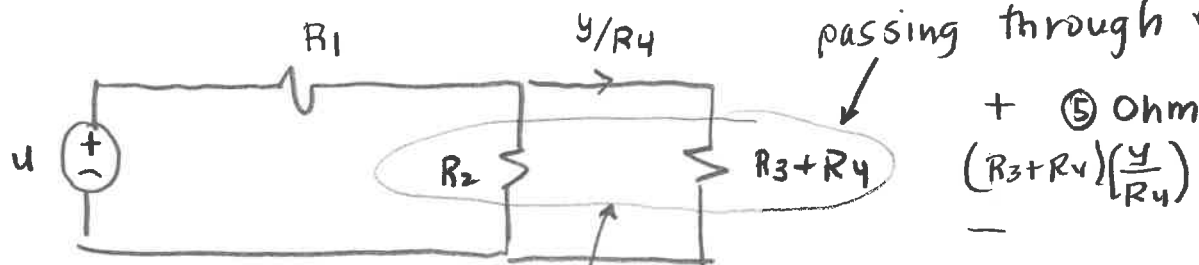
Use series-parallel concepts to relate y to u .

(Instead of straight KVL, KCL, Ohm as we did on pg 170)

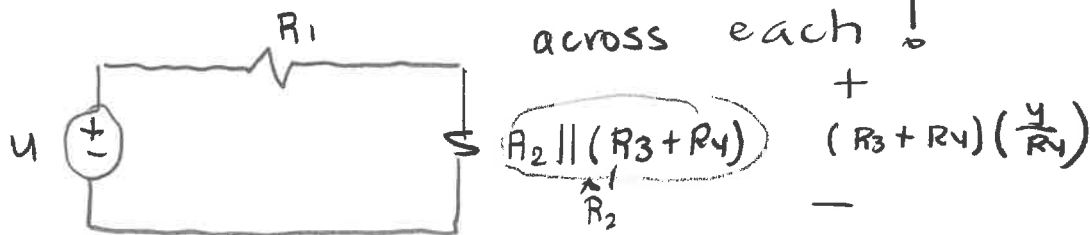
Solution:



③ R_3 & R_4 are in series with current y/R_4 passing through each!



⑥ R_2 & (R_3+R_4) are in parallel with voltage $(R_3+R_4)(\frac{y}{R_4})$ across each!



By voltage division (& KVL), it follows that voltage across R_2 is:

$$(R_3+R_4)\left(\frac{y}{R_4}\right) = \left(\frac{\hat{R}_2}{R_1 + \hat{R}_2}\right)u = \left[\frac{R_2 \parallel (R_3+R_4)}{R_1 + [R_2 \parallel (R_3+R_4)]}\right]u$$

Example 7

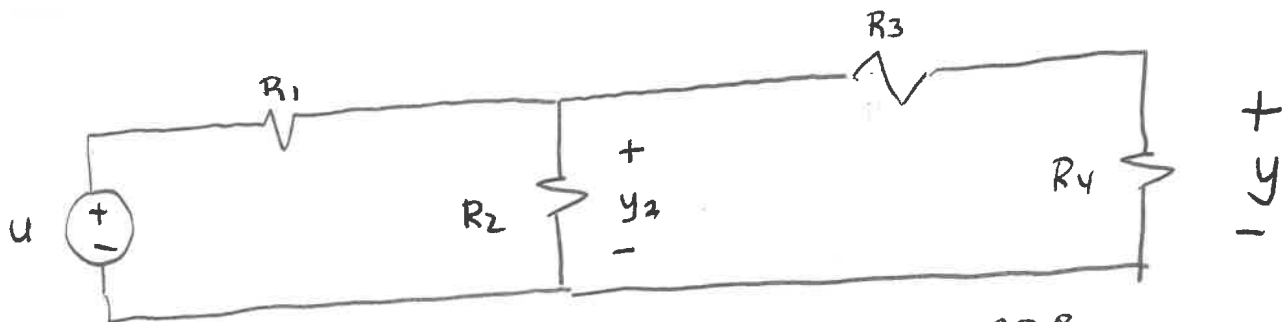
172

Algebra: From previous expression, we get the MUCH cleaner (simpler) looking result:

$$y = \left[\frac{R_4}{R_3 + R_4} \right] \left[\frac{R_2 \parallel (R_3 + R_4)}{R_1 + [R_2 \parallel (R_3 + R_4)]} \right] u$$

call this y_2

Lets visualize this on our circuit:



Note: By voltage division

$$y = \left(\frac{R_4}{R_3 + R_4} \right) y_2$$

where y_2 is voltage across parallel combination

$$\hat{R}_2 = R_2 \parallel (R_3 + R_4)$$

i.e. $y_2 = \left[\frac{\hat{R}_2}{R_1 + \hat{R}_2} \right] u$

$$= \left[\frac{R_2 \parallel (R_3 + R_4)}{R_1 + (R_2 \parallel (R_3 + R_4))} \right] u$$

u as on pg 170

CHECK:

Letting $R_1 = 1$ yields

$$y = \left[\frac{1}{1+1} \right] \left[\frac{1 \parallel 2}{1 + 1 \parallel 2} \right] u = \left[\frac{1}{2} \right] \left[\frac{2/3}{1 + 2/3} \right] u = \left(\frac{1}{2} \right) \left(\frac{2/3}{5/3} \right) u = \left(\frac{1}{5} \right) u \quad \checkmark$$

Note: This shows that the above result is readily (quickly) obtained by inspection using series-parallel voltage division concepts!

Always good to do a CHECK!

Example 7

(Propagating x rightward)

180

b

Relate x to u

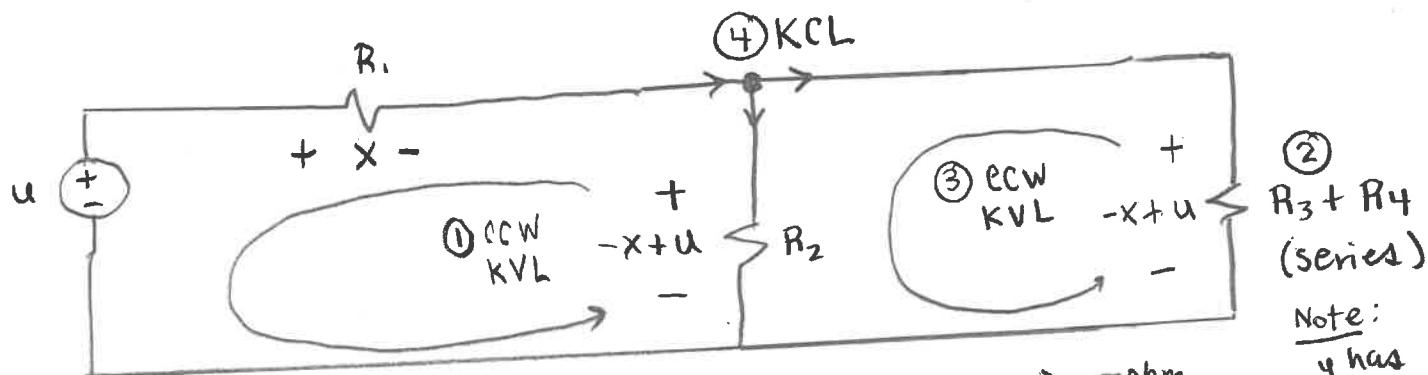
(don't use y ... only x !!!)

Then solve for x & y

when $R_1 = R$



Solution: (always show all work on your circuit!)



Note:
 y has been lost here!!!

$$\textcircled{4} \text{ KCL} = \left(\frac{x}{R_1} \right) = \left(\frac{-x+u}{R_2} \right) + \left(\frac{-x+u}{R_3+R_4} \right)$$

Always box in your eq relating x to u !

algebra = $x \left[\frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3+R_4} \right] = u \left[\frac{1}{R_2} + \frac{1}{R_3+R_4} \right]$

$$\Rightarrow x = \frac{\left[\frac{1}{R_2} + \frac{1}{R_3+R_4} \right]}{\left[\frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3+R_4} \right]} u$$

$R_1 = R$

$$\downarrow = \frac{\left[\frac{1}{R} + \frac{1}{2R} \right]}{\left[\frac{1}{R} + \frac{1}{R} + \frac{1}{2R} \right]} u$$

$$= \left(\frac{\frac{2+1}{2R}}{\frac{2+2+1}{2R}} \right) u$$

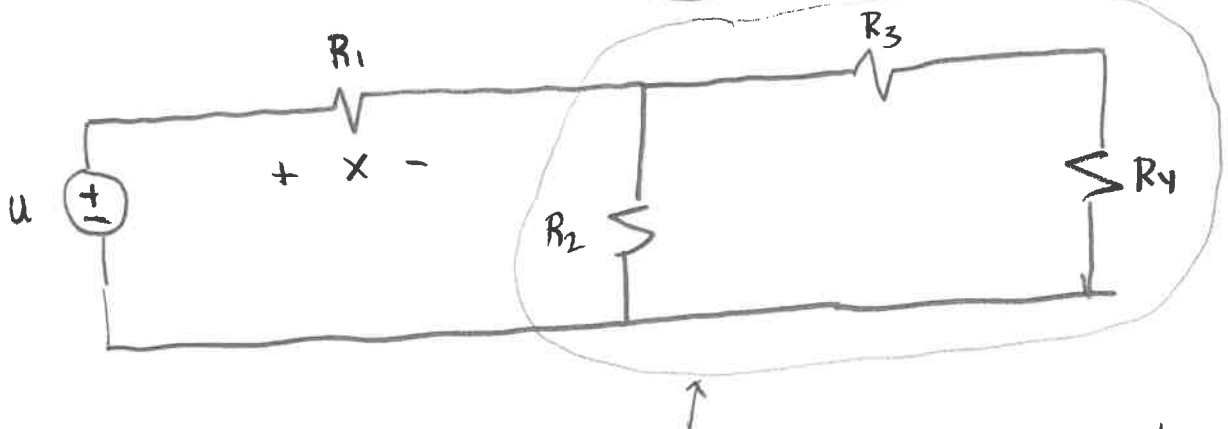
$$x = \left(\frac{3}{5} \right) u$$

$\uparrow R_1 = R$

Example 7

190

Here is a MUCH EASIER way to solve for x ---- using series-parallel voltage-divider concepts!

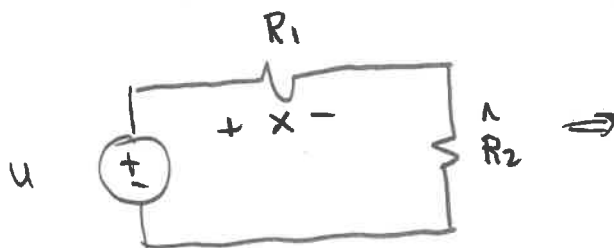


We note that all this can be replaced by:

$$\hat{R}_2 = R_2 \parallel (R_3 + R_4)$$

because R_3 & R_4 are in series
 $\rightarrow R_2$ is in parallel with $(R_3 + R_4)$.

This then yields the voltage divider circuit:



Now (from Example 2), we get

$$x = \left[\frac{R_1}{R_1 + \hat{R}_2} \right] u$$

or \rightarrow This is BEST way to write x !

For $R_i = R$, $x = \left[\frac{R}{R + R \parallel 2R} \right] u$
 $= \left[\frac{R}{R + \frac{2}{3}R} \right] u = \left(\frac{3}{5} \right) u \checkmark \checkmark$

$$x = \left[\frac{R_1}{R_1 + R_2 \parallel (R_3 + R_4)} \right] u$$

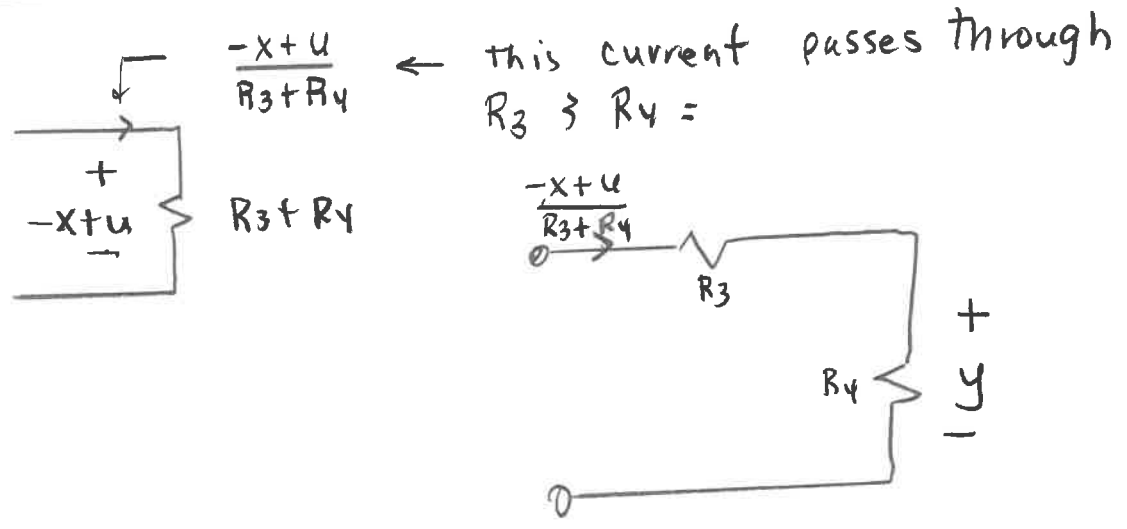
Example 7

200

Check on X:
 x must be
 $x = u - \left[\frac{R_3}{R_4} + 1 \right] y$

Now that we have $X = \left(\frac{3}{5} \right) u$

How do we get y?



From this, it follows that

$$y \stackrel{\text{Ohm}}{=} R_4 \left[\frac{-x+u}{R_3+R_4} \right]$$

Letting $R_i = R$ then yields =

$$\begin{aligned} y &= R \left[\frac{-x+u}{2R} \right] \\ &= \frac{1}{2} [u - x] \\ &= \frac{1}{2} \left[u - \left(\frac{3}{5} \right) u \right] \\ &= \frac{1}{2} \left[\frac{2}{5} u \right] \end{aligned}$$

$$y = \left(\frac{1}{5} \right) u$$

Check on X:
 x must be
 $x = u - \left[\frac{R_3}{R_4} + 1 \right] y$
 $R_i = R \rightarrow x = u - [2y]$
 $= u - 2 \left(\frac{1}{5} \right) u$

$$x = \frac{3}{5} u$$

which agrees with what we got above!

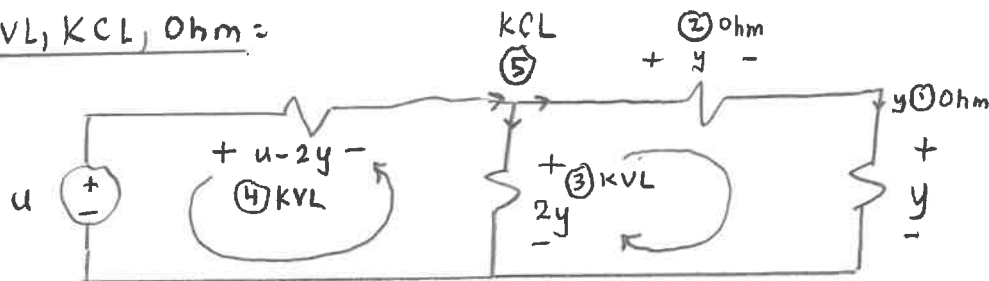


Example 7

(Summary for all $R_i = 1$)

201

KVL, KCL, Ohm:

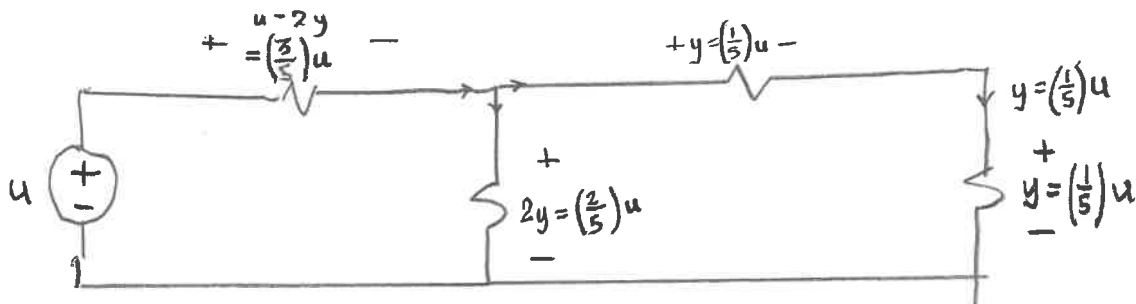


$$\begin{aligned} \text{⑤ KCL} &= \left(\frac{u-2y}{1} \right) = \left(\frac{2y}{1} \right) + y \quad \text{algebra} \Rightarrow u = 5y \\ & \quad (+ \text{ Ohm}) \end{aligned}$$

$$\boxed{y = \left(\frac{1}{5} \right) u}$$

Compute all v's & i's from above analysis:

(so that you can see that KVL & KCL are satisfied everywhere)



Note: KVL is intact satisfied around each loop!

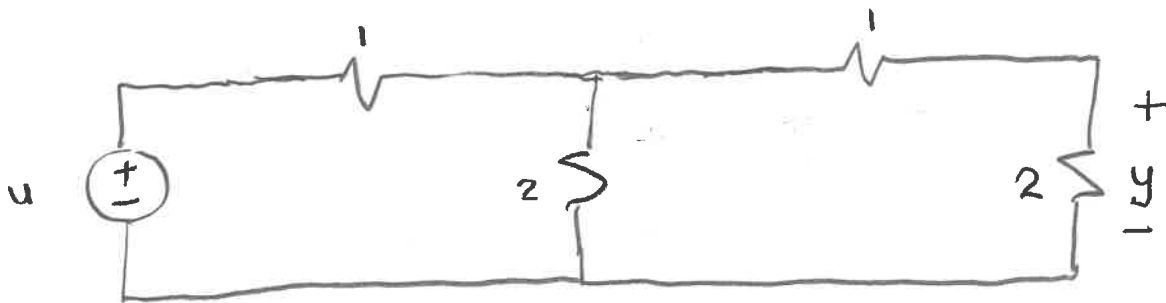
KCL " " " " at each node !!



Problem 7

(Voltage Divider with Extra Resistors)

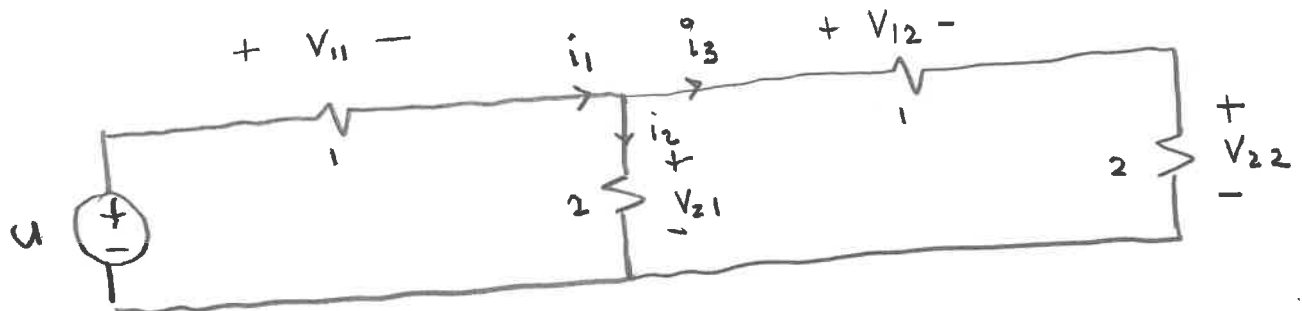
210



- a) Relate y to u by using Ohm, KCL, KVL to propagate y leftward to get an equation relating y to u & the resistors in the circuit.

Hint: Duplicate steps delineated in Example 7!

- b) Given the above, compute each of the voltages & currents in the circuit (in terms of $u!!!$) =

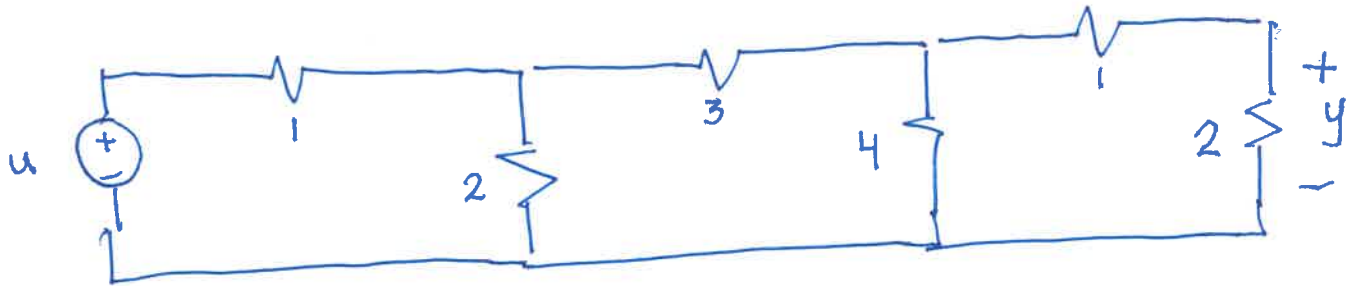


- c) Show that
- $$u = V_{11} + V_{21} \quad (\text{i.e., KVL satisfied in left loop})$$
- $$V_{21} = V_{12} + V_{22} \quad (\text{i.e., KVL satisfied in right loop})$$
- $$i_1 = i_2 + i_3 \quad (\text{KCL satisfied at top node}) \quad (2)$$

Example 8

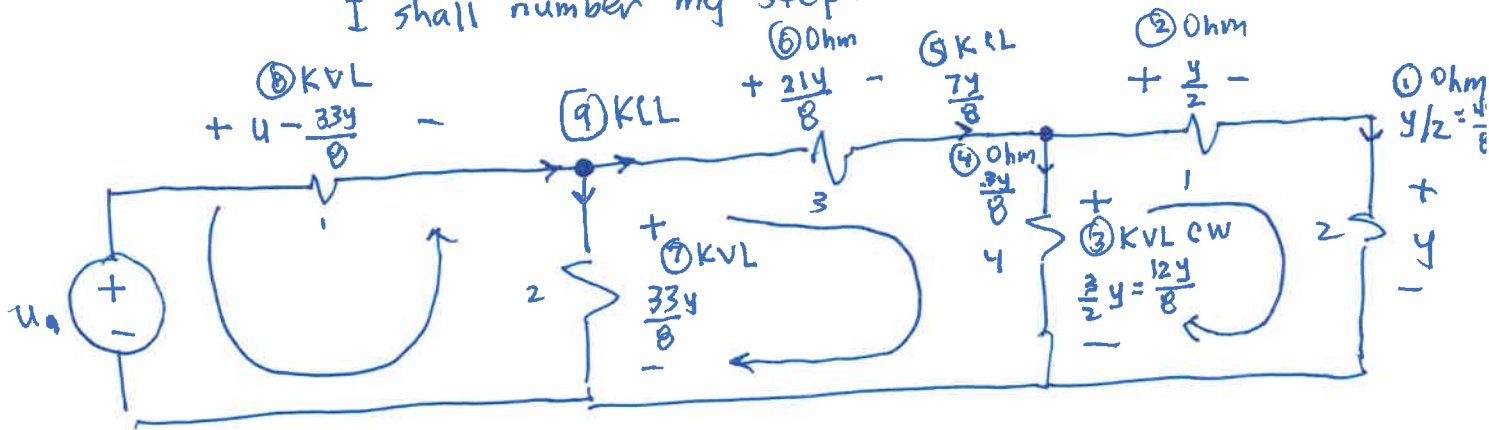
(Propagating y leftward)

Relate y to u



solution: You must ~~(I/always)~~ always show all work on your circuit!)

I shall number my steps:



9 KCL:
(+ Ohm)

$$\left(u - \frac{33y}{8} \right) = \left(\frac{33y}{8} \right) + \left(\frac{7y}{8} \right)$$

algebra

$$u = y \left[\left(\frac{33}{8} \right) + \frac{33}{16} + \left(\frac{7}{8} \right) \right]$$

$$= y \left[\frac{113}{16} \right]$$

$$y = \left(\frac{16}{113} \right) u$$

Note:

voltage x across top left 1 ohm resistor is

$$x = u - \frac{33y}{8} = u - \left(\frac{33}{8} \right) \left(\frac{16}{113} \right) u$$

$$= u - \frac{66}{113} u$$

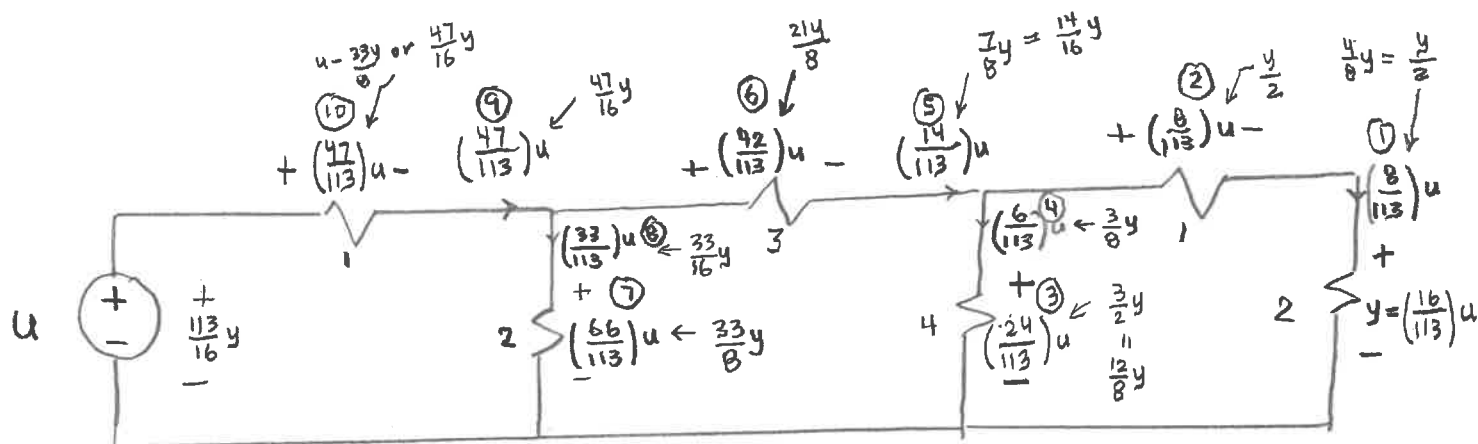
$$x = \left(\frac{47}{113} \right) u$$

Example 8

(Summary for all $R_i = 1$)

221

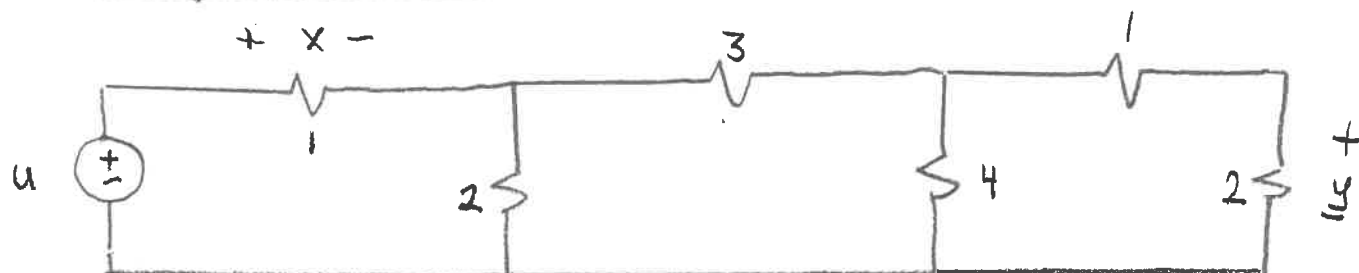
Compute all v 's & i 's to actually see that KVL is satisfied within each loop & KCL is satisfied at each node =



Note: KVL is in fact satisfied within each loop!
KCL " " " " at each node!



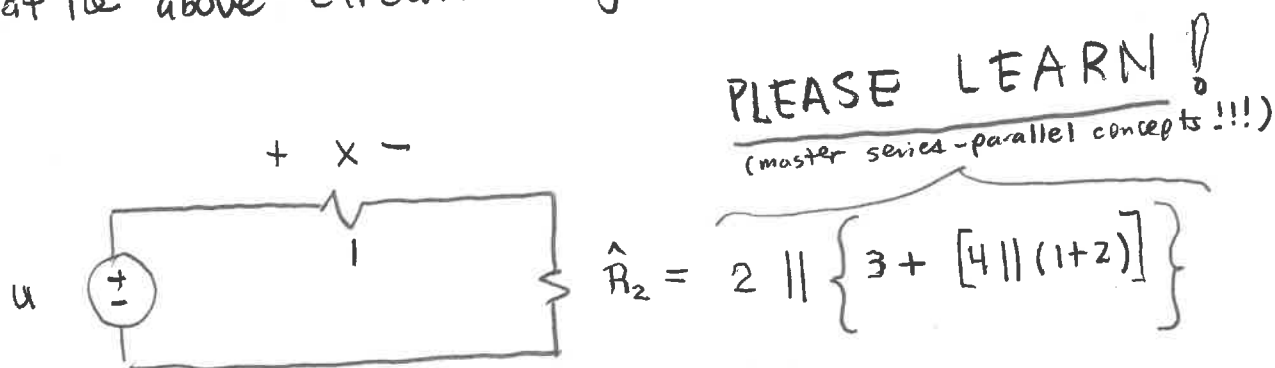
- a) Relate x to u by propagating x rightward through the circuit. (Only use variable x --- NOT y !)



Note: The x you get must agree with that found in Example 8!!!

- b) Now determine y Note: The y you get must agree with that found in Example 8!!!

- c) Now find x by using series-parallel concepts to note that the above circuit may be written as



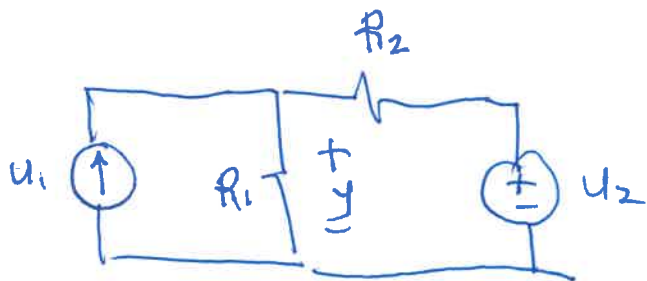
Note: Result you get for x here must agree with that found in (a)!

Example

(2 Sources

Superposition)

240

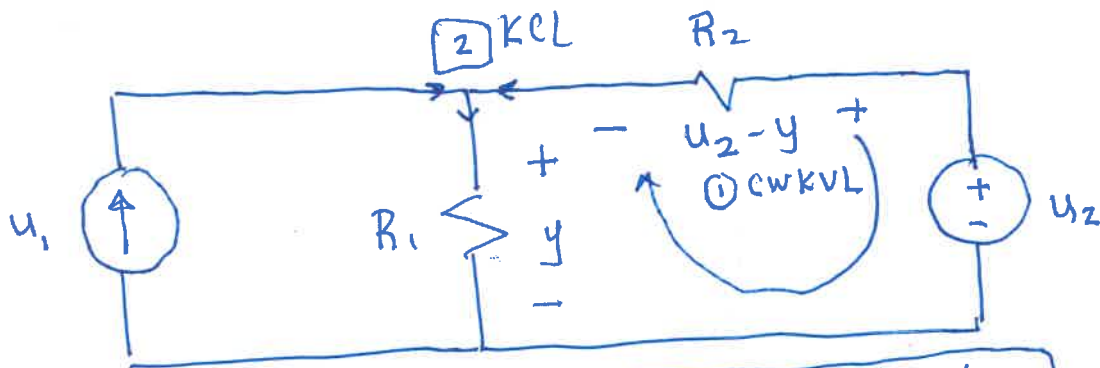


Relate y to u_1 & u_2

$$(\gamma R_1, R_2)$$

solution:

(You MUST always show all work on your circuit!)



$$\boxed{2} \text{ KOL} = (+0 \text{ hm})$$



$$U_1 = \left(\frac{y}{R_1} \right) + \left(\frac{u_2 - y}{R_2} \right)$$

~~$$\frac{u_2 - y}{R_2}$$~~

algebra: $u_1 + \frac{u_2}{R_2} = y \left[\frac{1}{R_2} + \frac{1}{R_1} \right]$

$$R_2 u_1 + u_2 = y \cdot \left[1 + \frac{R_2}{R_1} \right]$$

$$= y \left[\frac{R_1 + R_2}{R_1} \right]$$

$$y = \left[\frac{R_1 R_2}{R_1 + R_2} \right] u_1 + \left[\frac{R_1}{R_1 + R_2} \right] u_2$$

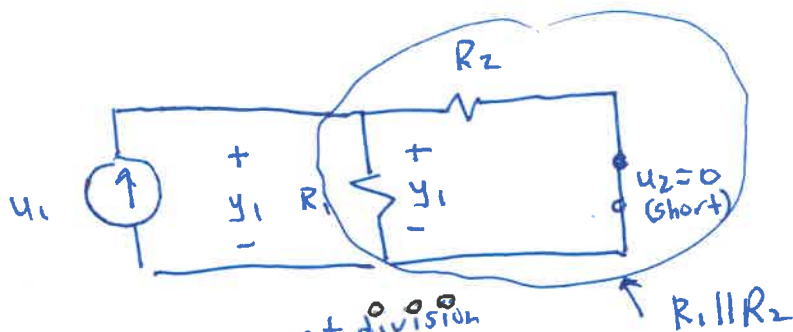
$$\begin{aligned} & \downarrow \\ & = \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \end{bmatrix} (u_1 + u_2) \\ & = \frac{1}{2} u_1 + \frac{1}{2} u_2 \end{aligned}$$

Example 9 - (Superposition: A Consequence of Linearity)

250

Lets show that $y = y_1 + y_2$

where $y_1 = y|_{u_2=0}$ $y_2 = y|_{u_1=0}$



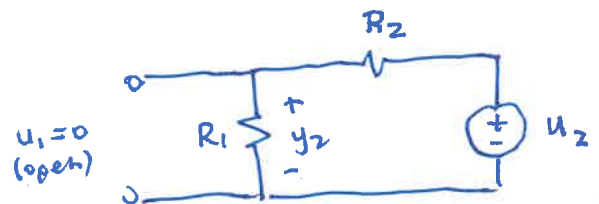
current division

$$\frac{y_1}{R_1} = \left(\frac{R_2}{R_1 + R_2} \right) u_1$$

or

$$y_1 = \left(\frac{R_1 R_2}{R_1 + R_2} \right) u_1$$

Ohm's Law u_1



$$y_2 = \left(\frac{R_1}{R_1 + R_2} \right) u_2$$

Voltage Division

\Rightarrow we've shown that

$$y = y_1 + y_2$$

$$= (R_1 || R_2) u_1 + \left(\frac{R_1}{R_1 + R_2} \right) u_2$$

Hence we have the principle of Superposition!

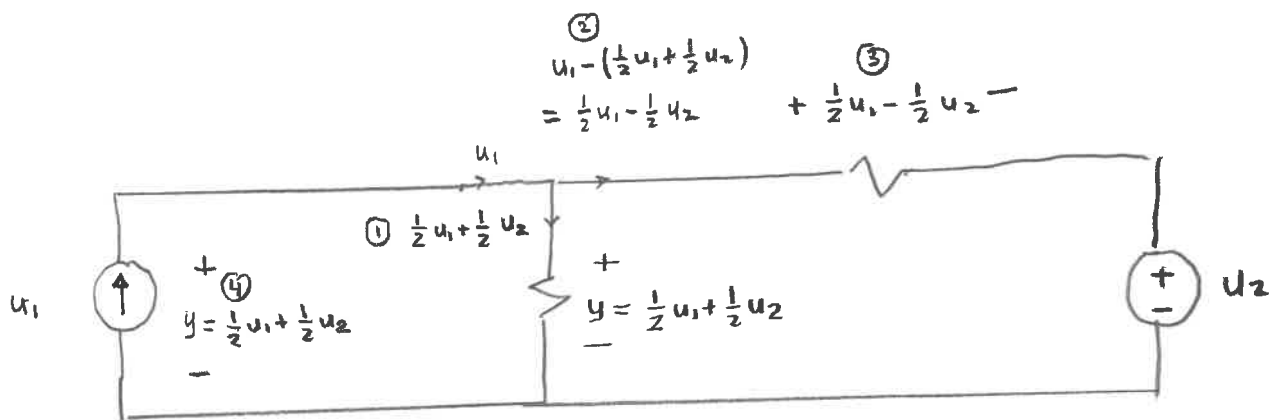


Example 9

(Summary for all $R_i = 1$)

251

Compute all v's & i's for $R_i = 1$:

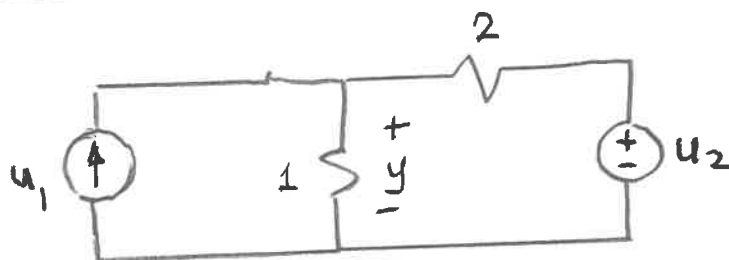


Note = KVL is in fact satisfied within each loop!
 KCL " " " " at each node!!



Problem 9 (2 sources & design)

260



a) Relate y to u_1 & u_2 (do NOT introduce another variable!!! use y, u_1, u_2)

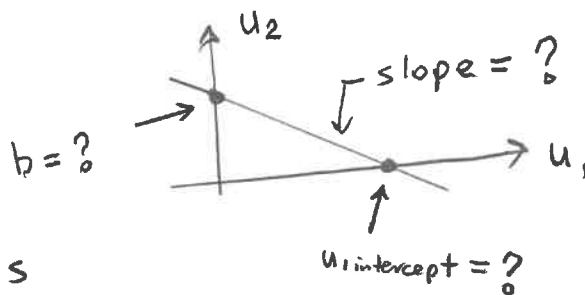
b) Suppose we desire $y = \frac{1}{3}$.

What equation must u_1 & u_2 satisfy to yield $y = \frac{1}{3}$?

----- Write the equation as

$$u_2 = \boxed{?} + \boxed{?} u_1$$

Now graph u_2 vs u_1



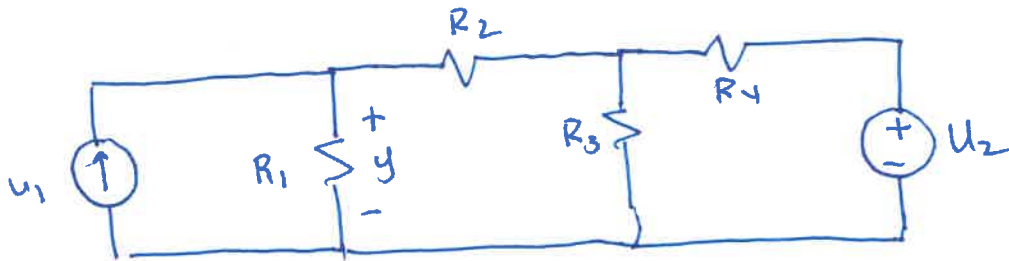
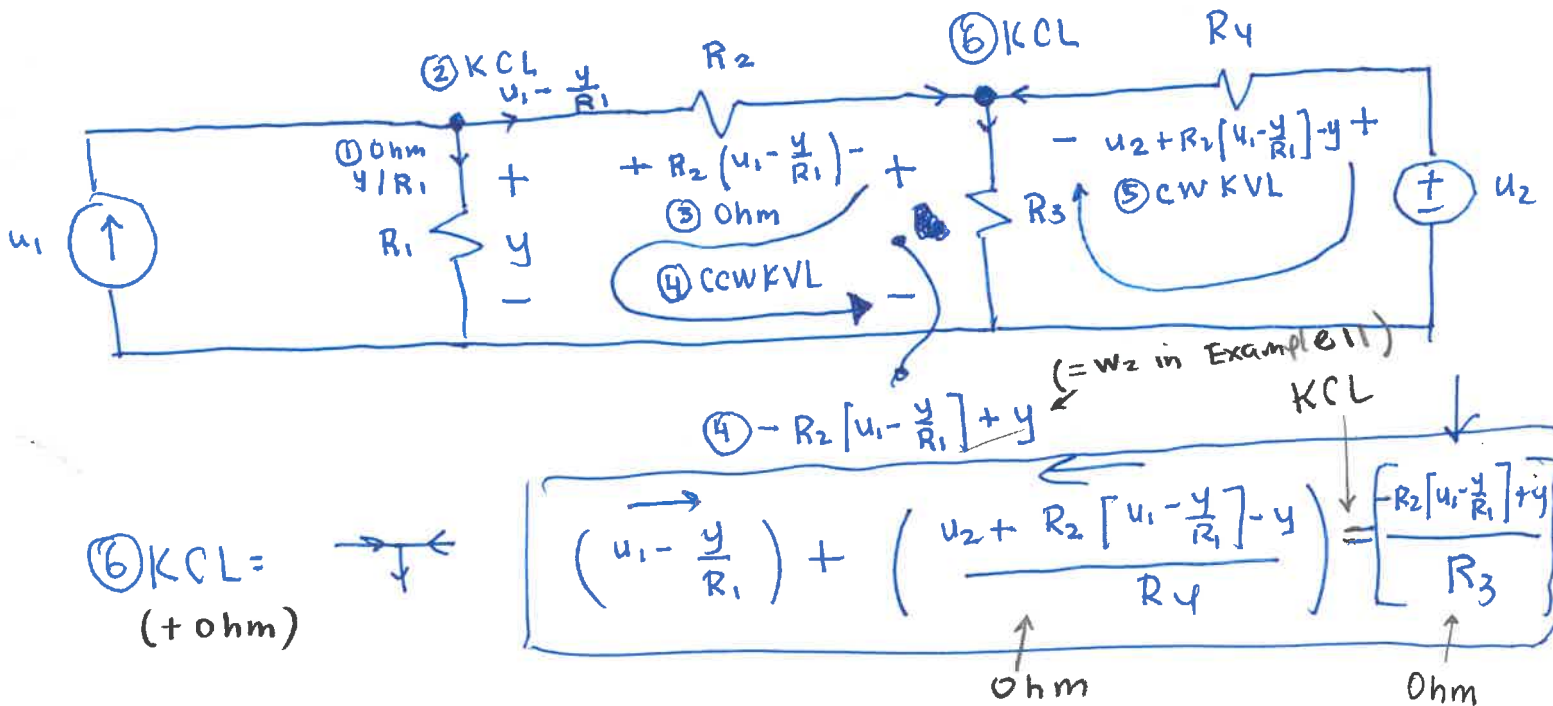
Note:

Here, we have used our analysis in order to figure out the set of all u_1 - u_2 combinations that result in $y = \frac{1}{3}$.

Given this, this is a design problem!

Example 10

(2 Sources & Superposition Again)

a) Relate y to u ($\{R_1, 2, 3, 4\}$)(do NOT introduce another variable... use y !!!)Solution: (You must always show all work on your circuit!)

algebra: $u_1 \left[1 + \frac{R_2}{R_4} + \frac{R_2}{R_3} \right] + \frac{u_2}{R_4} = y \left[\frac{1}{R_1} + \frac{R_2/R_1}{R_4} + \frac{1}{R_4} + \frac{R_2/R_1}{R_3} + \frac{1}{R_3} \right]$

$R_1 = 1 \quad y = \left[\frac{1 + \frac{R_2}{R_4} + \frac{R_2}{R_3}}{1 + \frac{R_2}{R_4} + \frac{R_2}{R_3} + 1} \right] u_1 + \left[\frac{1}{1 + \frac{R_2}{R_4} + \frac{R_2}{R_3} + 1} \right] u_2 = \left(\frac{3}{5} \right) u_1 + \left(\frac{1}{5} \right) u_2$

$y = \left[\frac{1 + R_2 \left(\frac{1}{R_3} + \frac{1}{R_4} \right)}{\frac{1}{R_1} + \frac{1}{R_3} \left(\frac{R_2}{R_1} + 1 \right) + \frac{1}{R_4} \left(1 + \frac{R_2}{R_1} \right)} \right] u_1 + \frac{1}{R_4} \left[\frac{1}{\frac{1}{R_1} + \frac{1}{R_3} \left(\frac{R_2}{R_1} + 1 \right) + \frac{1}{R_4} \left(1 + \frac{R_2}{R_1} \right)} \right] u_2$

$= y_1 + y_2$ call this y_1 call this y_2

Example 10

algebra on y_1 :

$$\frac{y_1}{u_1} = \frac{1 + \frac{R_2}{R_3 \parallel R_4}}{\frac{1}{R_1} + \frac{1}{R_3 \parallel R_4} \left(\frac{R_2}{R_1} + 1 \right)}$$

$$= \frac{R_2 + R_3 \parallel R_4}{\frac{R_3 \parallel R_4}{R_1} + \frac{R_2}{R_1} + 1}$$

$$= \frac{R_1 [R_2 + R_3 \parallel R_4]}{R_1 + [R_2 + R_3 \parallel R_4]}$$

$$= R_1 \parallel (R_2 + R_3 \parallel R_4)$$

↑

We shall get this

on next page

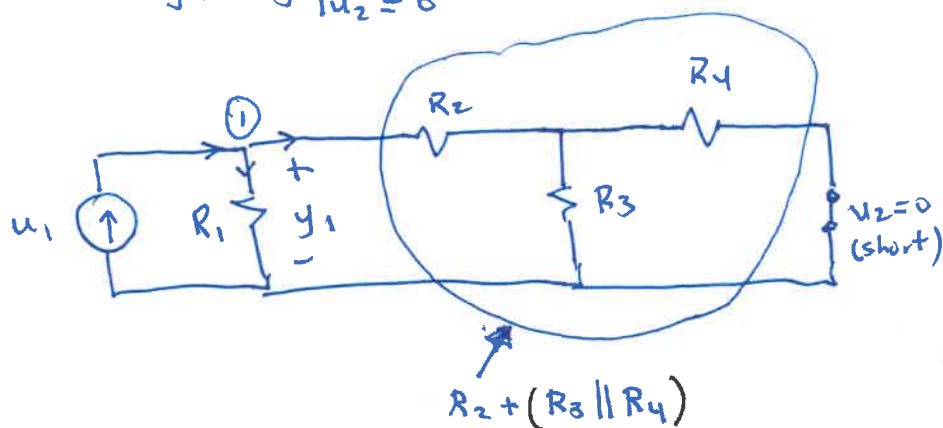
by using superposition to find y

i.e. find $y_1 = y|_{u_2=0}$ & $y_2 = y|_{u_1=0}$

Example 10

b) Now let's compute y_1 & y_2 separately showing that $y = y_1 + y_2$ by the principle of superposition!

$$y_1 = y \mid u_2 = 0$$



$$\textcircled{1} \text{ KCL: } u_1 = \frac{y_1}{R_1} + \frac{y_1}{R_2 + (R_3 \parallel R_4)}$$

$$y_1 = \left[\frac{1}{\frac{1}{R_1} + \frac{1}{R_2 + (R_3 \parallel R_4)}} \right] u_1$$

Note: For $R_2 = 1$, $y_1 = \left[\frac{1}{1 + \frac{1}{2}} \right] u_1 = \left[\frac{2}{3} \right] u_1$

$$y_1 = \left[R_1 \parallel [R_2 + (R_3 \parallel R_4)] \right] u_1 = \left[\frac{3}{2} \right] u_1$$

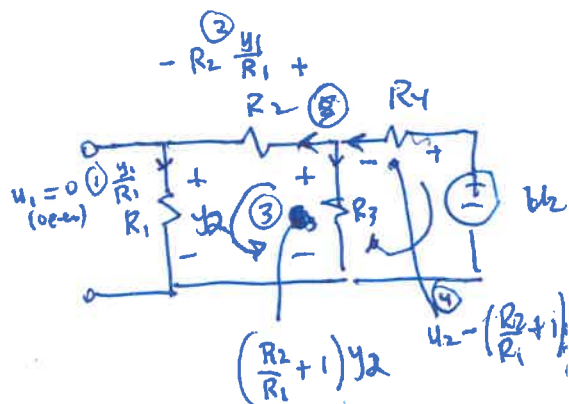
This is the BEST way to write y_1 !

(much simpler than what we got on pg 270!)

Note: The KVL, KCL, & Ohm we did on pg 270 is still VERY VERY IMPORTANT TO LEARN!

Note: This is $\frac{1}{R_2 \parallel R_4} = \frac{R_3 + R_4}{R_3 R_4}$

$$y_2 = y \mid u_1 = 0$$



$$\textcircled{5} \text{ KCL: } \frac{u_2 - \left(\frac{R_2}{R_1} + 1\right)y_2}{R_4} = \frac{\left(\frac{R_2}{R_1} + 1\right)y_2}{R_3} + \frac{y_1}{R_1}$$

$$\frac{u_2}{R_4} = y_2 \left[\frac{\frac{R_2}{R_1} + 1}{R_4} + \frac{\frac{R_2}{R_1} + 1}{R_3} + \frac{1}{R_1} \right]$$

$$y_2 = \frac{1}{R_4} \left[\frac{1}{\frac{1}{R_1} + \left(\frac{1}{R_3} + \frac{1}{R_4}\right)\left(\frac{R_2}{R_1} + 1\right)} \right] u_2$$

For $R_1 = 1$, $\left[\frac{1}{1 + 2(1+1)} \right] u_2 = \frac{1}{5} u_2$ agrees with what we got earlier! (on page 270)



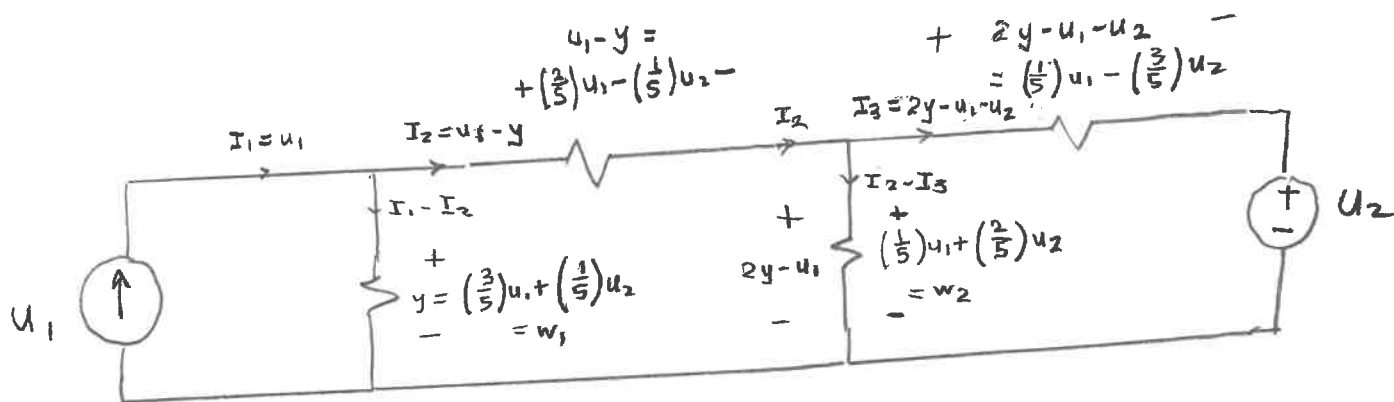
Example 10

(Summary for all $R_i = 1$)

291

Compute all v 's & i 's when all $R_i = 1$

(so that we can actually see that KVL & KCL are satisfied everywhere)



Note On Symbols =

y - used in Example 10 (page 270)

w_1, w_2 - used in Example 11 (page 310)

I_1, I_2, I_3 - used in Example 12 (page 340)

$$y = w_1 = I_1 - I_2 = (\frac{3}{5})u_1 + (\frac{1}{5})u_2$$

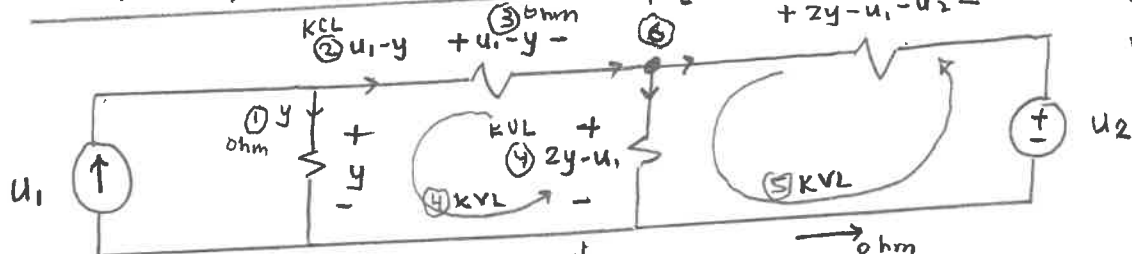
$$2y - u_1 = w_2 = I_2 - I_3$$

$$I_1 = u_1$$

$$I_2 = w_1 - w_2 = u_1 - y = (\frac{2}{5})u_1 - (\frac{1}{5})u_2$$

$$I_3 = w_2 - u_2 = 2y - u_1 - u_2 = (\frac{1}{5})u_1 + (\frac{3}{5})u_2$$

KVL, KCL, Ohm for $R_i = 1$



$$\textcircled{6} \text{ KCL } = \left(\frac{u_1 - y}{1} \right) = \left(\frac{2y - u_1}{1} \right) + \left(\frac{2y - u_1 - u_2}{1} \right) \Rightarrow 3u_1 + u_2 = 5y$$

$$\Rightarrow y = (\frac{3}{5})u_1 + (\frac{1}{5})u_2 \checkmark$$

$$= w_1$$

$$w_2 = 2y - u_1 = (\frac{1}{5})u_1 + (\frac{2}{5})u_2$$

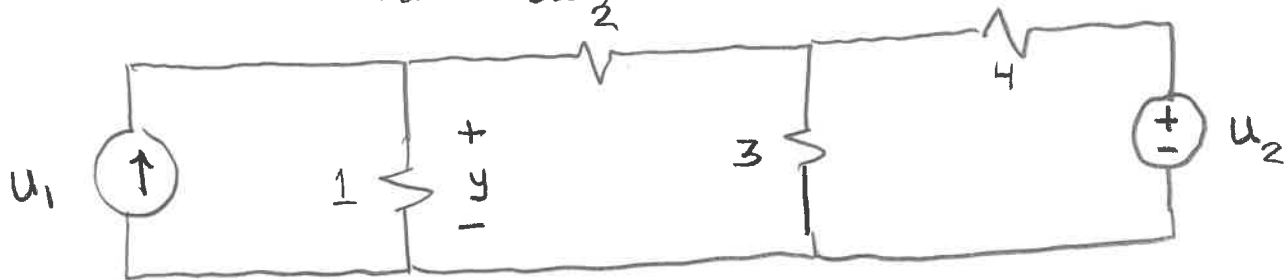
It's always useful to solve examples/problems with all $R_i = 1$ so that you can strengthen your circuit strategizing!!!



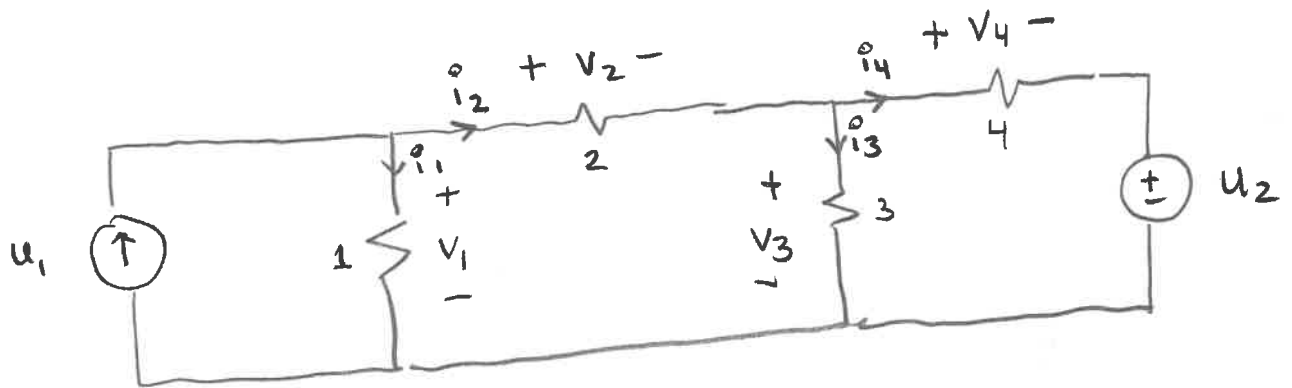
Problem 10

300

- a) Relate y to u_1 & u_2 (by propagating y rightward as was done in Example 10)
- (use only y ... don't introduce any other variables!!!)



- b) Use [a] to compute each voltage & current in the circuit =

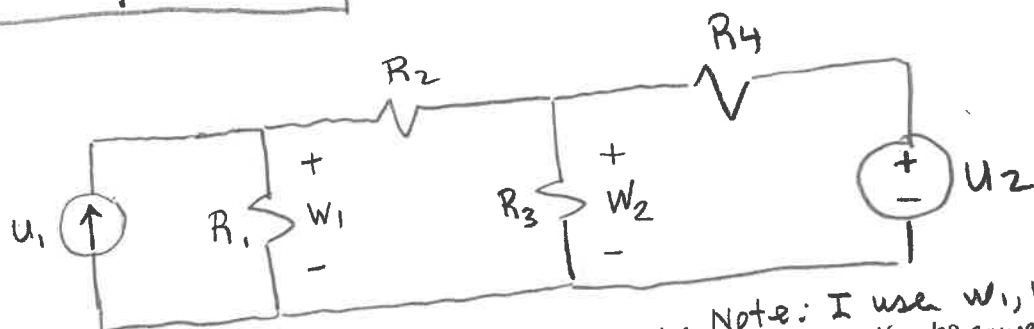


- c) Show that
- $$u_1 = i_1 + i_2 \quad (\text{KCL satisfied at top left node})$$
- $$V_1 = V_2 + V_3 \quad (\text{KVL satisfied in middle loop})$$
- $$V_3 = V_4 + u_2$$

Note: Try not to confuse the v_i & the u_i !

Example 11

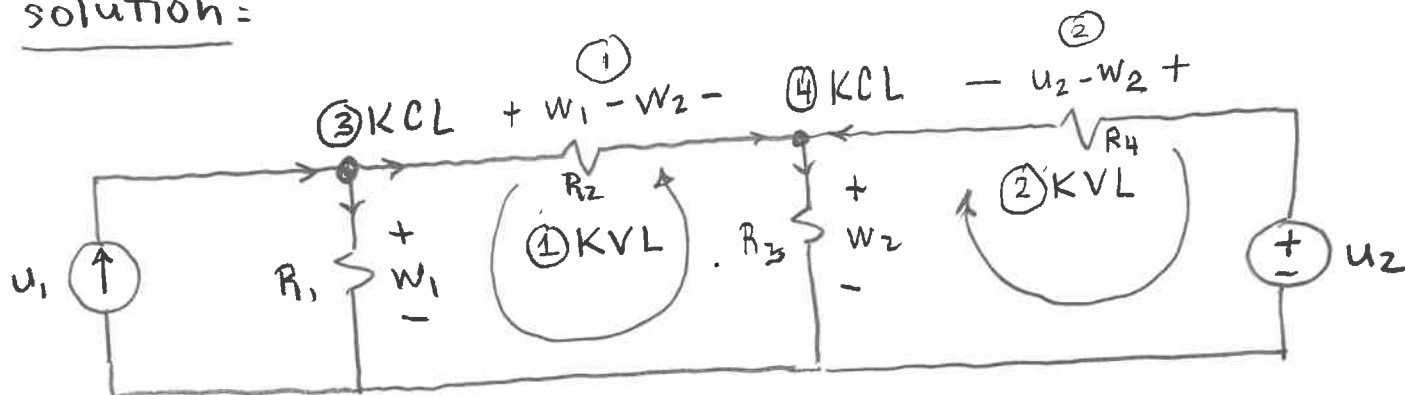
(Example 10 via Nodal Analysis)



Note: I use w_1, w_2 instead of v_1, v_2 because v_1, v_2 can be confused with u_1, u_2 (3 $R_{1,2,3,4}$)

Relate the nodal voltages w_1, w_2 to u_1, u_2 (Write in "matrix - vector" form)

solution:



$$\textcircled{3} \text{ KCL} = \begin{matrix} \text{KCL} & \text{ohm} & \text{ohm} \\ \downarrow & \downarrow & \downarrow \\ u_1 = \left(\frac{w_1}{R_1} \right) + \left(\frac{w_1 - w_2}{R_2} \right) \end{matrix} \quad \text{[A]}$$

$$\textcircled{4} \text{ KCL} = \begin{matrix} \text{ohm} & \text{ohm} & \text{KCL} & \text{ohm} \\ \downarrow & \downarrow & \downarrow & \downarrow \\ \left(\frac{w_1 - w_2}{R_2} \right) + \left(\frac{u_2 - w_2}{R_4} \right) = \left(\frac{w_2}{R_3} \right) \end{matrix} \quad \text{[B]}$$

This gives us 2 eqs in the 2 unknowns w_1, w_2 !!! 😊

Note: From Example 10 (pg 270), it follows that

$$\begin{aligned} w_1 &= y \\ w_1 - w_2 &= R_2 \left(u_1 - \frac{y}{R_1} \right) \text{ or } w_2 = \overset{y}{w_1} - R_2 \left(u_1 - \frac{y}{R_1} \right) \\ w_2 &= \left(1 + \frac{R_2}{R_1} \right) y - R_2 u_1 \end{aligned}$$

Lets now write eqs [A] & [B] in matrix-vector form.

Example 11 (Example 10 via Nodal Analysis)

Here we write eqs \boxed{A} & \boxed{B} in matrix-vector form.

$$\boxed{A} \Rightarrow \left(\frac{1}{R_1} + \frac{1}{R_2}\right) w_1 + \left(-\frac{1}{R_2}\right) w_2 = u_1$$

$$\boxed{B} \Rightarrow \left(-\frac{1}{R_2}\right) w_1 + \left(\frac{1}{R_2} + \frac{1}{R_3} + \frac{1}{R_4}\right) w_2 = \left(\frac{1}{R_4}\right) u_2$$

From the above, we get the following matrix-vector form =

$$\begin{bmatrix} \left(\frac{1}{R_1} + \frac{1}{R_2}\right) & \left(-\frac{1}{R_2}\right) \\ \left(-\frac{1}{R_2}\right) & \left(\frac{1}{R_2} + \frac{1}{R_3} + \frac{1}{R_4}\right) \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} = \begin{bmatrix} u_1 \\ \left(\frac{1}{R_4}\right) u_2 \end{bmatrix}$$

\uparrow \uparrow \uparrow
 A x b

The above is in the standard matrix-vector form =

$$Ax = b ! \quad \text{😊}$$

Note: If you had values for $R_1, R_2, R_3, R_4, u_1, u_2$, then you can feed A & b to a descent calculator so it can solve for w_1, w_2 ! (or MATLAB)

Example 11 (using Calculator or MATLAB)

321

How do we feed (A, b) to your calculator (or MATLAB) to compute w_1, w_2 ?

Let's rewrite our $Ax = b$ as follows =

$$\begin{bmatrix} (\frac{1}{R_1} + \frac{1}{R_2}) & (-\frac{1}{R_2}) \\ (-\frac{1}{R_2}) & (\frac{1}{R_2} + \frac{1}{R_3} + \frac{1}{R_4}) \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} u_1 + \begin{bmatrix} 0 \\ \frac{1}{R_4} \end{bmatrix} u_2 = b$$

\uparrow A \uparrow x \uparrow b₁ \uparrow b₂

Now suppose all $R_i = 1 =$

$$\begin{bmatrix} 2 & -1 \\ -1 & 3 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} u_1 + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u_2 = b$$

\uparrow A \uparrow x \uparrow b₁ \uparrow b₂

If (A, b_1) yield x_1 (i.e. $Ax_1 = b_1$) & (A, b_2) yield x_2 (i.e. $Ax_2 = b_2$), then the general solution (by linearity) is given by:

$$x = \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} u_1 + \begin{bmatrix} x_2 \\ x_1 \end{bmatrix} u_2$$

Why?

$$\begin{aligned} Ax &= A(x_1 u_1 + x_2 u_2) \\ &= (Ax_1)u_1 + (Ax_2)u_2 \\ &= b_1 u_1 + b_2 u_2 \\ &= b \end{aligned}$$

Inverse of matrix A

Here's some

Material from Linear Algebra: If $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$, then $A^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$

$$\text{Note: } A A^{-1} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} = \frac{1}{ad-bc} \begin{bmatrix} ad-bc & -ab+ba \\ cd-dc & -bc+ad \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\text{For our } A = \begin{bmatrix} 2 & -1 \\ -1 & 3 \end{bmatrix}, A^{-1} = \frac{1}{6-1} \begin{bmatrix} 3 & 1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} \frac{3}{5} & \frac{1}{5} \\ \frac{1}{5} & \frac{2}{5} \end{bmatrix}$$

$$Ax_1 = b_1 \Rightarrow x_1 = A^{-1}b_1 = \begin{bmatrix} \frac{3}{5} & \frac{1}{5} \\ \frac{1}{5} & \frac{2}{5} \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} \frac{3}{5} \\ \frac{1}{5} \end{bmatrix}$$

$$Ax_2 = b_2 \Rightarrow x_2 = A^{-1}b_2 = \begin{bmatrix} \frac{3}{5} & \frac{1}{5} \\ \frac{1}{5} & \frac{2}{5} \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{1}{5} \\ \frac{2}{5} \end{bmatrix}$$

Can be obtained from calculator or MATLAB!

$$\Rightarrow \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} = \begin{bmatrix} \frac{3}{5} u_1 + \frac{1}{5} u_2 \\ \frac{1}{5} u_1 + \frac{2}{5} u_2 \end{bmatrix}$$

$$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} u_1 + \begin{bmatrix} x_2 \\ x_1 \end{bmatrix} u_2$$



Agreed with w_i on page 291

Problem 11

(Propagation & Nodal Analysis)

(a) Solve Example 10 for y when $R_1 = R_2 = R_3 = R_4 = 1$

(b) Solve Example 11 for w_1, w_2 when $R_1 = R_2 = R_3 = R_4 = 1$

Show that $w_1 = y$

$$w_2 = \left(1 + \frac{R_2}{R_1}\right)y - R_2 u_1$$

i.e. what we get in (b) via nodal analysis MUST agree with what we get in (a) !!!
 \uparrow via propagation

(c) Redo Problem 10 using nodal voltages w_1, w_2 (with $R_i = 1$).

You need to show that $w_1 = v_1 = y$

$$w_2 = v_3 = v_1 - v_2$$

i.e. what we get via nodal analysis MUST agree with what we get in Problem 10 !!!

Important Observations

① In Example 10, we show that the variable y is all that we need to analyze the circuit.

Once y is found, any voltage or current in the circuit may be found in terms of our expression for y !!!

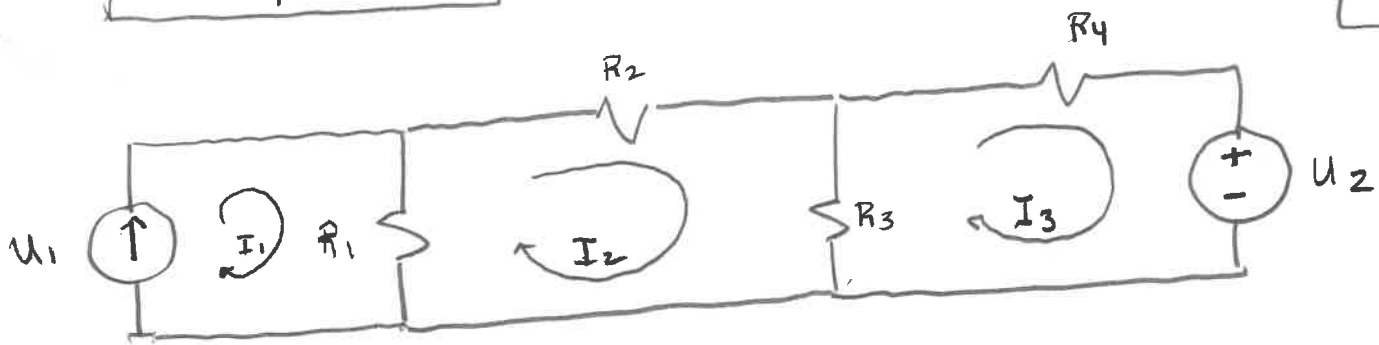
② In Example 11, we use two variables w_1, w_2 to analyze the circuit. Here, the resulting steps are simpler than in Example 10 but we MUST solve 2 eqs in 2 unknowns w_1, w_2, \dots , the resulting simplicity comes at a price...

... NOTHING IS EVER FREE!

Example 12

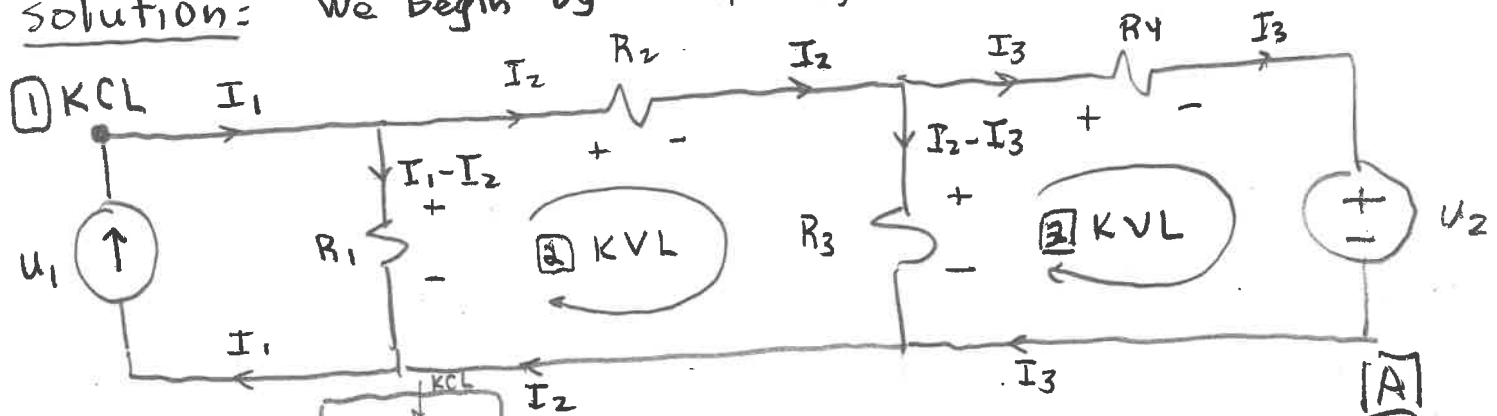
(Example 10 via Mesh Analysis)

340



Relate the mesh currents I_1, I_2, I_3 to u_1, u_2 (R_1, R_2, R_3, R_4)

Solution: we begin by interpreting I_1, I_2, I_3 on the circuit:



① KCL = $I_1 = u_1$

② KVL = (tohm)

$$R_1 (I_1 - I_2) = R_2 I_2 + R_3 (I_2 - I_3)$$

③ KVL = (tohm)

$$R_3 (I_2 - I_3) = R_4 I_3 + u_2$$

↓ This gives us 3 eqs in the 3 unknowns I_1, I_2, I_3 !
Solution for I_1, I_2, I_3 must agree with our results from Example 10 or Example 11.

Note: From Example 10 (pg 270), it follows that

$$R_1 (I_1 - I_2) = y \Rightarrow I_2 = I_1 - \frac{y}{R_1} = u_1 - \frac{y}{R_1}$$

From Example 11 (pg 310), $R_1 (I_1 - I_2) = w_1$ & $R_3 (I_2 - I_3) = w_2$... etc...

Lets now write eqs [A], [B], [C] in matrix-vector form.

$$I_3 = \frac{R_3 I_2 - u_2}{R_3 + R_4}$$

Example 12

(Example 10 via Mesh Analysis)

Here, we write eqs $[A]$, $[B]$, $[C]$ in matrix-vector form.

$$[A] \Rightarrow I_1 = u_1$$

$$[B] \Rightarrow -R_1 I_1 + (R_1 + R_2 + R_3) I_2 - R_3 I_3 = 0$$

$$[C] \Rightarrow -R_3 I_2 + (R_3 + R_4) I_3 = -u_2$$

From the above, we get the following matrix-vector form:

$$\begin{bmatrix} 1 & 0 & 0 \\ -R_1 & (R_1 + R_2 + R_3) & -R_3 \\ 0 & -R_3 & (R_3 + R_4) \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix} = \begin{bmatrix} u_1 \\ 0 \\ -u_2 \end{bmatrix}$$

$\uparrow \qquad \qquad \uparrow \qquad \qquad \uparrow$
 $A \qquad \qquad x \qquad \qquad b$

The above is in the standard matrix-vector form:

$$Ax = b!$$



Note: If you had values for $R_1, R_2, R_3, R_4, u_1, u_2$, then you can feed A & b to a descent calculator (or MATLAB) so it can solve for I_1, I_2, I_3 !

Example 12

(using calculator or MATLAB)

351

How do we feed (A, b) to your calculator or MATLAB to compute $I_{1,2,3}$?

Lets rewrite our $Ax=b$ as follows:

$$\begin{bmatrix} 1 & 0 & 0 \\ -R_1 & (R_1+R_2+R_3) & -R_3 \\ 0 & -R_3 & R_3+R_4 \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} u_1 + \begin{bmatrix} 0 \\ 0 \\ -1 \end{bmatrix} u_2 = b$$

$\uparrow \quad \quad \quad \uparrow \quad \quad \quad \uparrow$
 $A \quad \quad \quad x \quad \quad \quad b_1 \quad \quad \quad b_2$

Now suppose all $R_i = 1$:

$$\begin{bmatrix} 1 & 0 & 0 \\ -1 & 3 & -1 \\ 0 & -1 & 2 \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} u_1 + \begin{bmatrix} 0 \\ 0 \\ -1 \end{bmatrix} u_2 = b$$

$\uparrow \quad \quad \quad \uparrow \quad \quad \quad \uparrow$
 $A \quad \quad \quad x \quad \quad \quad b_1 \quad \quad \quad b_2$

If (A, b_1) yields x_1 (i.e. $Ax_1 = b_1$) & (A, b_2) yields x_2 (i.e. $Ax_2 = b_2$), then the general solution (by linearity) is given by:

$$x = \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix} = \begin{bmatrix} 1 \\ x_1 \\ 1 \end{bmatrix} u_1 + \begin{bmatrix} 1 \\ x_2 \\ 1 \end{bmatrix} u_2$$

Why?

$$\begin{aligned} Ax &= A(x_1 u_1 + x_2 u_2) \\ &= (Ax_1) u_1 + (Ax_2) u_2 \\ &= b_1 u_1 + b_2 u_2 \\ &= b \end{aligned}$$

From above eqs, it follows that

$$I_1 = u_1$$

$$-I_1 + 3I_2 - I_3 = 0 \Rightarrow 3I_2 - I_3 = I_1 = u_1$$

$$-I_2 + 2I_3 = -u_2 \Rightarrow -3I_2 + 6I_3 = -3u_2$$

$$5I_3 = u_1 - 3u_2$$

$$I_3 = \left(\frac{1}{5}\right)u_1 - \left(\frac{3}{5}\right)u_2$$

$$\begin{aligned} \Rightarrow I_2 &= 2I_3 + u_2 \\ &= \left(\frac{2}{5}\right)u_1 - \left(\frac{6}{5}\right)u_2 + u_2 \end{aligned}$$

$$\Rightarrow I_2 = \left(\frac{2}{5}\right)u_1 - \left(\frac{1}{5}\right)u_2$$

Note: $I_{1,2,3}$ here agree with that found on page 291!



Note:

The simplicity of Mesh (or Nodal) analysis comes at a price

... More equations that must be solved simultaneously!

Problem 12

(Propagation, Nodal, & Mesh Analysis)

- (a) Solve Example 10 for y when $R_1 = R_2 = R_3 = R_4 = 1$.
- (b) Solve Example 11 for w_1, w_2 " " "
- (c) Solve Example 12 for I_1, I_2, I_3 " " "
- (d) Show that the answers obtained in (a), (b), (c) are in agreement!

i.e.

Show w_1, w_2 from Example 11 satisfy:

$$w_1 = y$$

$$w_2 = \left(1 + \frac{R_2}{R_1}\right)y - R_2 u_1$$

Show I_1, I_2, I_3 from Example 12 satisfy:

$$I_1 = u_1$$

$$I_2 = u_1 - \frac{y}{R_1}$$

$$I_3 = \frac{R_3 I_2 - u_2}{R_3 + R_4}$$

Notes:

The simplicity of Nodal & Mesh analysis comes at a price...

... MORE EQUATIONS THAT MUST BE SOLVED SIMULTANEOUSLY!

(e) Repeat the above for Problem 10.

i.e. show that you get same results

via propagation (Problem 10)
nodal analysis (Problem 11c)
mesh analysis

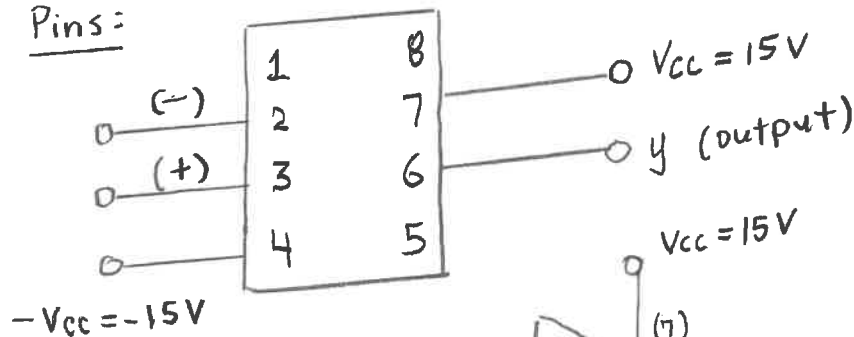
Example 13

(Introduction to 741 Operational Amplifier, Ideal/Standard Op-Amp Assumptions, Buffer/Follower Amplifier, & Its Use!)

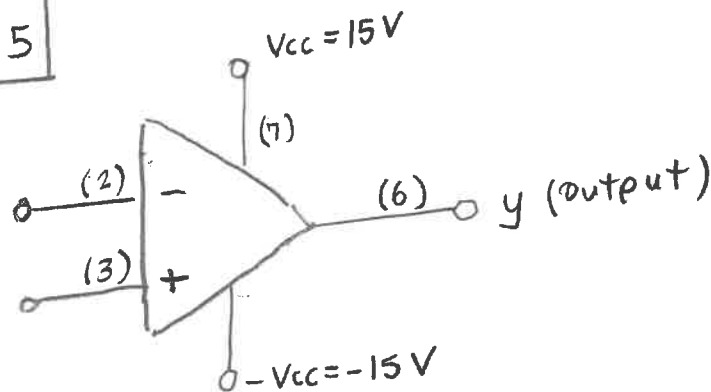
741 Operational Amplifier

(David Fullagar, Fairchild Semiconductor 1968)

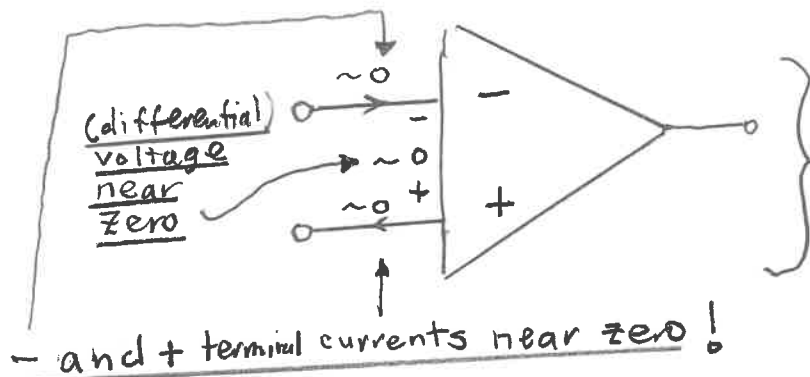
Pins:



Schematic:



Ideal Op-Amp Assumptions



Note:

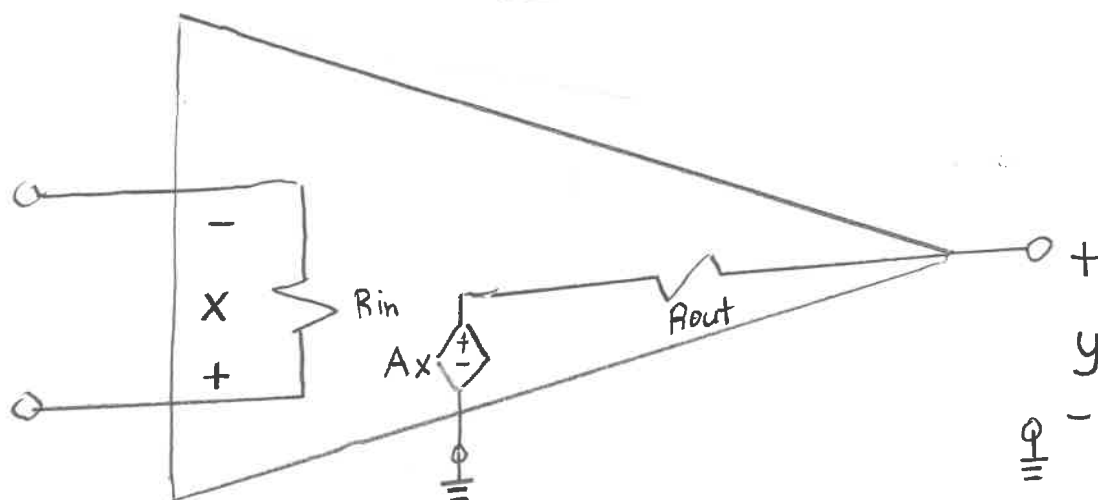
These ideal op-amp assumptions are a consequence of the following standard (limiting) op-amp assumptions:

(input resistance) $R_{in} \rightarrow \infty$ large
 (output resistance) $R_{out} \rightarrow 0$ small
 (gain) $A \rightarrow \infty$ large

lets explain a little

Example 13

Standard Op-Amp Model



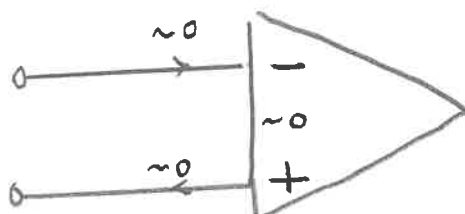
R_{in} - input resistance

R_{out} - output resistance

A_x - voltage dependant voltage source

As $R_{in} \rightarrow \infty$ (Infinite input resistance)
 $R_{out} \rightarrow 0$ (Zero output resistance)
 $A \rightarrow \infty$ (Infinite gain)

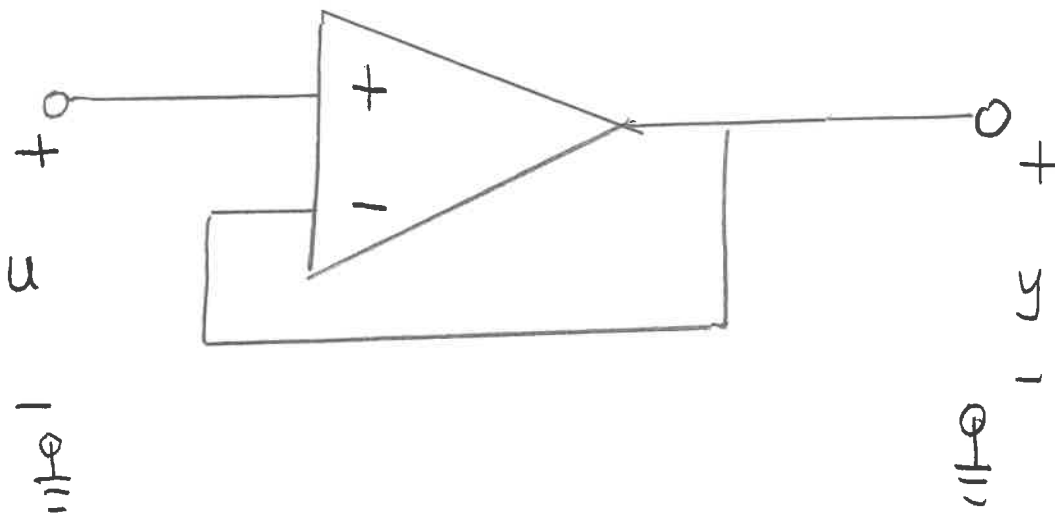
we get The Ideal op-amp assumptions =



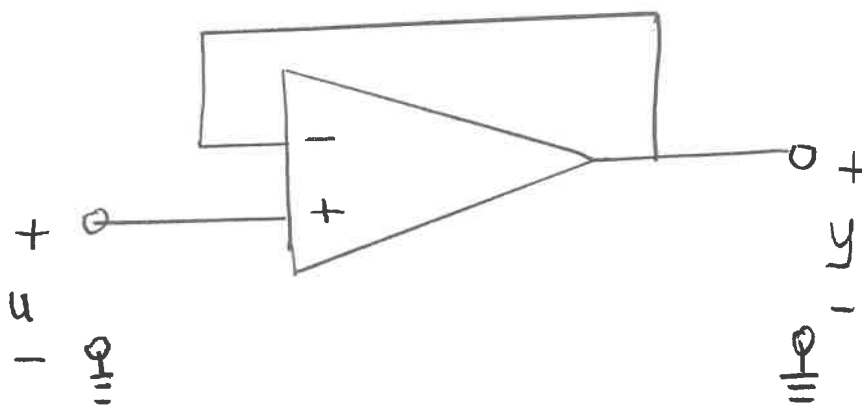
Now, lets examine the Buffer / Follower Amplifier - - -

Example 13

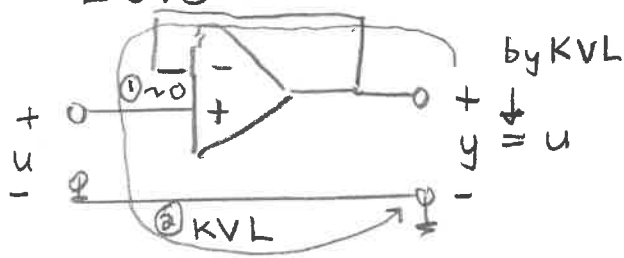
Buffer/Follower Amplifier



or



Lets show that



$$y = u$$

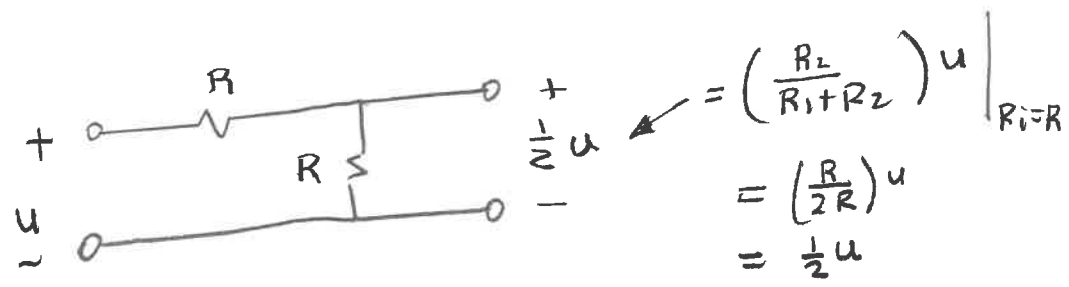
Buffer/Follower
(under ideal op-amp assumptions)
... How/Why is this useful?

Example 13

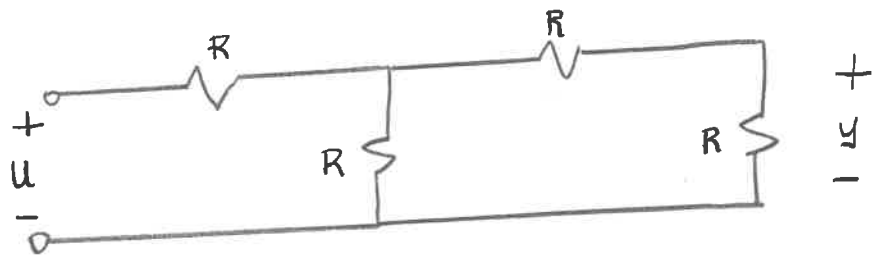
400

Why is a Buffer/Follower Amplifier useful?

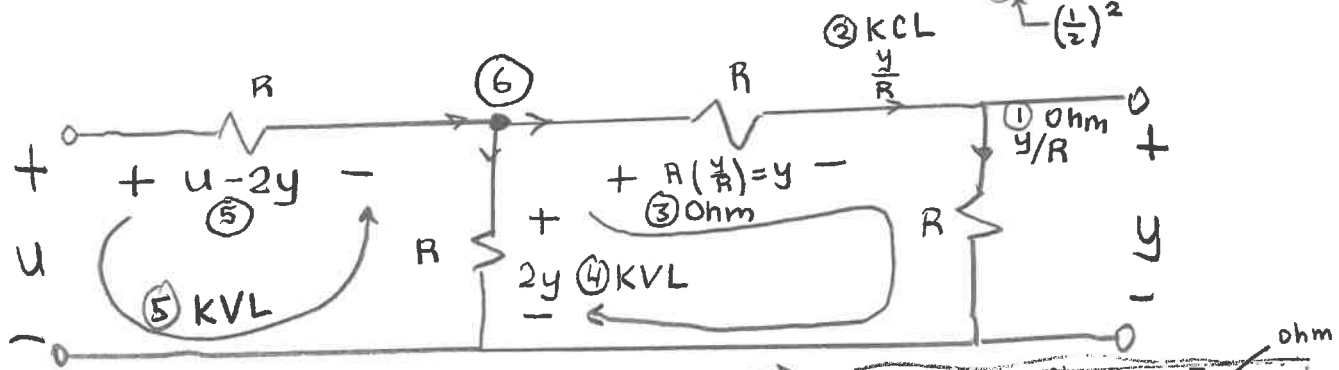
Consider the simple voltage divider circuit:



Now consider 2 of these cascaded:



Lets relate y to u ... (using KVL, KCL, Ohm)
 Note: it's not going to be $\frac{1}{4} u$!!!
 (using $\frac{1}{2}$)²



(6) KCL (+ohm) = $\frac{u-2y}{R} = \frac{2y}{R} + \frac{y}{R}$

Now we do algebra...

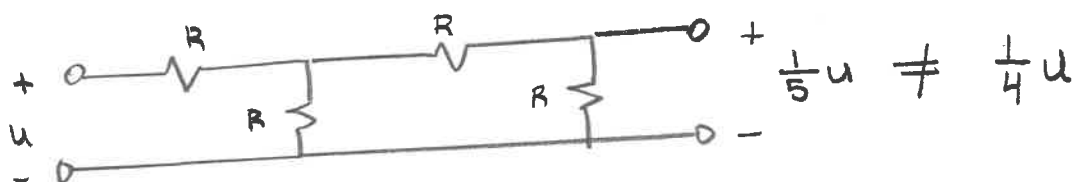
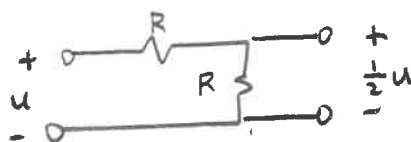
Example 13

Algebra = $y \left[\frac{2}{R} + \frac{2}{R} + \frac{1}{R} \right] = \left[\frac{1}{R} \right] u$

or $y = \frac{1}{5} u \neq \frac{1}{4} u$

Summary:

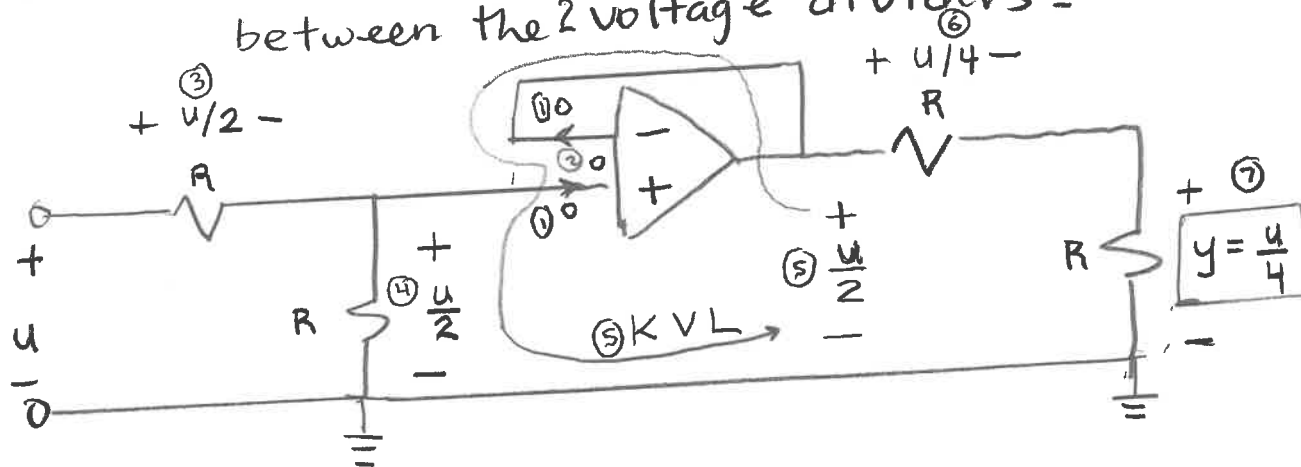
Even though



How do we get the desired $y = \frac{1}{4} u$?

Answer: Use a Buffer/Follower Amplifier

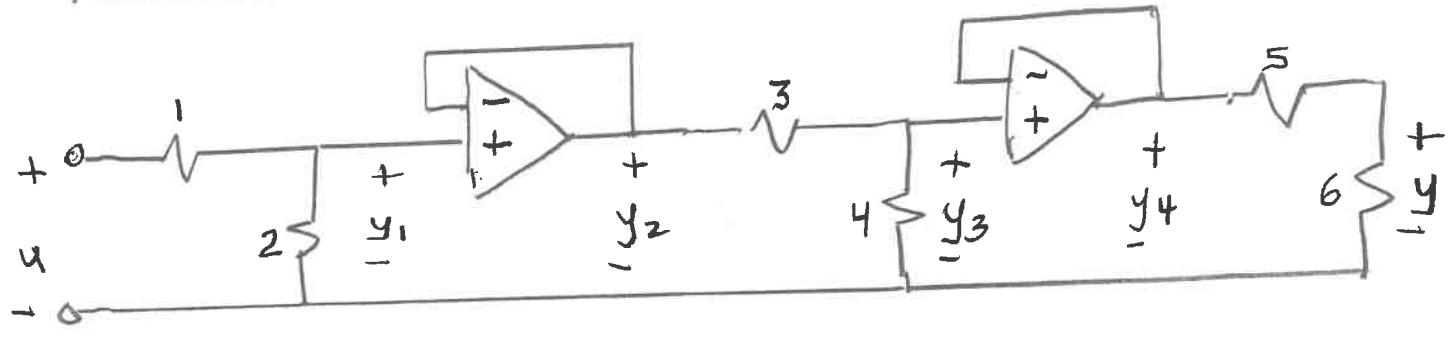
between the 2 voltage dividers =



Buffer/Follower Amplifier permits us to design circuits systematically & modularly ... to get the desired "cascaded product" result by inserting buffer/follower in between

Problem 13

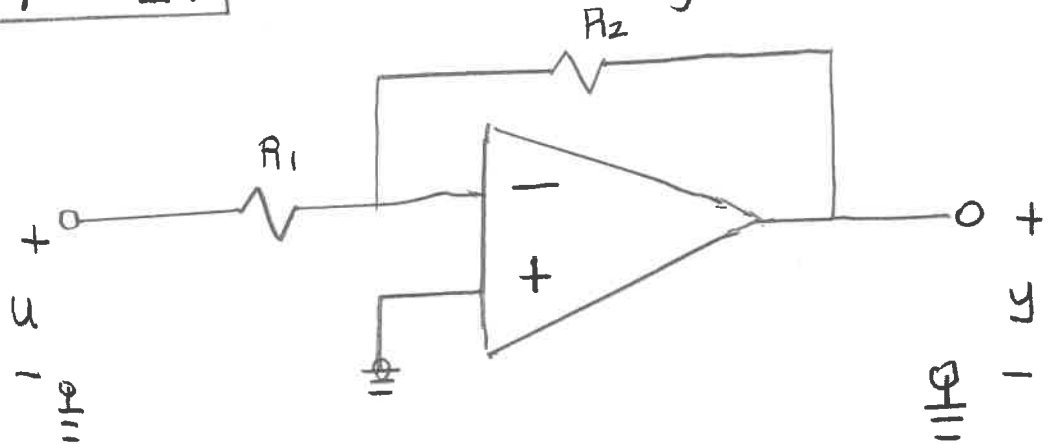
420



Relate $\begin{Bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \\ y \end{Bmatrix}$ to u .

Example 14

(Inverting Amplifier)



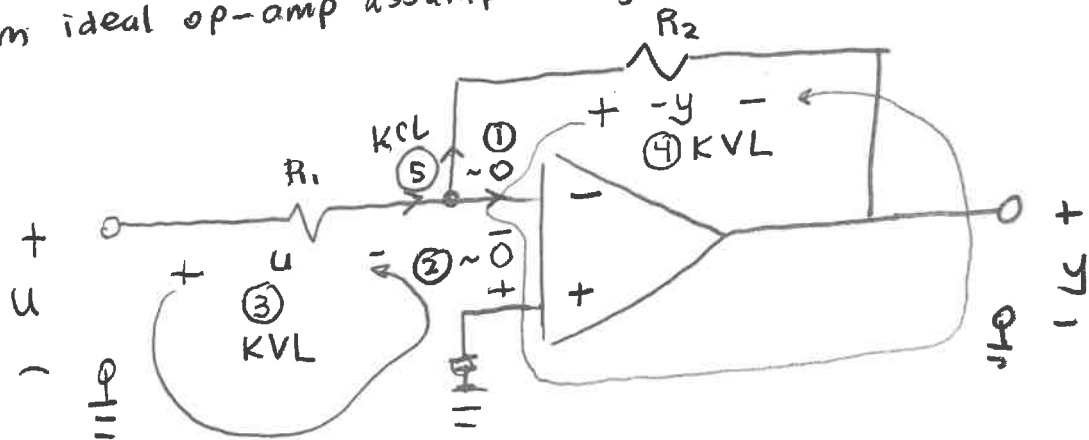
a Show that

$$y = - \left(\frac{R_2}{R_1} \right) u$$

(using ideal op-amp assumptions)

solution =

From ideal op-amp assumptions, we have =



$$\textcircled{5} \text{ KCL (3 ohm)} = \begin{array}{c} \uparrow 0 \\ \rightarrow \text{ } \end{array} \quad \text{ohm} \left(\frac{u}{R_1} \right) = \left(\frac{-y}{R_2} \right) + 0$$

algebra

$$\Rightarrow y = - \left(\frac{R_2}{R_1} \right) u$$

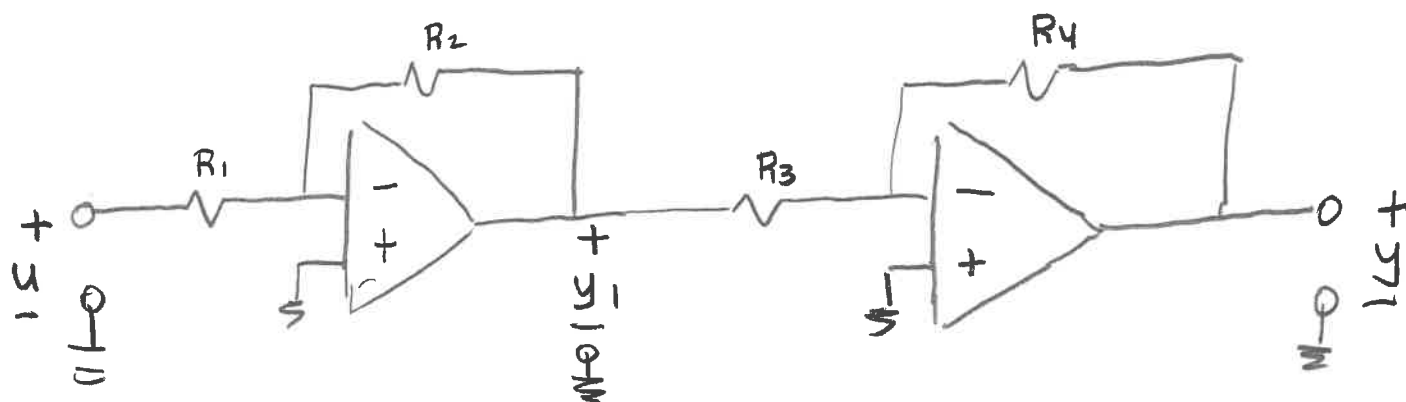
.. the desired result!



Example 14

440

(b) Now consider 2 cascaded Inverting amplifiers:



From ideal op-amp assumptions, it follows that

$$y_1 = - \left(\frac{R_2}{R_1} \right) u$$

3

$$y = - \left(\frac{R_4}{R_3} \right) y_1$$

or

$$y = \left(\frac{R_4}{R_3} \right) \left(\frac{R_2}{R_1} \right) u$$

Note: Suppose we desire $y = g u$.
To achieve this, we can use $R_2 = g R_1$
 & $R_4 = R_3$

Here, we can achieve any gain g
(> 1 , $= 1$, or < 1 !!!)

Problem 14

450

Show how inverting amplifiers can be used to achieve:

[a] $y = -10u$

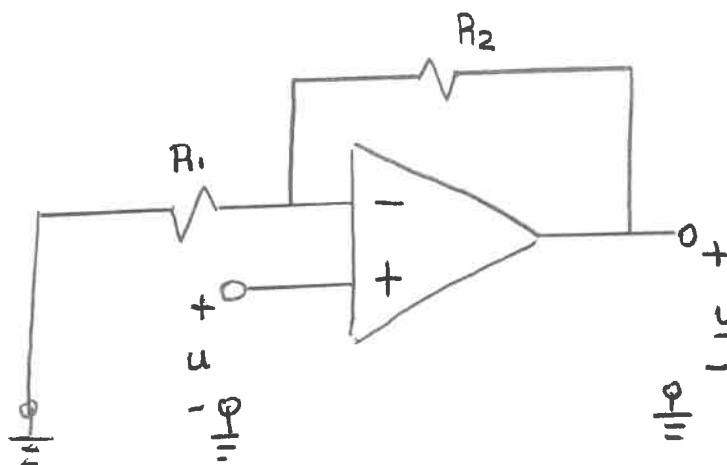
[b] $y = 10u$

[c] $y = \frac{1}{5}u$

Note:- The above is "design!" 😊

Example 15

(Non-Inverting Amplifier)



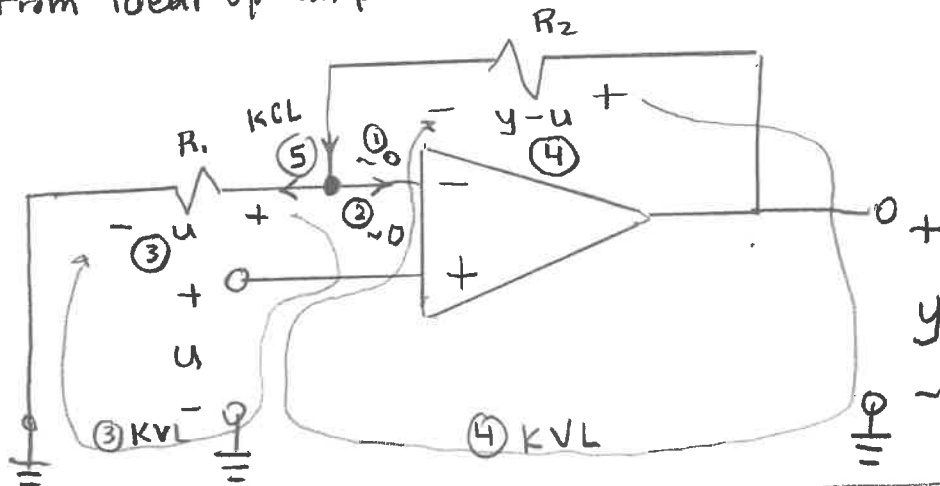
a) Show that

$$y = \left(1 + \frac{R_2}{R_1}\right) u$$

(using ideal op-amp assumptions)

solution:

From ideal op-amp assumptions, we have =



$$\textcircled{5} \text{ KCL} =$$

(+ Ohm)

$$\left(\frac{u}{R_1}\right) + 0 = \left(\frac{y-u}{R_2}\right)$$

(Ohm) (KCL) (Ohm)

Multiply both sides
by R_2 algebra \Rightarrow

$$\frac{y}{R_2} = u \left[\frac{1}{R_1} + \frac{1}{R_2} \right]$$

$$\Rightarrow y = \left[1 + \frac{R_2}{R_1} \right] u$$

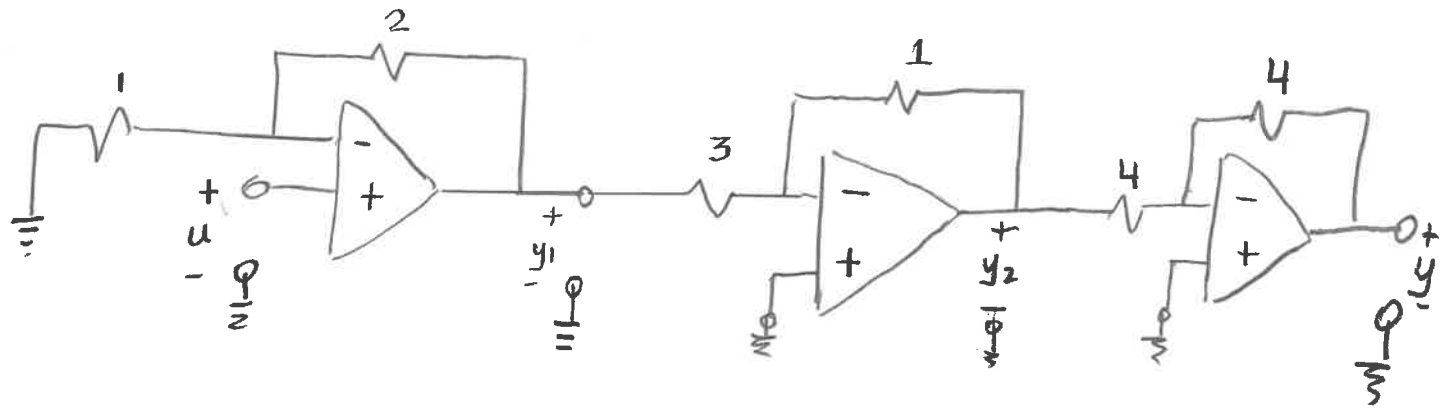
Note:To achieve $y = 10u$, we just need $R_2 = 9R_1$.To achieve $y = \frac{1}{2}u$, we need $R_2 = -\frac{1}{2}R_1$ (Negative Resistance!!!)

... more on this later ...

... the desired
result!

Problem 15

470

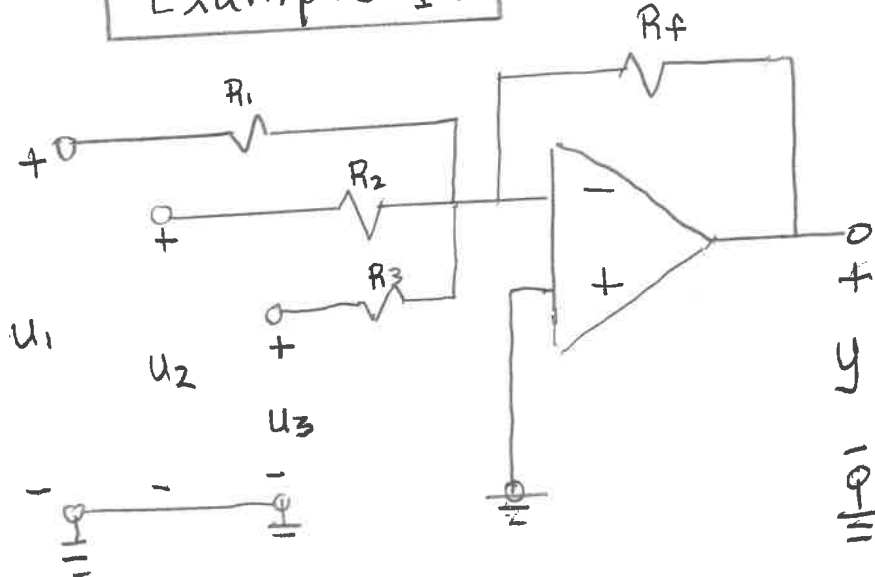


- Relate
- a) y_1 to u
 - b) y_2 to u
 - c) y to u

Example 16

(Inverting Summing Amplifier)

480



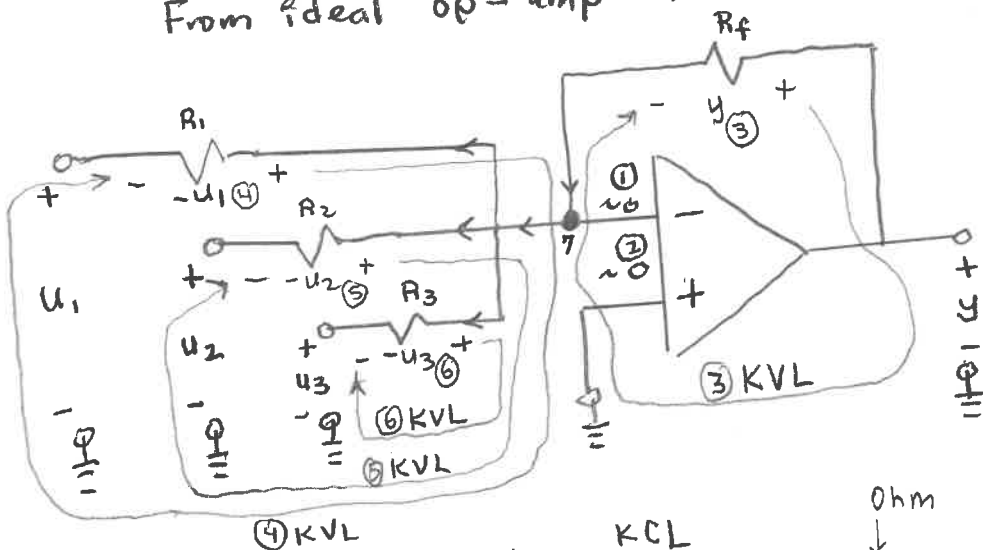
[a] Show that

$$y = -\left(\frac{R_f}{R_1}\right)u_1 - \left(\frac{R_f}{R_2}\right)u_2 - \left(\frac{R_f}{R_3}\right)u_3$$

(using ideal op-amp assumptions)

solution:

From ideal op-amp assumptions, we have:



(7) KCL = (+ Ohm)

Ohm ↓
KCL ↓
 $\left(\frac{y}{R_f}\right) =$

Ohm ↓ Ohm ↓ Ohm ↓
 $\left(\frac{-u_1}{R_1}\right) + \left(\frac{-u_2}{R_2}\right) + \left(\frac{-u_3}{R_3}\right)$

$\Rightarrow y = -\left(\frac{R_f}{R_1}\right)u_1 - \left(\frac{R_f}{R_2}\right)u_2 - \left(\frac{R_f}{R_3}\right)u_3$
... the desired result!



Problem 16

490

Show how to achieve

$$y = g \left[\left(\frac{R_f}{R_1} \right) u_1 + \left(\frac{R_f}{R_2} \right) u_2 + \left(\frac{R_f}{R_3} \right) u_3 \right]$$

Hint: place inverter with gain $\left(-\frac{R_2}{R_1} \right) = -g$

on output of circuit in Example 16.

Show your final circuit in your solution!

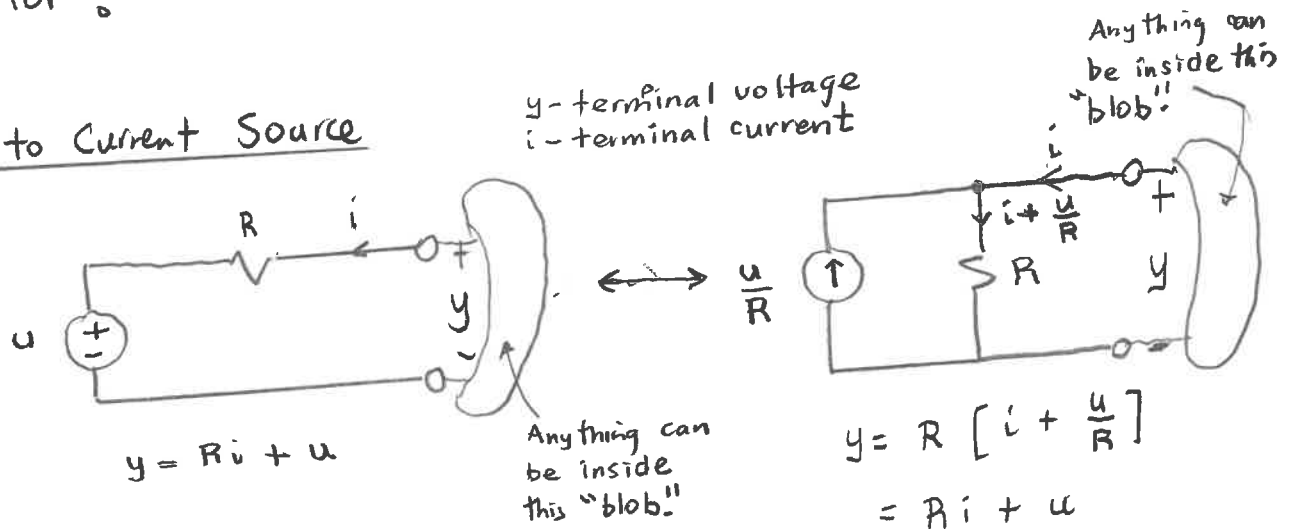
Overview of Source Transformation Concepts

500

Questions:

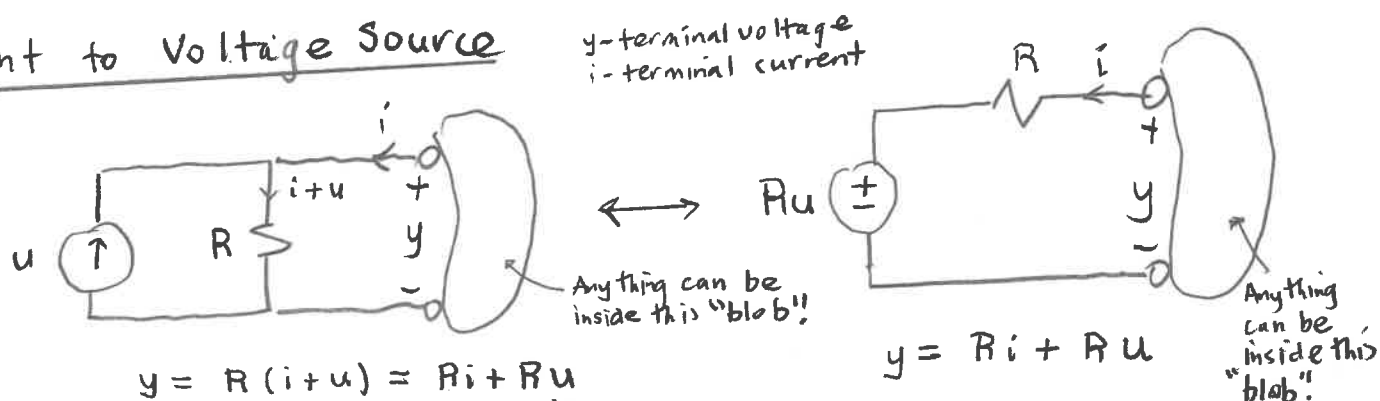
- 1] How can we transform a voltage source in series with a resistor to a current source in parallel with a resistor?
- 2] How can we transform a current source in parallel with a resistor to a voltage source in series with a resistor?

Voltage to Current Source



The above 2 circuits are said to be equivalent because they have the exact same y - i relationship between the terminal voltage y & the terminal current i .

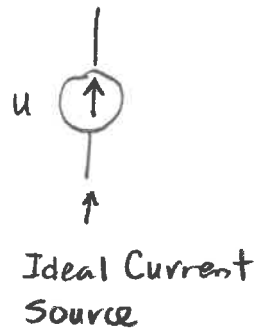
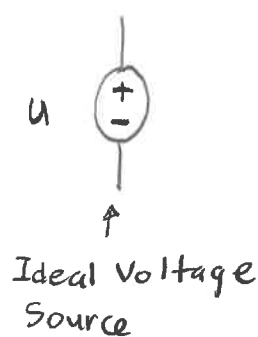
Current to Voltage Source



The above 2 circuits are also said to be equivalent from a terminal y - i perspective!!!

A Practical Note on Real Voltage & Current Sources

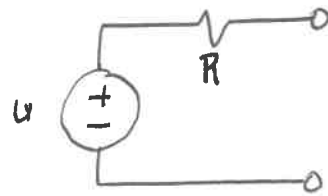
These are ideal sources!



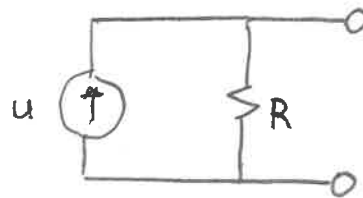
Note: These only exist in books ... NOT in the real world!

In the real world

(1) A Real Voltage Source must have a series resistance:



(2) A Real Current Source must have a parallel resistance:

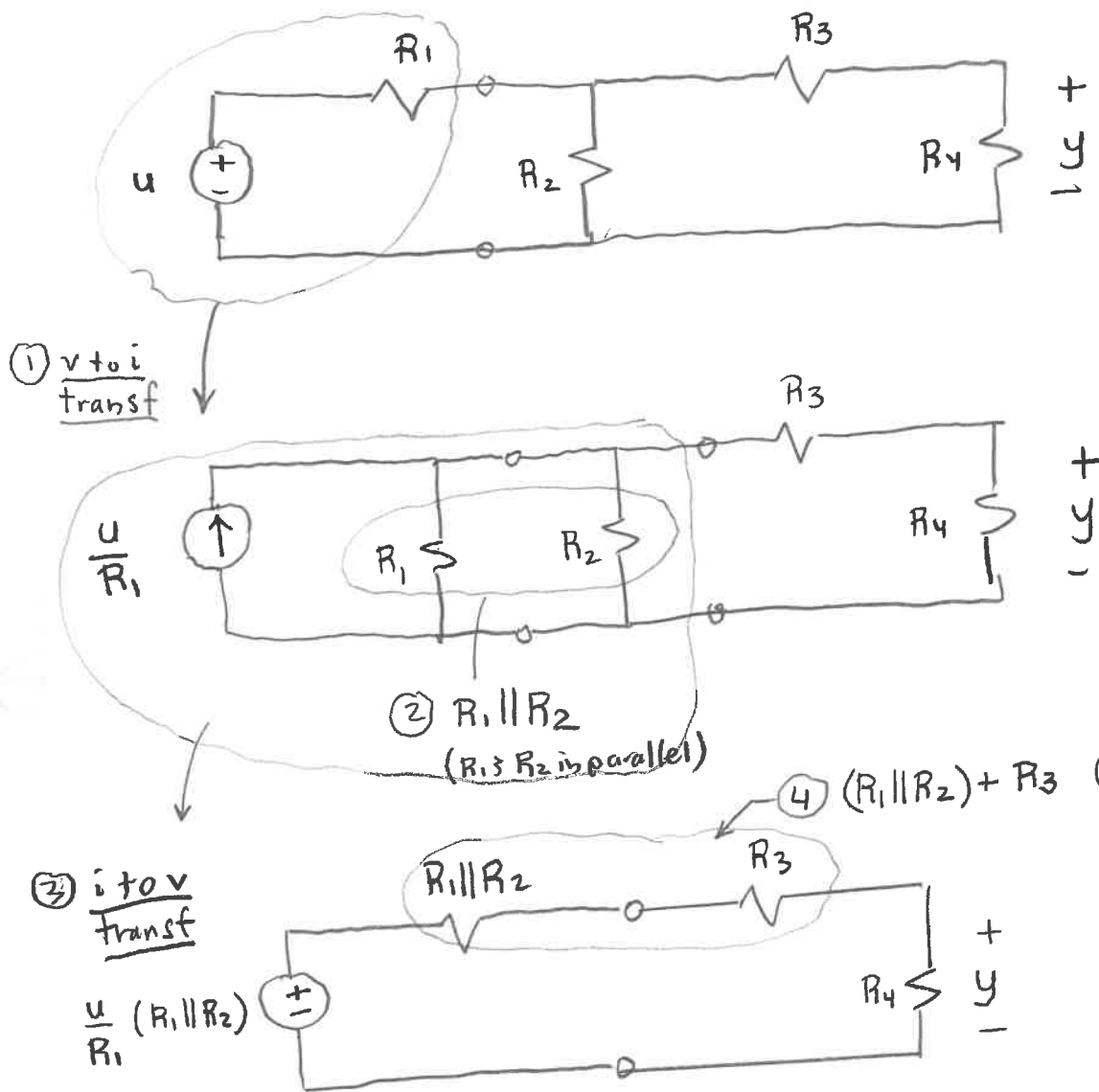


Example 17

(Example 7a via Source Transformations)

510

Relate y to u (via source transformations)



⑤ By voltage division (Example 2), we have
pg 170

$$y = \left[\frac{R_4}{[(R_1 \parallel R_2) + R_3] + R_4} \right] \frac{u}{R_1} (R_1 \parallel R_2)$$

Check for $R_i = 1$ (or R)

$$\frac{(1)(1)}{1+1} = \frac{1}{2}$$

$$y = \left[\frac{1}{\left(\frac{1}{2} + 1 + 1 \right)} \right] \frac{u}{1} \left(\frac{1}{2} \right) = \left[\frac{1}{\frac{5}{2}} \right] \frac{u}{2} = \frac{u}{5} \quad \checkmark \checkmark$$

... as obtained in Example 7a Page 170

Notes:

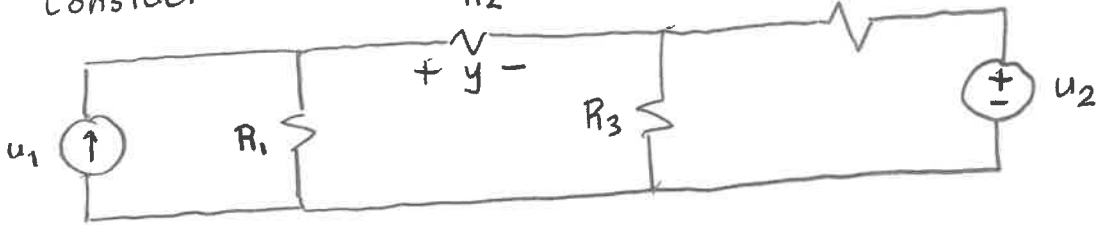
Always a good idea to do a simple check using nice R_i values!

Problem 17

(Made for Source Transformations!!)

Consider the circuit from Example 10 (page 270)

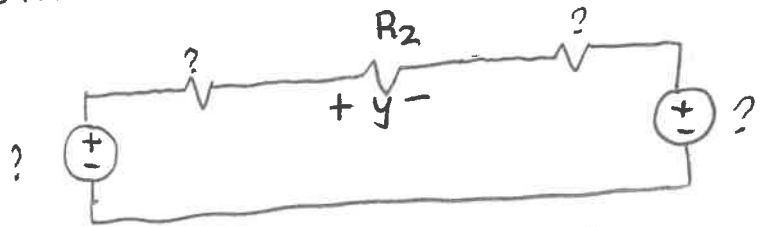
520



Hints: To get started apply KCL to get downward current through R_1 .

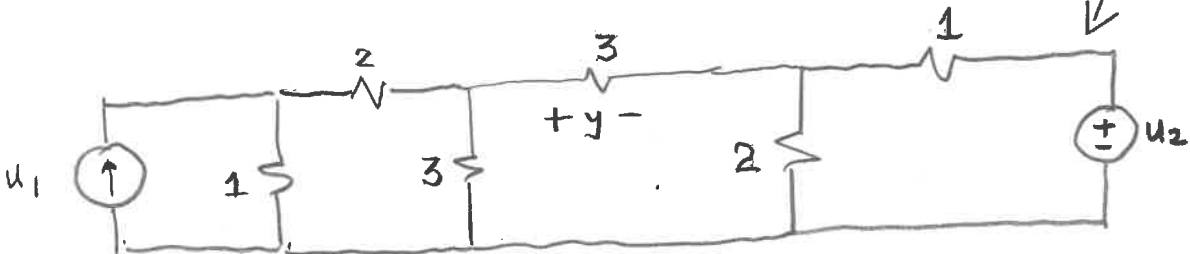
a) Relate y to u (via KVL, KCL, Ohm)

b) Now use source transformations on the left & on the right to get



Then solve for y ! (Is source transformation a COOL Method?)

Now Consider the more complicated circuit + Our 1st Cool ("Needy") Circuit

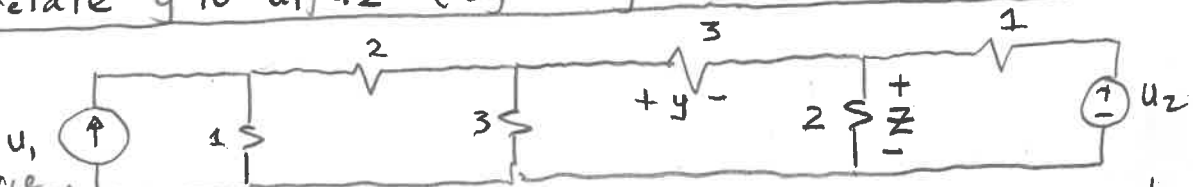


c) Use source transformations to relate y to u_1, u_2

Can this be solved with standard KVL, KCL, Ohm, without introducing another variable? NO!

d) Now relate y to u_1, u_2 (by using Z , KVL, KCL, Ohm)

* Needed to Introduce Another Variable if we don't use source trans

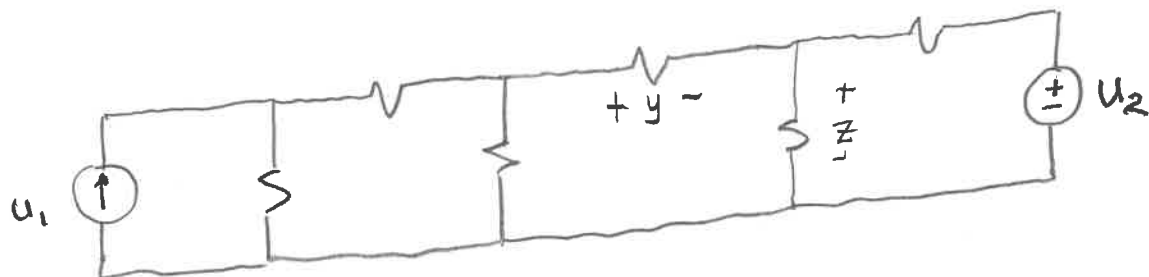


You'll get 2 eqs in the 2 unknowns y, Z ... solve for y !

Problem 17

530

Now consider the simplified (All $R_i = 1$) circuit =



e Use KVL, KCL, Ohm to relate y, z to u_1, u_2 .
You'll get 2 eqs in the 2 unknowns y, z --- solve for y !

f Now use source transformations to find y (do NOT use z !!!)
It is NOT needed when you use source transformations!

Important Observation / Lesson =

Many circuits are one (1) variable circuits;
i.e. the circuit can be completely analyzed using only one (1) variable --- additional variables (such as z above or node voltages in nodal analysis or mesh currents in mesh analysis may be completely unnecessary!!!)

The circuit above is a one (1) variable circuit when source transformations are used; i.e. the introduction of z becomes unnecessary!

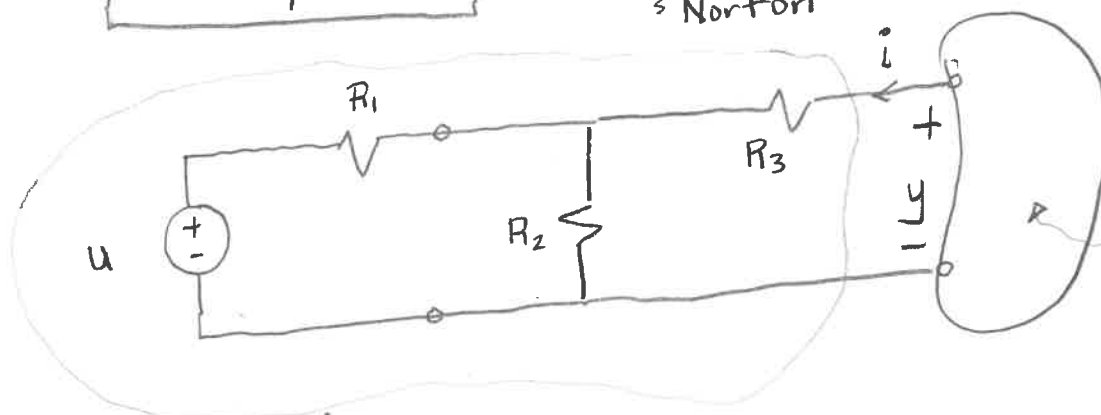
A GOOD RULE =

DON'T INTRODUCE ADDITIONAL VARIABLES UNLESS NEEDED!

Example 18

(Thevenin Equivalents)
 \approx Norton

540



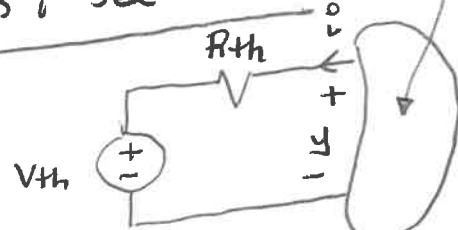
y - terminal voltage
 i - terminal current

Anything can be inside this "blob."

Main Question: How can we replace what y & i "see" with

(A "simplification" or "approximation" problem)

the much simpler cct =

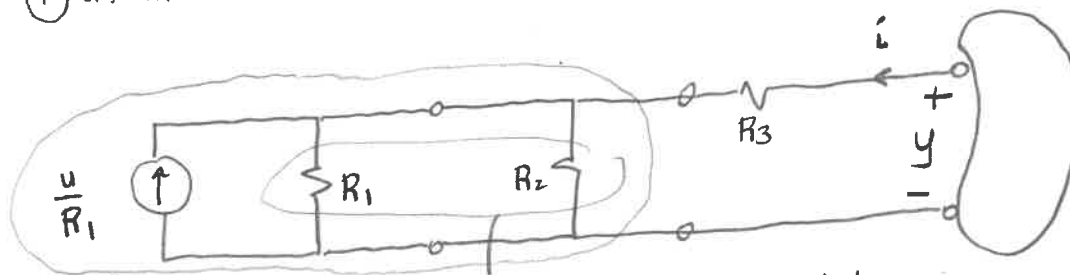


$$y = R_{th} i + V_{th}$$

Let's answer this in several ways!

a) Use source transformations to find V_{th} & R_{th}

① U & R_1 can be transformed to =



② R_1 & R_2 are in parallel
 ... combine to $R_1 \parallel R_2 \triangleq \frac{R_1 R_2}{R_1 + R_2}$



Note:
 Our analysis has greatly simplified what y sees looking leftward!

\Rightarrow From this, we get

$$V_{th} = \left(\frac{U}{R_1} \right) (R_1 \parallel R_2) \quad \& \quad R_{th} = (R_1 \parallel R_2) + R_3$$

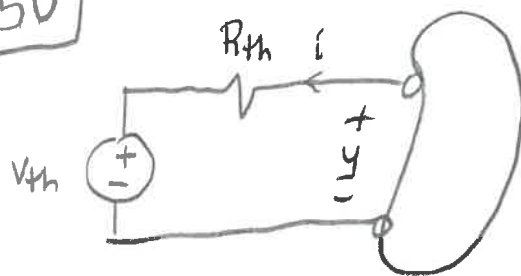
$$= \left(\frac{R_2}{R_1 + R_2} \right) U$$

Example 18

(Thevenin & Norton Equivalents)

550

Noting that $y = R_{th} i + V_{th}$



it follows that

when $i = 0$, $y = y_{oc} = V_{th}$ (open circuit)

$$\Rightarrow V_{th} = y_{oc} \triangleq y|_{i=0}$$

$$i_{sc} = i|_{y=0}$$

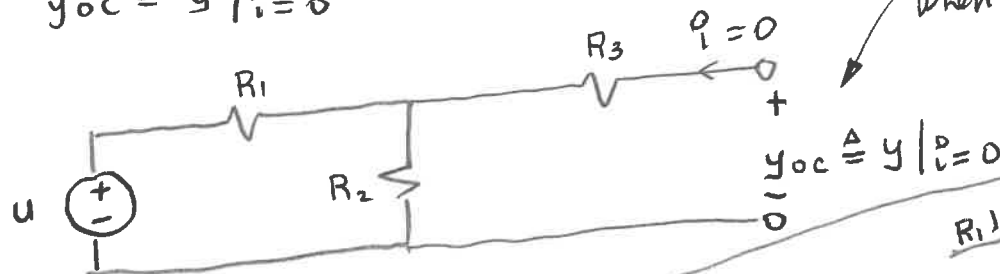
If we set $y = 0$ ($y_{sc} = 0$) (short circuit), it follows that $0 = R_{th} i_{sc} + V_{th}$ or

$$R_{th} = \frac{-V_{th}}{i_{sc}}$$

Lets apply the above to our circuit.

b Find $y_{oc} = y|_{i=0}$, $V_{th} = y_{oc}$, $i_{sc} = i|_{y=0}$, $R_{th} = \frac{-V_{th}}{i_{sc}}$

Find $y_{oc} = y|_{i=0}$



This is the relationship between y & u when $i = 0$!

By voltage division

$$V_{th} = y_{oc} = y|_{i=0} = \left(\frac{R_2}{R_1 + R_2} \right) u$$

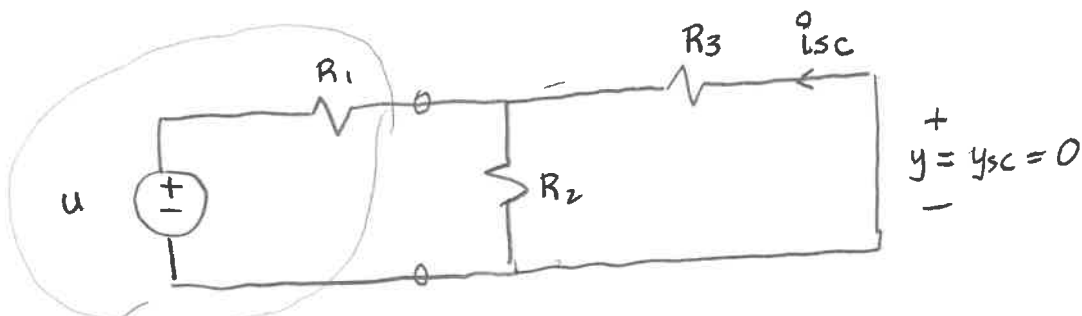
↑ agrees with what we got at bottom of page 530!

$\frac{R_1 R_2}{R_1}$ from page 530

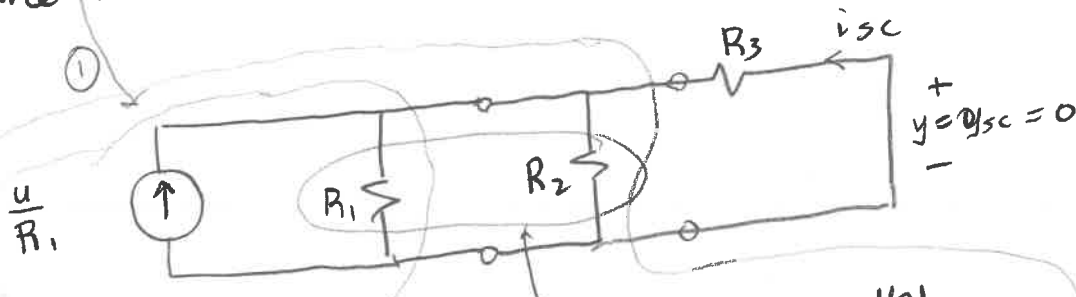
Example 18 (Thevenin & Norton Equivalents)

560

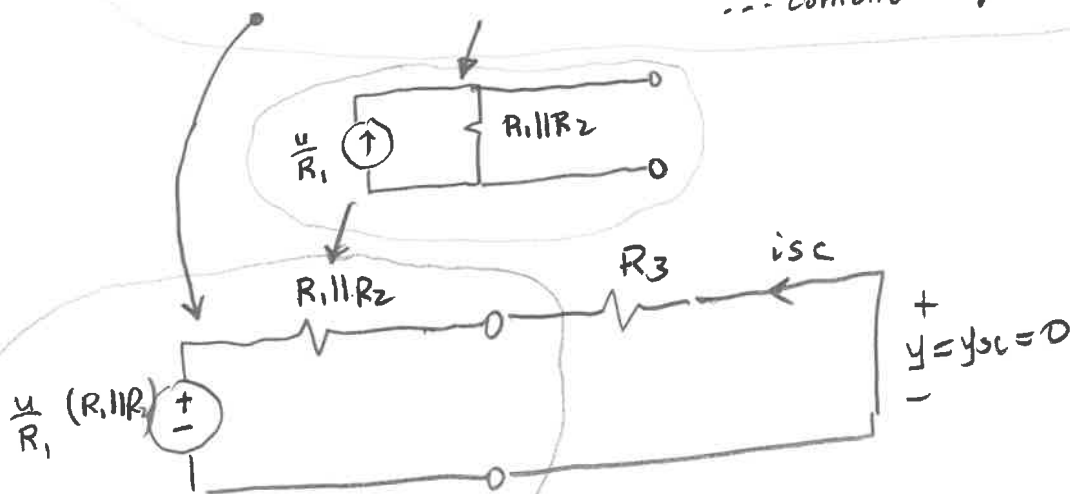
Now find $i_{sc} = i^o | y=0$



By source transformations =



② R_1 & R_2 are in parallel
... combine to get $R_1 || R_2$



$$\Rightarrow i_{sc} = \frac{-\frac{u}{R_1} (R_1 || R_2)}{(R_1 || R_2) + R_3}$$

Now, we compute

$$R_{th} = \frac{-V_{th}}{i_{sc}} =$$

$$\frac{-\frac{(R_1 || R_2)}{R_1} u}{-\frac{u}{R_1} (R_1 || R_2)} = (R_1 || R_2) + R_3$$

agrees with
result on
pg 530 !

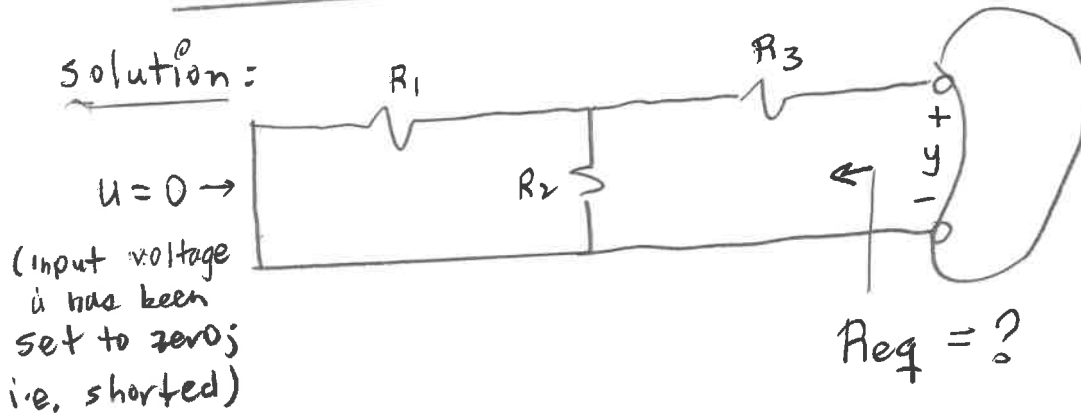
Example 18

(Thevenin & Norton Equivalents)

570

[C] Set $u=0$ & determine the equivalent resistance as seen from y looking leftward.

Solution:

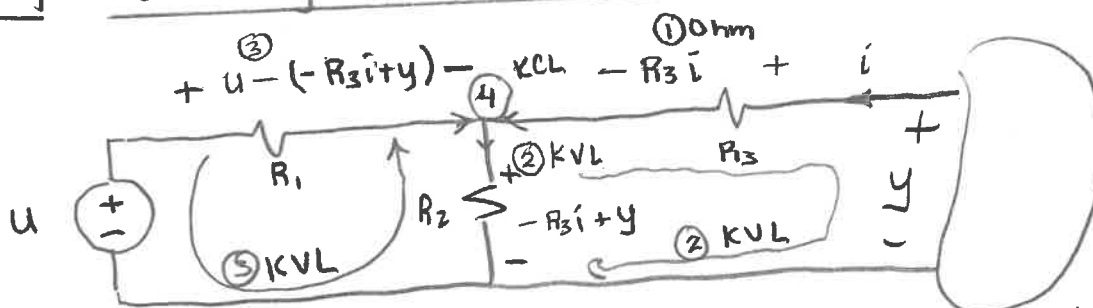


$$R_{eq} = R_3 + (R_1 \parallel R_2)$$

... but this is precisely $R_{th} = R_3 + (R_1 \parallel R_2)$.

THIS IS MOST GENERAL METHOD FOR FINDING A THEVENIN EQUIVALENT

[D] Relate y to i ($\{ u, R_1, R_2, R_3, R_4 \}$ via (KVL, KCL, Ohm))



Note:

This method is essential when the circuit has dependent sources!

$$\textcircled{4} \text{ KCL } = \left(\frac{u - (-R_3 i + y)}{R_1} \right) + i = \left(\frac{-R_3 i + y}{R_2} \right)$$

(+ Ohm)



$$\frac{u}{R_1} + i \left[\frac{R_3}{R_1} + 1 + \frac{R_3}{R_2} \right] = y \left[\frac{1}{R_1} + \frac{1}{R_2} \right]$$

algebra \Rightarrow

Example 18

(Thevenin & Norton Equivalents)

580

Multiplying both sides by R_1 yields:

$$u + i \left[R_3 + R_1 + \frac{R_1 R_3}{R_2} \right] = y \left[1 + \frac{R_1}{R_2} \right]$$

Multiplying both sides by R_2 yields:

$$R_2 u + i \left[\underbrace{R_2(R_1 + R_3) + R_1 R_3}_{R_1 R_2 + R_3(R_1 + R_2)} \right] = y [R_1 + R_2]$$

$$y = \left[\underbrace{\frac{R_1 R_2}{R_1 + R_2}}_{R_1 \parallel R_2} + R_3 \right] i + \left[\underbrace{\frac{R_2}{R_1 + R_2}}_{\frac{R_1 \parallel R_2}{R_1}} \right] u$$

$$\Rightarrow y = R_{th} i + V_{th} \quad \text{where} \quad R_{th} = (R_1 \parallel R_2) + R_3$$

$$V_{th} = \left(\frac{R_1 \parallel R_2}{R_1} \right) u \\ = \left(\frac{R_2}{R_1 + R_2} \right) u$$

as we got on page 530

Remember:

Using KVL, KCL, Ohm to relate y to i

$$y = \boxed{\phantom{R_{th}}} i + \boxed{\phantom{V_{th}}}$$

R_{th} V_{th}

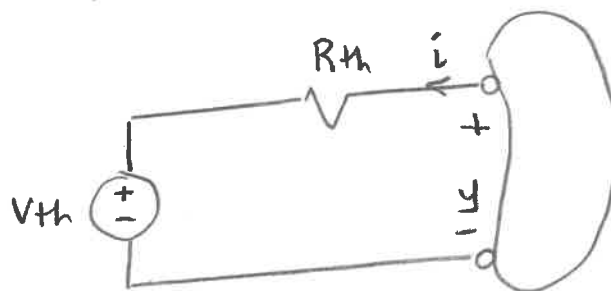
is the most general method to find R_{th} & V_{th} .

The other methods are not general; i.e. they do not always work (e.g. when we have dependent sources!!!).

Example 18 (Thevenin & Norton Equivalents)

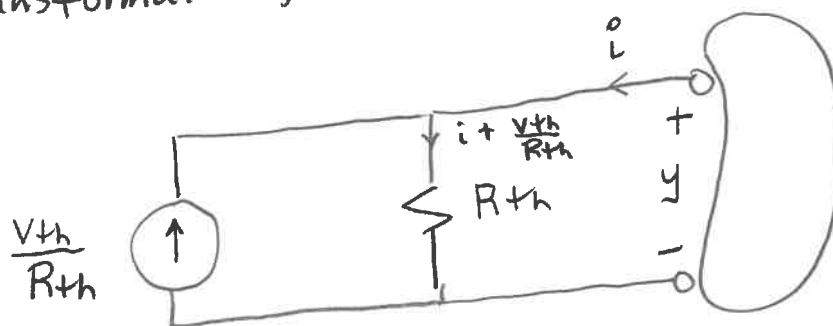
590

If our Thevenin equivalent is



$$y = R_{th} i + V_{th}$$

then the so-called Norton equivalent
(by source transformation) is

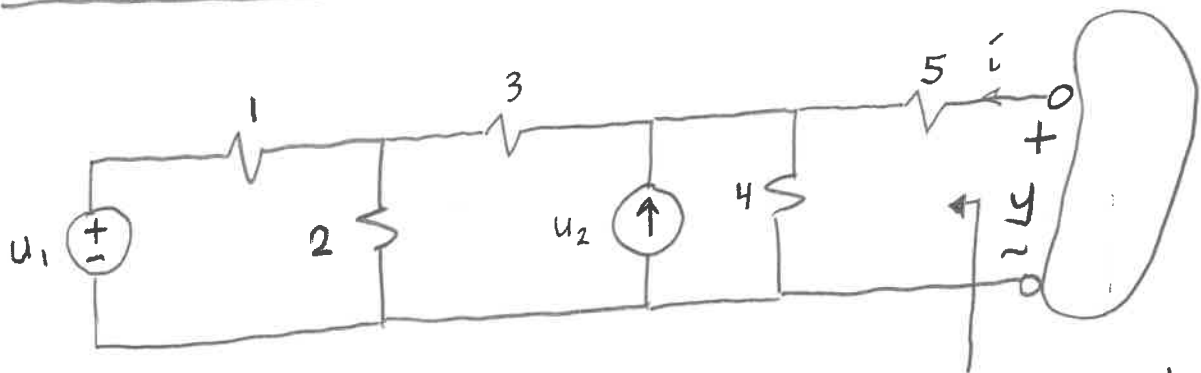


$$\begin{aligned} y &= R_{th} \left(i + \frac{V_{th}}{R_{th}} \right) \\ &= R_{th} i + V_{th} \end{aligned}$$

Problem 18

(Thevenin & Norton Equivalent)

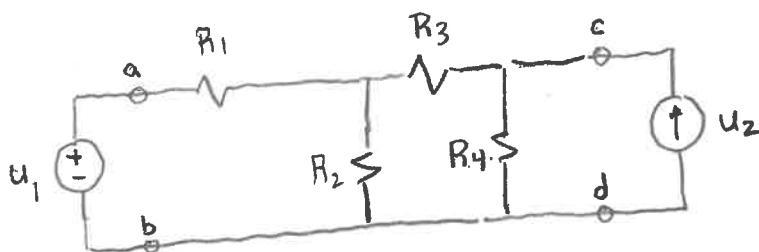
600



- [a] Find a Thevenin equivalent at y looking leftward.
 [b] " " Norton " " " "

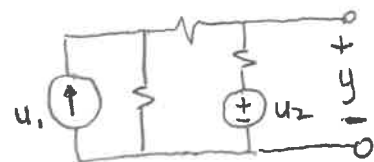
Hint: Relate y to i
 $y = \boxed{?} i + \boxed{?}$

Consider the circuit =



- [c] Find a Thevenin equivalent at u_1 (between a, b) looking rightward.
 [d] Find a Thevenin equivalent at u_2 (between c, d) " leftward.

Consider the circuit (with all $R_i = 1$) =



- [e] Find a Thevenin equivalent at y looking leftward (using KVL, KCL, Ohm)
 [f] Repeat [e] using source transformations Hint: Start at u_1 & proceed step-by-step rightward

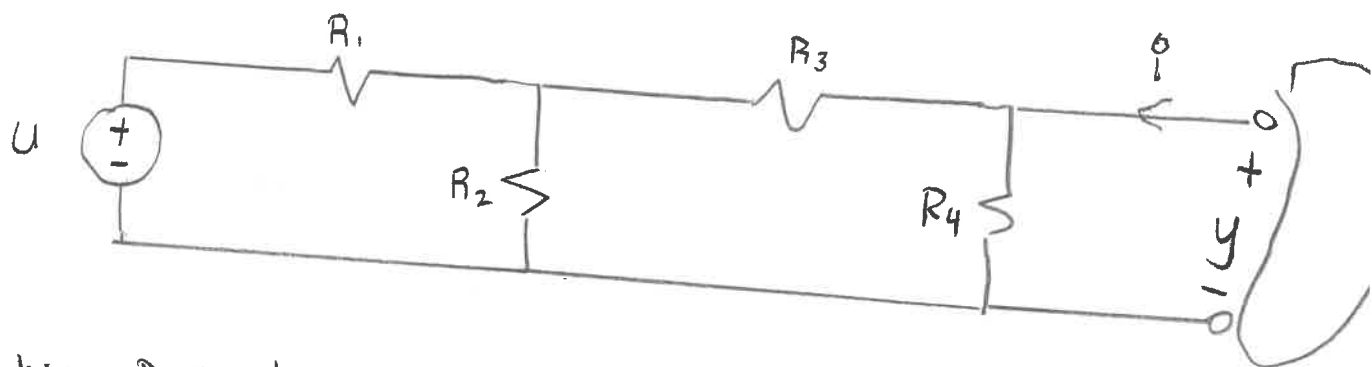
Addition to

Example 18

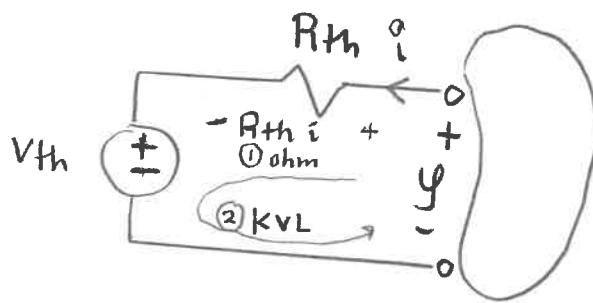
Finding a
Thevenin Equivalent
via different Methods

- Also useful for Thevenin Lab!!!

601



We wish to find a thevenin equivalent for the above circuit at y looking leftward:



$$\textcircled{2} \text{KVL} = y = R_{th} i + V_{th}$$

How do we find R_{th} & V_{th} ?

We shall do this using several methods.

--- lets go ---



Addition to

Example 18

(Thevenin Equivalent = Different Methods) / 602

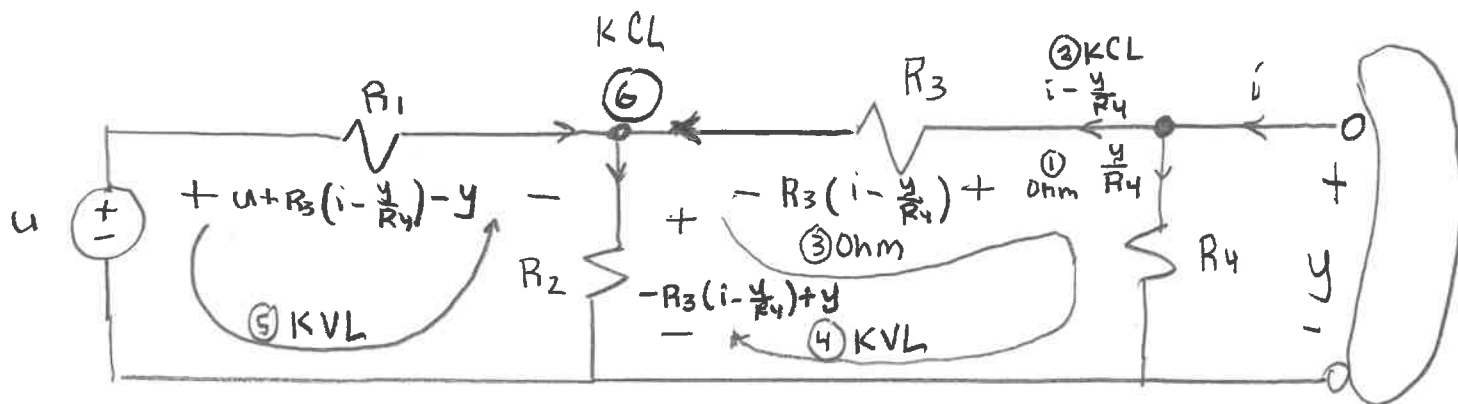
Note =

This is the most general method.
It can always be applied...

a Method 1

use KVL, KCL, Ohm to relate y to i

... even when we have dependent sources!



⑥ KCL =
(+ Ohm)

$$\left(\frac{u + R_3 \left(i - \frac{y}{R_4} \right) - y}{R_1} \right) + \left(i - \frac{y}{R_4} \right) = \left(\frac{-R_3 \left(i - \frac{y}{R_4} \right) + y}{R_2} \right)$$

"bucket"
Algebra
 \Rightarrow

$$u \left[\frac{1}{R_1} \right] + i \left[\frac{R_3}{R_1} + 1 + \frac{R_3}{R_2} \right] = y \left[\frac{R_3/R_4}{R_1} + \frac{1}{R_1} + \frac{1}{R_4} + \frac{R_3/R_4 + \frac{1}{R_2}}{R_2} \right]$$

$$\Rightarrow y = \left\{ \frac{\left[1 + R_3 \left(\frac{1}{R_1} + \frac{1}{R_2} \right) \right]}{\left(\frac{R_3}{R_4} + 1 \right) \left(\frac{1}{R_1} + \frac{1}{R_2} \right) + \frac{1}{R_4}} \right\} i + \left[\frac{\frac{1}{R_1}}{\left(\frac{R_3}{R_4} + 1 \right) \left(\frac{1}{R_1} + \frac{1}{R_2} \right) + \frac{1}{R_4}} \right] u$$

\uparrow
 $R_{th} = \{ \}$

\uparrow
 $V_{th} = [] u$

Lets do a little algebra to better understand the "form" of R_{th} & V_{th} .

a) Using KVL, KCL, Ohm to find R_{th} , V_{th} =

$$R_{th} = \frac{1 + R_3 \left(\frac{1}{R_1} + \frac{1}{R_2} \right)}{\left(\frac{R_3}{R_4} + 1 \right) \left(\frac{1}{R_1} + \frac{1}{R_2} \right) + \frac{1}{R_4}} = \frac{1 + R_3 \left(\frac{1}{R_1 \parallel R_2} \right)}{\left(\frac{R_3}{R_4} + 1 \right) \left(\frac{1}{R_1 \parallel R_2} \right) + \frac{1}{R_4}}$$

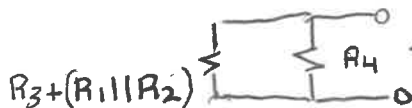
$$\frac{R_4 (R_1 \parallel R_2) \times}{R_4 (R_1 \parallel R_2) \times} = \frac{R_4 [R_1 \parallel R_2 + R_3]}{(R_3 + R_4) + R_1 \parallel R_2}$$

$$= \frac{R_4 [R_3 + R_1 \parallel R_2]}{R_4 + [R_3 + R_1 \parallel R_2]}$$

Notes

This is also useful for Thevenin Lab!

$$R_{th} = R_4 \parallel [R_3 + R_1 \parallel R_2]$$

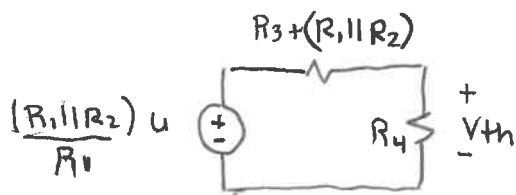


We'll see why R_{th} has this form soon!

$$V_{th} = \frac{\frac{u}{R_1}}{\left(\frac{R_3}{R_4} + 1 \right) \left(\frac{1}{R_1} + \frac{1}{R_2} \right) + \frac{1}{R_4}} = \frac{\frac{u}{R_1}}{\left(\frac{R_3}{R_4} + 1 \right) \left(\frac{1}{R_1 \parallel R_2} \right) + \frac{1}{R_4}}$$

$$= \frac{\frac{R_1 \parallel R_2}{R_1} u}{\left(\frac{R_3}{R_4} + 1 \right) + \frac{R_1 \parallel R_2}{R_4}}$$

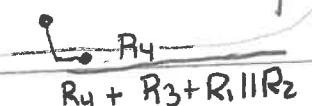
$$= \frac{R_4 \frac{R_1 \parallel R_2}{R_1} u}{R_3 + R_4 + R_1 \parallel R_2}$$



$$= \frac{(R_1 \parallel R_2) u}{R_1} \left[\frac{R_4 [R_3 + R_1 \parallel R_2]}{R_4 + [R_3 + R_1 \parallel R_2]} \right]$$

We'll also see why V_{th} has this form soon!

$$V_{th} = \left[\frac{(R_1 \parallel R_2) u}{R_1} \right] \left\{ R_4 \parallel [R_3 + R_1 \parallel R_2] \right\}$$



Addition to

Example 18

(Thevenin Equivalent: ^{Different} Methods)

604

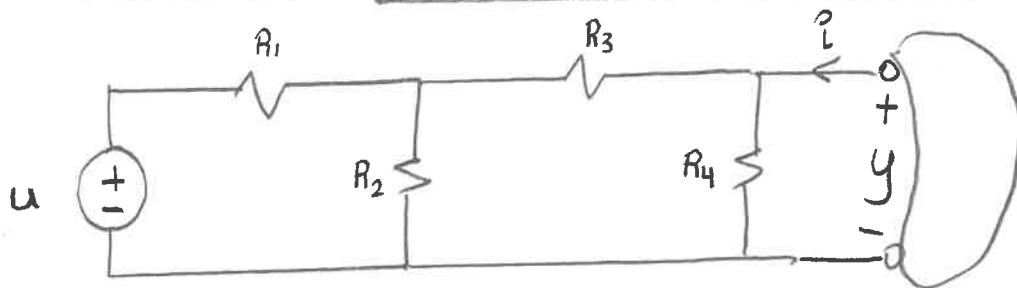
This method is "fairly straight forward" for the given circuit...

b

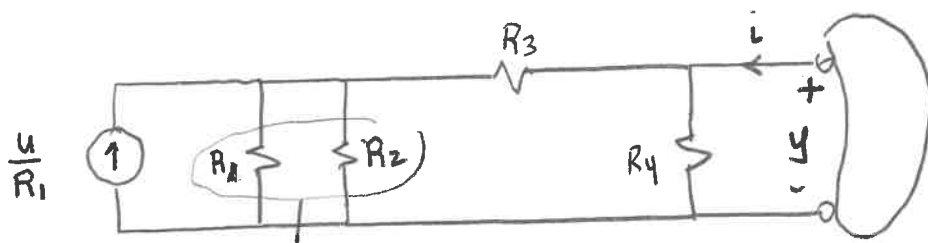
Method 2

Find V_{th} & R_{th} via repeated Source Transformations

The method also maximally illuminates the structure of V_{th} & R_{th} !

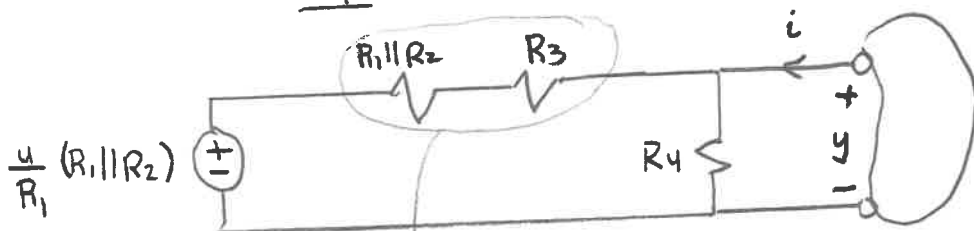


Step 1: v to i transf



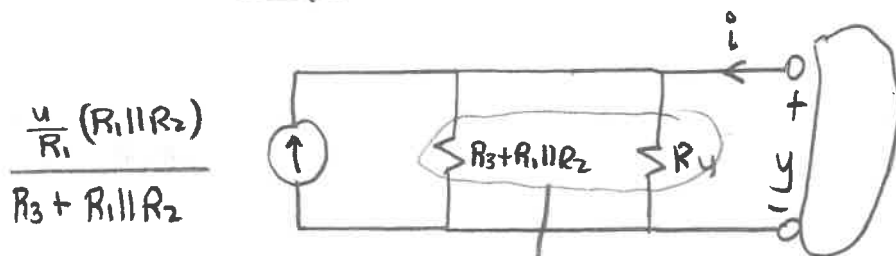
Step 2: $R_1 \parallel R_2$

Step 3: i to v transf



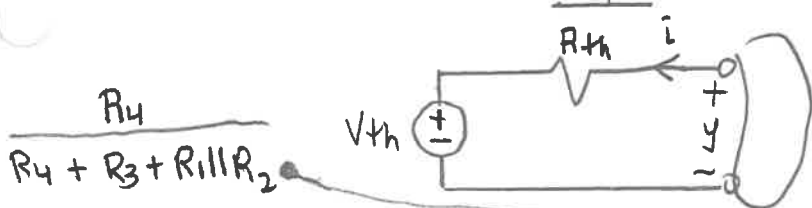
Step 4: $R_3 + R_1 \parallel R_2$ (series)

Step 5: v to i transf



Step 6: $R_4 \parallel [R_3 + R_1 \parallel R_2]$

Step 7: i to v transf



$$R_{th} = R_4 \parallel [R_3 + R_1 \parallel R_2]$$

$$V_{th} = \left[\frac{\frac{u}{R_1} (R_1 \parallel R_2)}{R_3 + R_1 \parallel R_2} \right] [R_4 \parallel (R_3 + R_1 \parallel R_2)]$$

Notes:

This is also useful for Thevenin Lab!

Repeated Source Transf Approach has Shown why R_{th} & V_{th} have the form derived in [a]!

Addition to

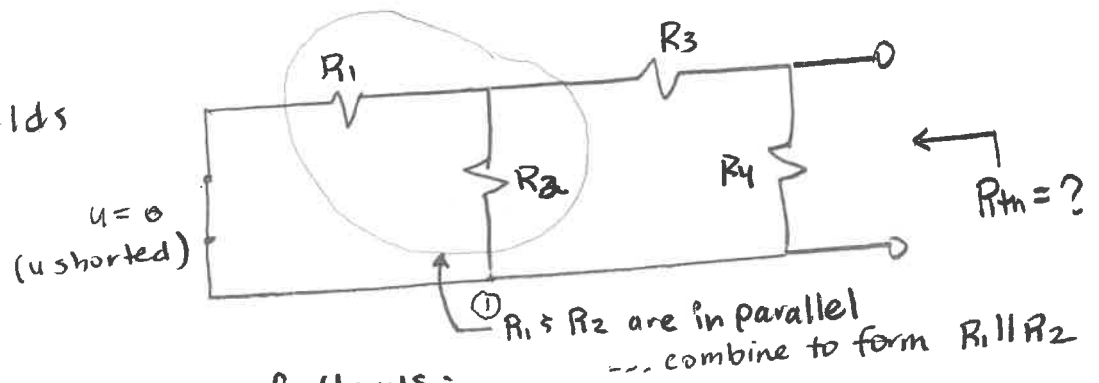
Example 18

(Thevenin Equivalent: ^{different} Methods)

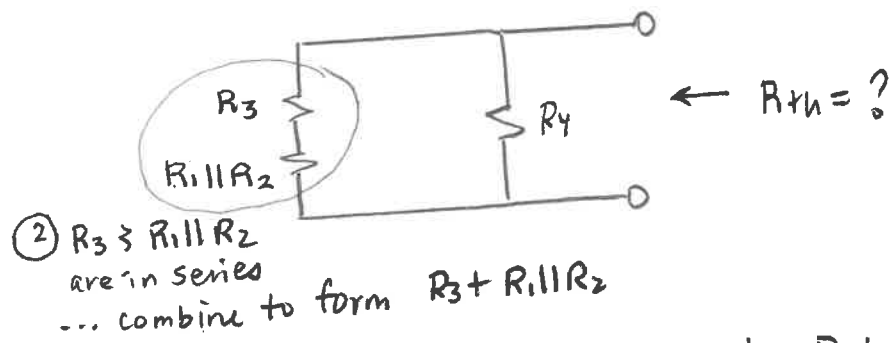
605

[c] Find R_{th} by setting $u=0$ & using series-parallel concepts.

letting $u=0$, yields



This can be rewritten as follows:



③ R_4 is in parallel with the combination $R_3 + R_1 \parallel R_2$

$$\Rightarrow R_{th} = R_4 \parallel [R_3 + (R_1 \parallel R_2)]$$

- as found in [a] & [b]

Note:

This is also useful
for Thevenin Lab!

Note: The series-parallel approach taken above in [c] is (by far) the **BEST APPROACH** to find R_{th} (& understand its form) for the circuit being considered!

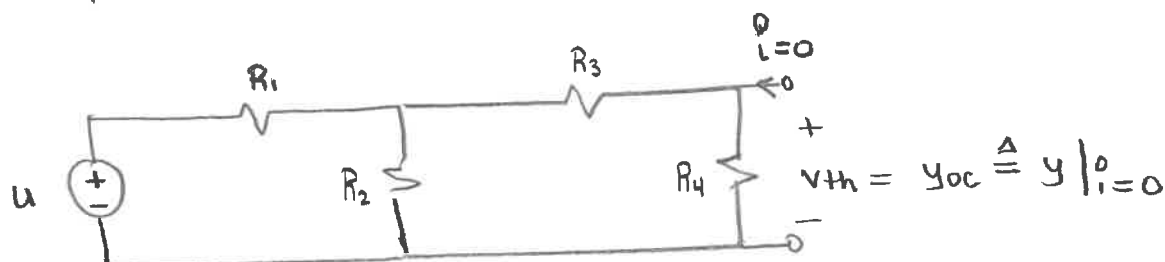
Addition to

Example 18

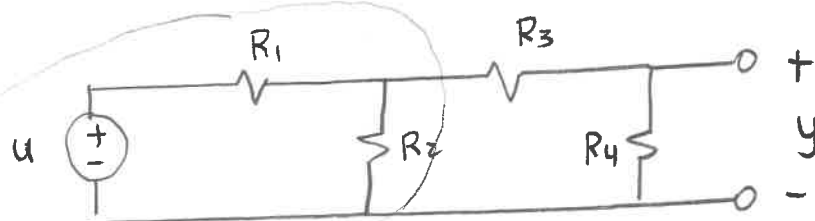
(Thevenin Equivalent: ^{different} Methods)

606

- [d] Find v_{th} by noting that it is the open circuit voltage $y_{oc} \triangleq y|_{i=0}$ (Also useful for Thevenin Lab!)

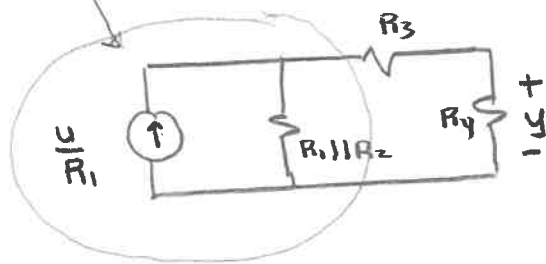


This is exactly like our standard (basic) problem of relating y to u :

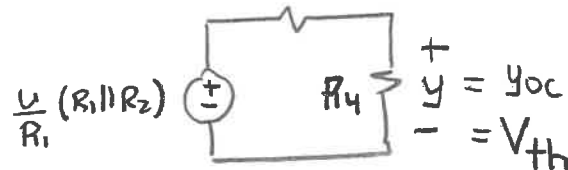


While basic KVL, KCL, Ohm can be used, the source transformation method is maximally illuminating & fairly straight forward with some practice (of course!).

①



②



③ voltage division

$$V_{th} = \left[\frac{R_4}{R_3 + R_1 \parallel R_2 + R_4} \right] \frac{u}{R_1} (R_1 \parallel R_2)$$

↑ this is cleanest way to write V_{th} !!!

Finally, we note that this may be rewritten as

$$V_{th} = \frac{R_4 [R_3 + R_1 \parallel R_2]}{R_3 + R_1 \parallel R_2 + R_4} \left[\frac{\frac{u}{R_1} (R_1 \parallel R_2)}{R_3 + R_1 \parallel R_2} \right] = \left[\frac{\frac{u}{R_1} (R_1 \parallel R_2)}{R_3 + R_1 \parallel R_2} \right] [R_4 \parallel [R_3 + R_1 \parallel R_2]]$$

as found in (a), (b)

Addition to

Example 18 (Thevenin Equivalent = Different Methods)

607

↓ Also useful for Thevenin Lab!

[e] Let $i_{sc} \triangleq i \big|_{y=0}$. Show that

$$R_{th} = - \left[\frac{y_{oc}}{i_{sc}} \right]$$

Also, show how to compute i_{sc} , compute it, & use y_{oc} & i_{sc} to compute $R_{th} (= -y_{oc}/i_{sc})$.

Since

$$y = R_{th} i + V_{th},$$

it follows that

$$V_{th} = y \big|_{i=0} \triangleq y_{oc},$$

$$\Rightarrow y = R_{th} i + y_{oc}$$

If $y = 0$, then $i = i_{sc} \triangleq i \big|_{y=0}$ &

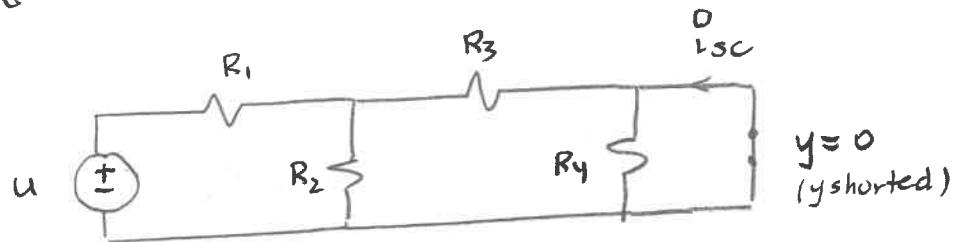
$$0 = R_{th} i_{sc} + y_{oc}$$

or

$$R_{th} i_{sc} = -y_{oc}.$$

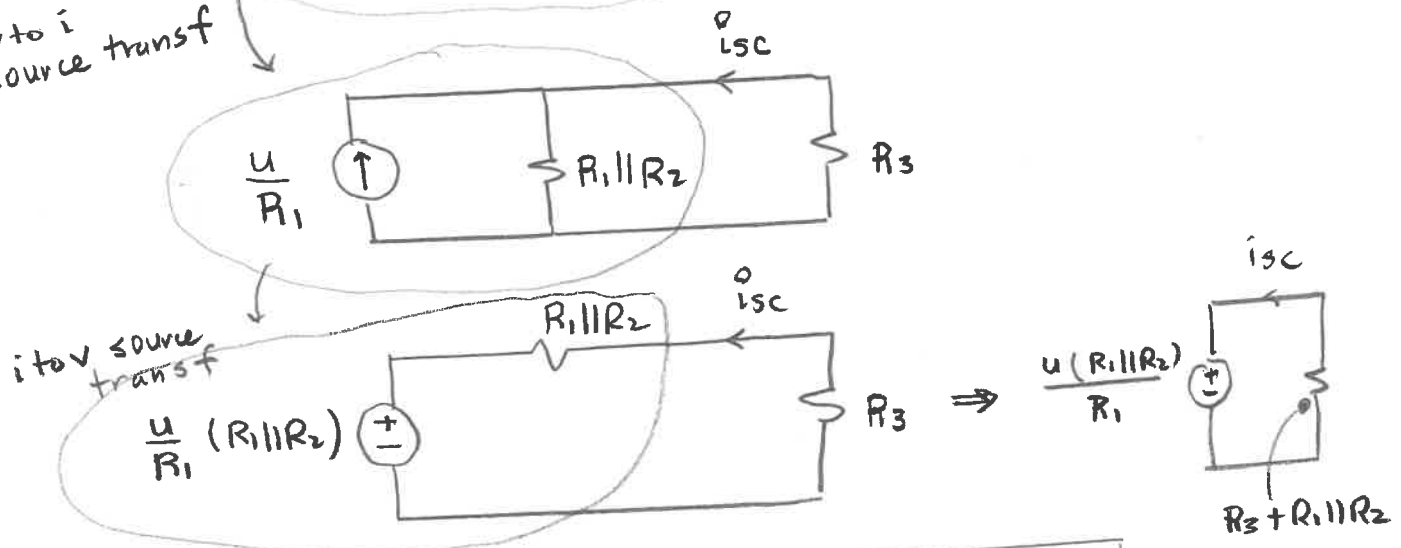
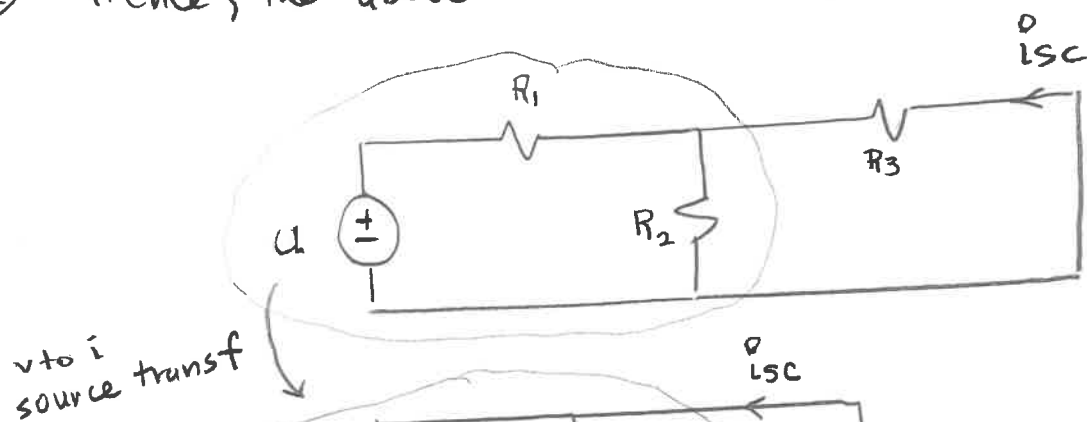
Hence,

$$R_{th} = - \left[\frac{y_{oc}}{i_{sc}} \right]$$

Find i_{sc} 

From this, it follows that there is no voltage across R_4 & hence no current through it!

⇒ Hence, the above reduces to



$$\Rightarrow i_{sc} = - \frac{\frac{u (R_1 \parallel R_2)}{R_1}}{R_3 + R_1 \parallel R_2}$$

Addition to

Example 18

(Thevenin Equivalent: ^{Different} Methods) 609

Now recall from [d] that

$$y_{oc} = v_{th} = \left[\frac{R_4}{R_4 + R_3 + R_1 \parallel R_2} \right] \frac{u(R_1 \parallel R_2)}{R_1}$$

Combining this with

$$i_{sc} = - \frac{\frac{u(R_1 \parallel R_2)}{R_1}}{R_3 + R_1 \parallel R_2}$$

yields =

$$- \left[\frac{y_{oc}}{i_{sc}} \right] = \cancel{\left[\frac{R_4}{R_4 + R_3 + R_1 \parallel R_2} \right] \frac{u(R_1 \parallel R_2)}{R_1}} \div \frac{\cancel{\frac{u(R_1 \parallel R_2)}{R_1}}}{R_3 + R_1 \parallel R_2}$$

Note:

In the lab, one can build the circuit, measure y_{oc} & i_{sc} & then use these to estimate R_{th} !

$$= \frac{R_4 [R_3 + R_1 \parallel R_2]}{R_4 + R_3 + R_1 \parallel R_2}$$

$$= R_4 \parallel [R_3 + R_1 \parallel R_2]$$

$$= R_{th} \text{ as we found in [a], [b], [c]}$$

Note: The formula

$$R_{th} = - \left[\frac{y_{oc}}{i_{sc}} \right]$$

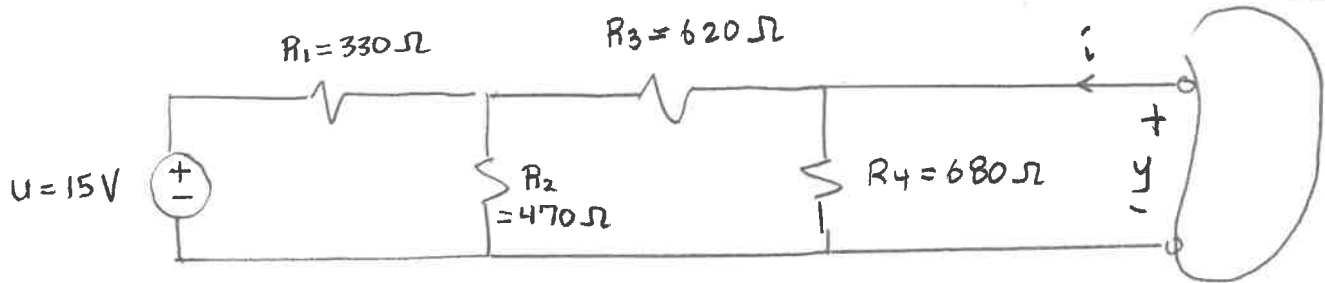
can only be used when we only have independent voltage & current sources in our circuit!!!

When the circuit has dependent sources, the formula cannot be used!!! --- One can still use KVL, KCL, Ohm as we did in [a]!!!

Thevenin Equivalent Lab Concepts

1/4

609a



We wish to find a Thevenin equivalent at y looking leftward; i.e.

$$y = R_{th} i + V_{th}$$

Step 1

Compute ideal R_{th} & V_{th} using ideal numbers above & formulae we derived for R_{th} & V_{th}

i.e.

$$R_{th} = R_4 \parallel [R_3 + (R_1 \parallel R_2)]$$

$$V_{th} = \left\{ \frac{R_4}{[R_3 + R_1 \parallel R_2] + R_4} \right\} \frac{U}{R_1} (R_1 \parallel R_2)$$

Step 2:

Measure U , R_1 , R_2 , R_3 , R_4 with your multimeter.

Now calculate your expected R_{th} & V_{th} using the above formulae.

Note: Also calculate the short circuit current =

$$i_{sc} = i|_{y=0} = \frac{-V_{th}}{R_{th}}$$

using your calculated R_{th} & V_{th} !

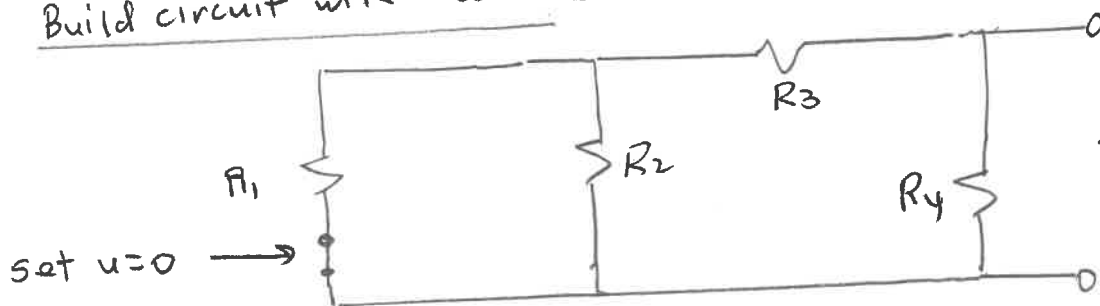
Measurements to be performed in Lab to Estimate R_{th} & V_{th}

- I Measure R_{th} directly with multimeter
- II Measure V_{th} " " "
- III Measure $i_{sc} = y|_{i=0}$ (short circuit current) with multimeter.

How do we perform these measurements?

I Measurement 1: Measure R_{th} directly with multimeter

Build circuit with $u=0$:

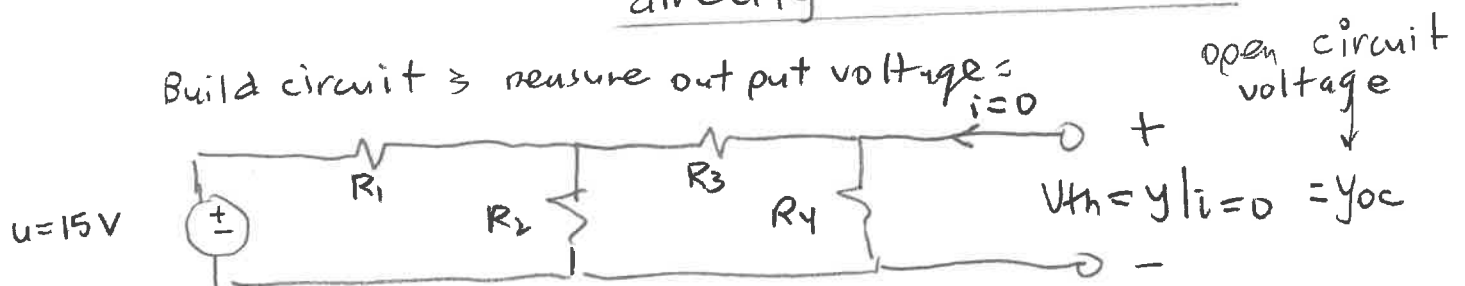


← Measure R_{th} directly with multimeter

- Compare this R_{th} to that found in step 2 above (page 1)

II Measurement 2 = Measure $V_{th} = y|_{i=0} = y_{oc}$ directly with multimeter

Build circuit & measure output voltage $= y|_{i=0}$ open circuit voltage



- compare this v_{th} to that found in step 2 above (page 1)

3/4
609c

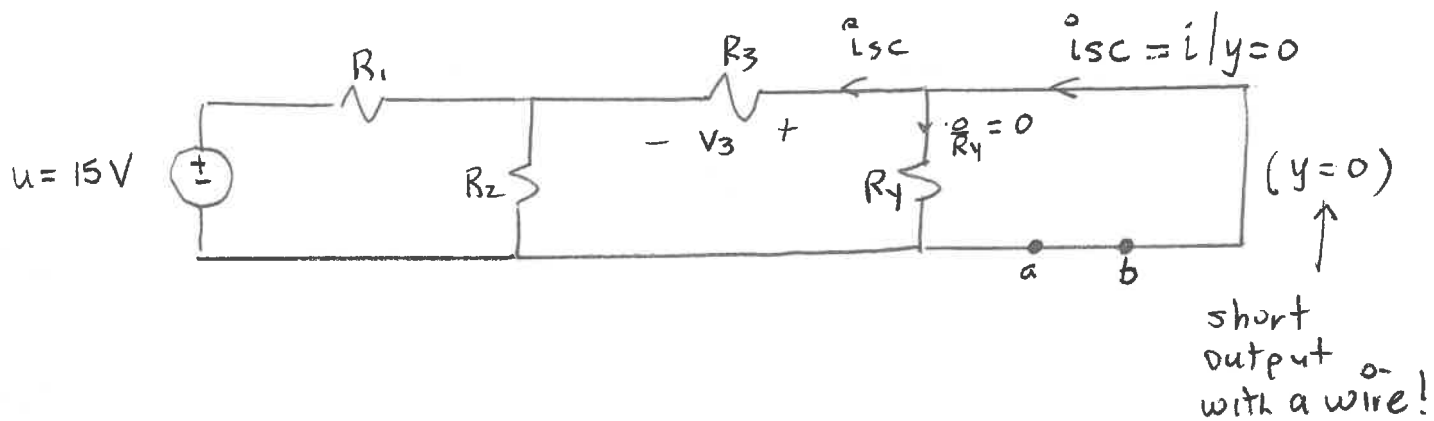
short circuit current

III

Measurement 3: Measure $i_{sc} = i |_{y=0}$

directly with multimeter

Build circuit with $y=0$ (ie short output) =



Can measure i_{sc} with your multimeter
(multimeter must be connected in series between points a & b !!!)

Note: Since voltage across R_4 is zero,
no current flows through R_4 (by Ohm!).

If you measure V_3 with your multimeter,
then you can estimate i_{sc} as:

$$i_{sc} = \frac{V_3}{R_3}$$

- compare this with what you got on page 1
step 2 !!!

- Now estimate R_{th} using

4/4

from II on page 2

609d

$R_{th} =$

$\frac{-V_{th}}$

i_{sc}

from III on page 3

- compare this with what you got on
page 1 step 2 !

Example 19

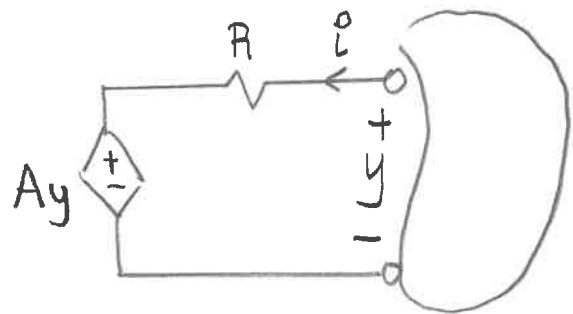
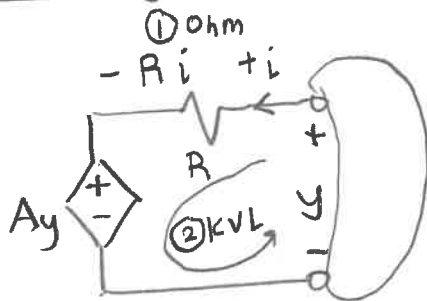
(Dependent Sources Can Result In Negative Resistance!!!)

(MORE COOLNESS!)

610

a) Relate y to i

① By Ohm



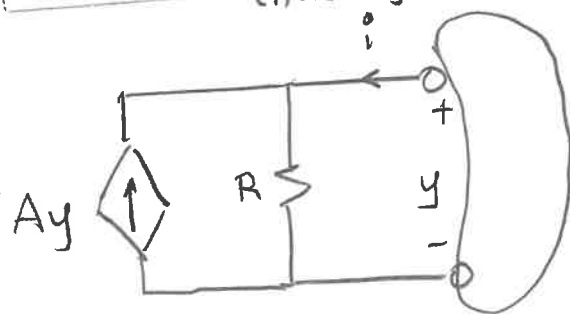
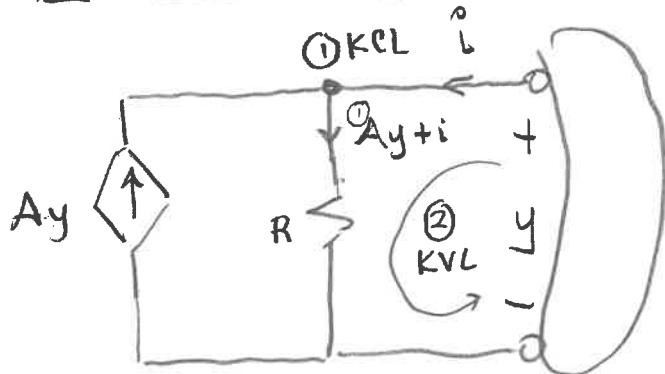
② By KVL = $y = Ri + Ay$ \Rightarrow algebra $y(1-A) = Ri$
 $\Rightarrow y = \left[\frac{R}{1-A} \right] i$

$$R_{th} = \frac{R}{1-A}$$

Hence,

$R_{th} < 0$ iff $A > 1$!
 (if and only if)

b) Relate y to i



② KVL (+Ohm) = $y = R(Ay + i) = Ri + RAy$
 $\Rightarrow y(1-RA) = Ri \Rightarrow y = \left[\frac{R}{1-RA} \right] i$

Example 19 (Dependent Sources Can Result In Negative Resistance !!!)

620

Since $y = \left[\frac{R}{1-RA} \right] i$

$$R_{th} = \frac{R}{1-RA}$$

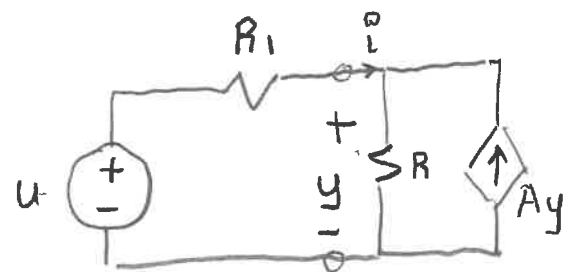
Hence,

$$R_{th} < 0 \iff A > \frac{1}{R}$$

(if and only if)

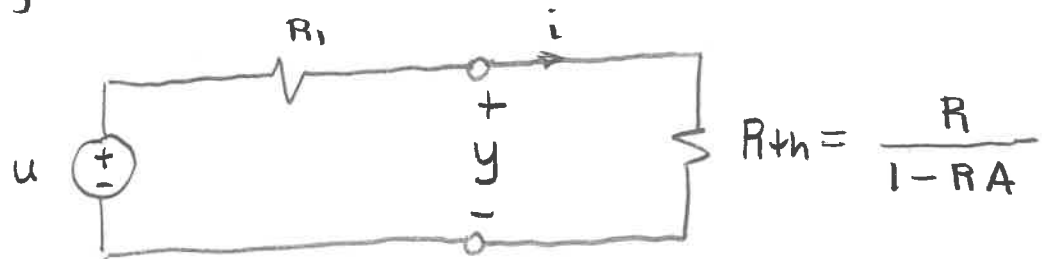
Now lets see how the above can impact a circuit.

Now consider the circuit



[c] Find a Theven equivalent from y looking rightward.

From [b] it follows that



[d] Relate y to u (Hint: This is a simple voltage divider ... see Example 2!)

From Example 2 on voltage division, we have

$$y = \left[\frac{R_{th}}{R_1 + R_{th}} \right] u$$

Example 19

(Dependent Sources Can Result In Negative Resistance!!!)

630

e) In d), find R_{th} & A such that $y = -g u$.

$$y = \left[\frac{R_{th}}{R_1 + R_{th}} \right] u = -g u \Rightarrow \frac{R_{th}}{R_1 + R_{th}} = -g$$

$$\Rightarrow R_{th} = -g R_1 - R_{th} g$$

$$\Rightarrow R_{th} (1 + g) = -g R_1$$

$$\Rightarrow R_{th} = \frac{-g R_1}{1 + g}$$

$$\text{But } R_{th} = \frac{R}{1 - RA} \Rightarrow R_{th} - R_{th} RA = R$$

$$\Rightarrow R_{th} RA = R_{th} - R$$

$$\Rightarrow A = \frac{R_{th} - R}{R_{th} R}$$

$$= \frac{1}{R} - \frac{1}{R_{th}}$$

$$= \frac{1}{R} - \frac{1}{\frac{-g R_1}{1 + g}}$$

$$= \frac{1}{R} + \frac{1 + g}{g R_1}$$

$$A = \frac{1}{R} + \frac{1}{R_1} \left(1 + \frac{1}{g} \right)$$

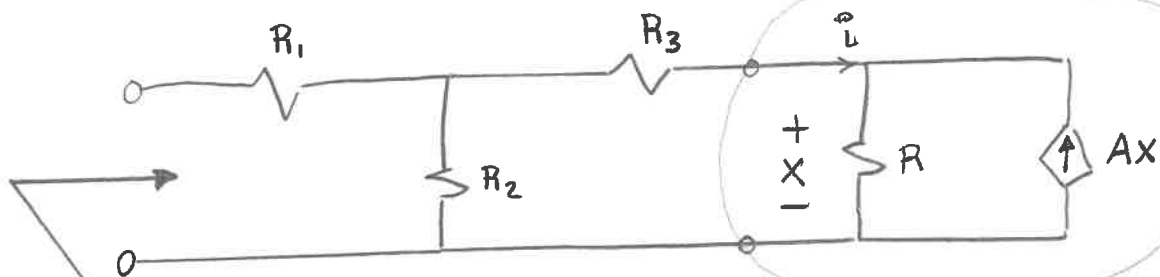
↑
This is how one would choose A (design)
so that $y = -g u$!

--- this is design!

Example 19

640

Consider the more complicated circuit =



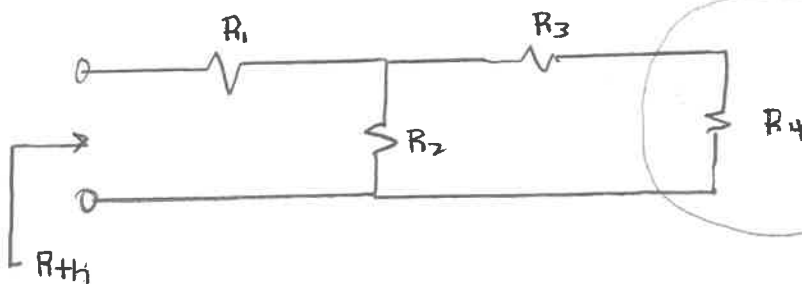
[f] Find R_{th}

1st we note (as in [b]) that

$$\begin{aligned} X &= R(i + Ax) \\ &= Ri + RAX \\ &= \left(\frac{R}{1-RA} \right) i \end{aligned}$$

Hence, the above ^{circuit} can be rewritten

$$R_4 \triangleq \frac{R}{1-RA}$$



From this, it follows from series-parallel concepts that

$$R_{th} = R_1 + R_2 \parallel (R_3 + R_4)$$

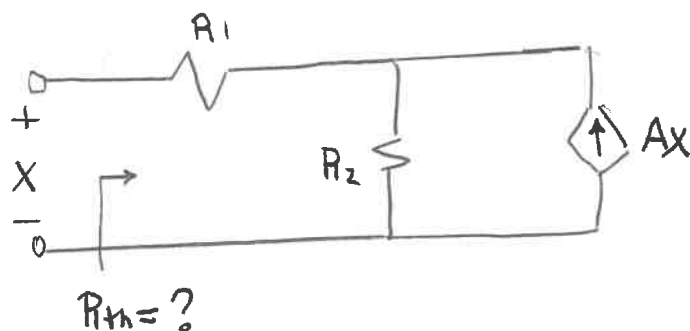
where

$$R_4 \triangleq \frac{R}{1-RA}$$

Example 19

650

- [g] Now consider a modified version of the circuit considered in [b]:



Note: If $R_1 = 0$, then we have the circuit in [b] :

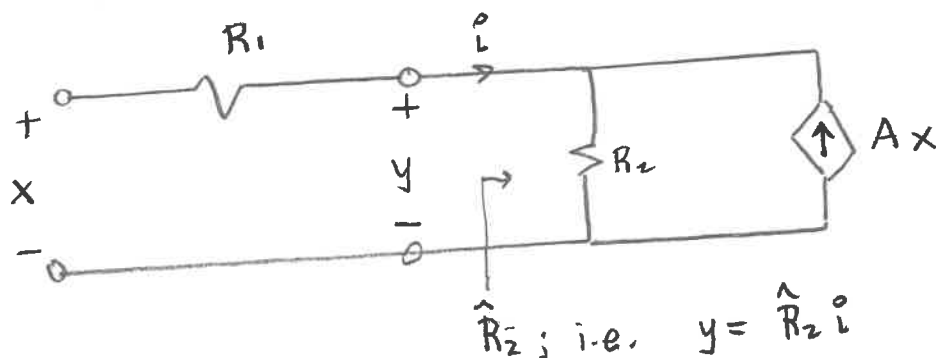
$$R_{th} = \frac{R_2}{1 - R_2 A}$$

How do we find R_{th} when $R_1 \neq 0$?

We know that

$$R_{th} = R_1 + \hat{R}_2 \quad \text{for some } \hat{R}_2$$

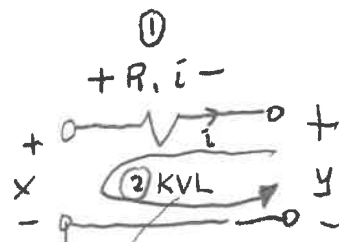
... but how do we find \hat{R}_2 ?



How can we relate y to i ?

From ohm's KVL, we note that $y = -R_1 i + x$

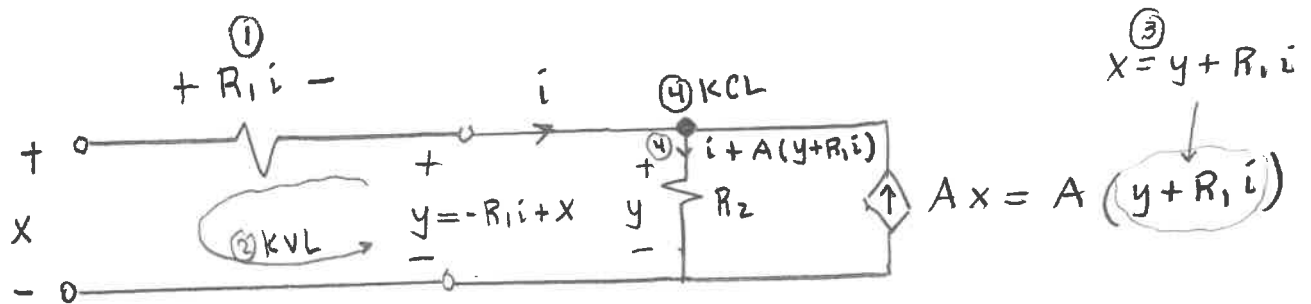
Hence, $x = y + R_1 i$ --- Now we can ROCK! ---



Example 19

660

Using $x \stackrel{(3)}{=} y + R_1 i$, we can relate y to i (to get \hat{R}_2) by considering the following:



From this, it follows that

(5) Ohm across R_2 (4) KCL at top right node

$$y = R_2 \left[i + A(y + R_1 i) \right]$$

$$= R_2 i + R_2 A y + R_2 A R_1 i$$

$$= R_2 [1 + A R_1] i + R_2 A y$$

$$= R_2 \left[\frac{1 + A R_1}{1 - A R_2} \right] i$$

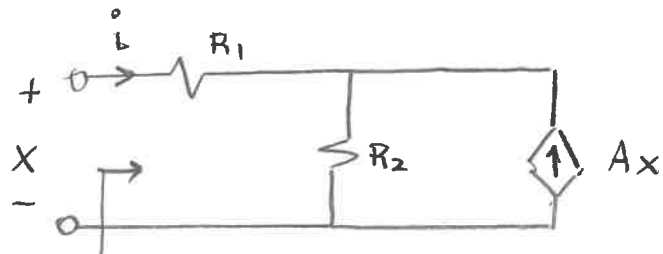
$$= \hat{R}_2 i$$

$$\Rightarrow \hat{R}_2 \triangleq R_2 \left[\frac{1 + A R_1}{1 - A R_2} \right]$$

$$\Rightarrow \boxed{\begin{aligned} R_{th} &= R_1 + \hat{R}_2 \\ \hat{R}_2 &\triangleq R_2 \left[\frac{1 + A R_1}{1 - A R_2} \right] \end{aligned}}$$

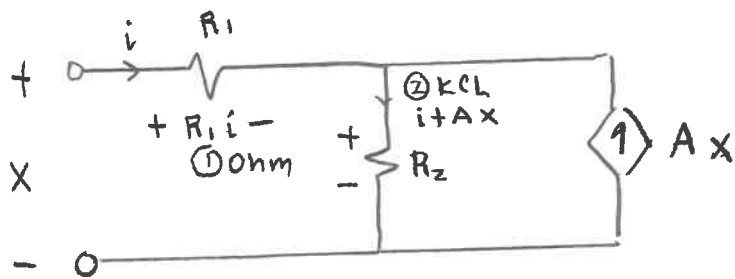
Note: when $R_1 = 0$, $R_{th} = \hat{R}_2 = R_2 \left[\frac{1+0}{1-A R_2} \right] = \frac{R_2}{1-A R_2}$ as in [b]!

Consider the same circuit as in [9]:



$R_{th} = ?$ (R_{th} was found in [9] on pages 650-660)

[h] Lets find R_{th} by relating x to i (i.e. $x = R_{th} i$)



$$\begin{aligned} \textcircled{3} \text{ KVL} = \quad X &= R_1 i + R_2 (i + A x) \\ (+0 \text{ ohm}) &= (R_1 + R_2) i + A R_2 x \end{aligned}$$

$$= \left[\frac{R_1 + R_2}{1 - A R_2} \right] i$$

using answer from [9] \rightarrow intelligent algebra

$$= \left[\frac{R_1 (1 - A R_2) + R_2 + \textcircled{R_1 A R_2}}{1 - A R_2} \right] i$$

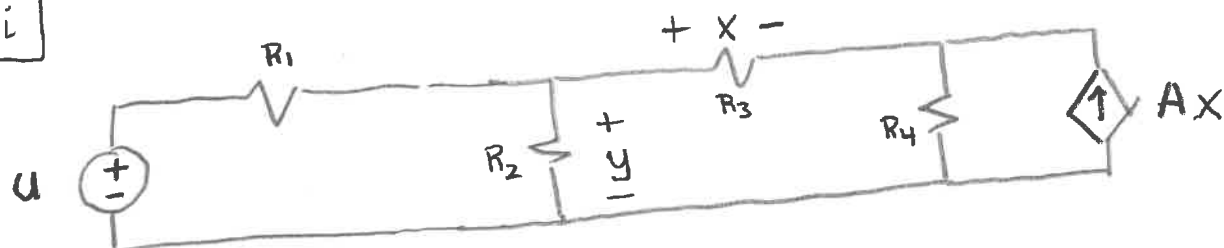
added to keep numerator the same

$$R_{th} = R_1 + R_2 \left[\frac{1 + A R_1}{1 - A R_2} \right] \dots \text{just as we got in [9]!} \quad \textcircled{\ddot{\smile}}$$

Example 19

680

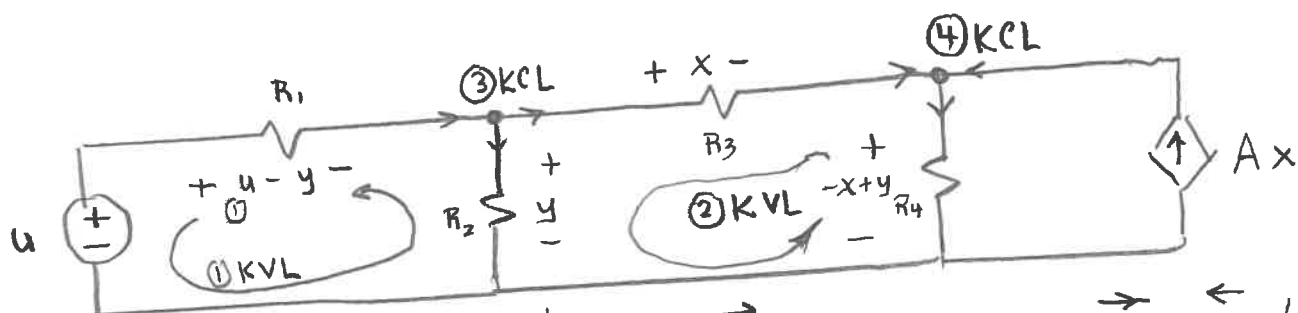
i



Relate y to u Hint: Will need 2 eqs in the 2 unknowns (y, x).

Solution:

Let's take a straight KVL-KCL-Ohm approach:



$$\textcircled{3} \text{ KCL} = \left(\frac{u-y}{R_1} \right) = \left(\frac{y}{R_2} \right) + \left(\frac{x}{R_3} \right)$$

$$\downarrow \text{algebra}$$

$$\frac{u}{R_1} = y \left[\frac{1}{R_1} + \frac{1}{R_2} \right] + x \left[\frac{1}{R_3} \right]$$

$$\textcircled{4} \text{ KCL} = \left(\frac{x}{R_3} \right) + Ax = \left(\frac{-x+y}{R_4} \right)$$

$$\downarrow \text{algebra}$$

$$x \left[\frac{1}{R_3} + A + \frac{1}{R_4} \right] = \frac{y}{R_4}$$

$$\Rightarrow x = \left[\frac{\frac{1}{R_4}}{A + \frac{1}{R_3} + \frac{1}{R_4}} \right] y$$

Substitute in for x

$$\frac{u}{R_1} = y \left[\frac{1}{R_1} + \frac{1}{R_2} \right] + \left[\frac{\frac{1}{R_4}}{A + \frac{1}{R_3} + \frac{1}{R_4}} \right] \cdot \frac{y}{R_3} = y \left[\frac{1}{R_1} + \frac{1}{R_2} + \frac{\frac{1}{R_3 R_4}}{A + \frac{1}{R_3} + \frac{1}{R_4}} \right]$$

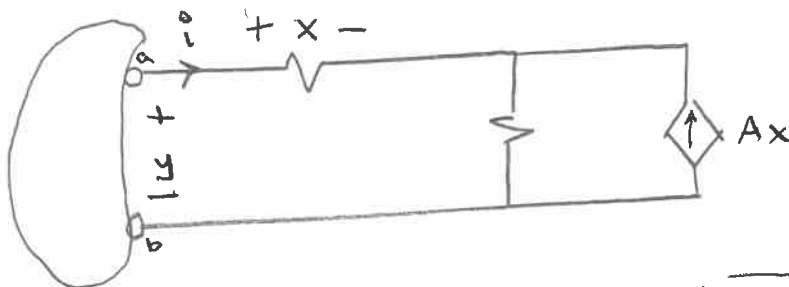
$$\Rightarrow y = \left[\frac{\frac{1}{R_1}}{\frac{1}{R_1} + \frac{1}{R_2} + \frac{\frac{1}{R_3 R_4}}{A + \frac{1}{R_3} + \frac{1}{R_4}}} \right] u \stackrel{R_1=1}{=} \left[\frac{1}{2 + \left(\frac{1}{A+2} \right)} \right] u = \left(\frac{A+2}{2A+5} \right) u = \left[\frac{A+2}{2A+5} \right] u$$

Problem 19

(Assume all $R_i = 1$)

690

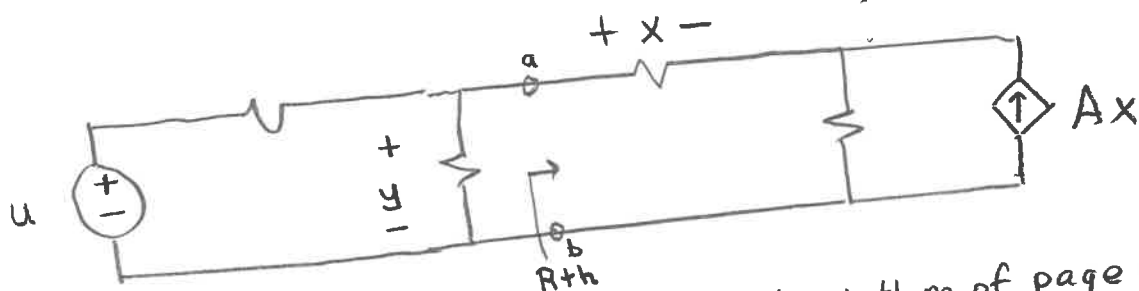
- a Find a Thevenin equivalent at y looking rightward for



by relating y to i i.e. $y = R_{th} i$.

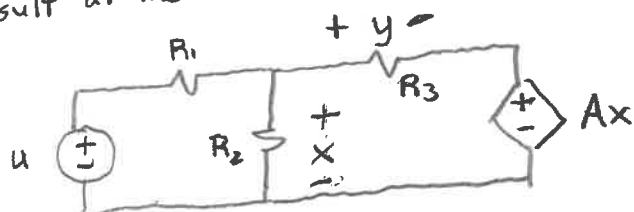
Hint: You'll need 2 eqs in the 2 unknowns y & x .
Get rid of x to get the desired relationship
relating y to i i.e. $y = R_{th} i$.

- b Use the above R_{th} , parallel concepts, & voltage division to solve for y in the following circuit
(Assume all $R_i = 1$)



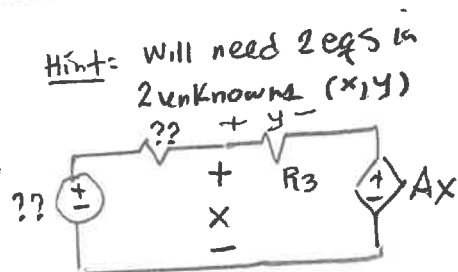
Note: You MUST get the result at the bottom of page 680!

Consider the following circuit



- c Relate y to u using KVL, KCL, Ohm. Hint: Will need 2 eqs in 2 unknowns (x, y)

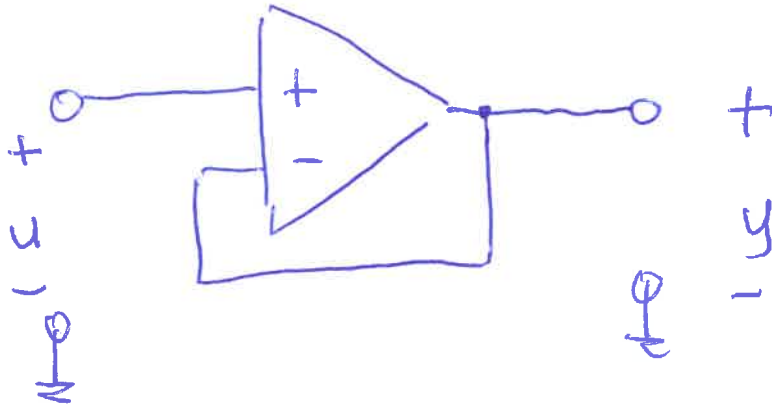
- d Apply 2 source transformations to get i →
Then relate y to u
(Show that c & d yield same result!)



Example 20

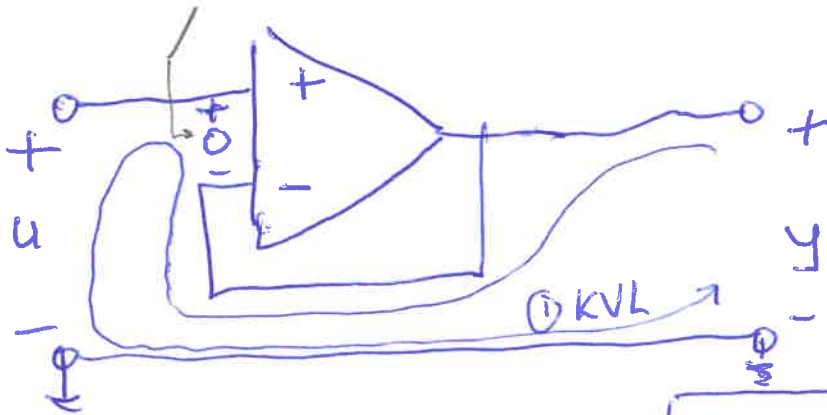
Analysis of Buffer/Follower Amplifier^{op-amp}
With Standard Model

700



a) Relate y to u using ideal op-amp assumptions

ideal op-amp assumption (near zero voltage across \pm terminals)



$$y = -0 + u \Rightarrow \boxed{y = u}$$

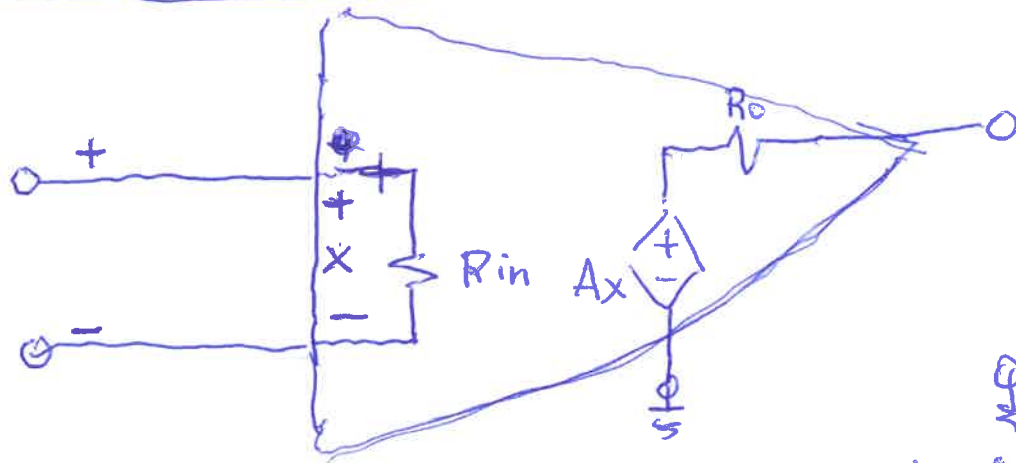
Ideal Buffer/Follower
Input/Output Relation

Example 20

(Analysis of Buffer/Follower...)

710

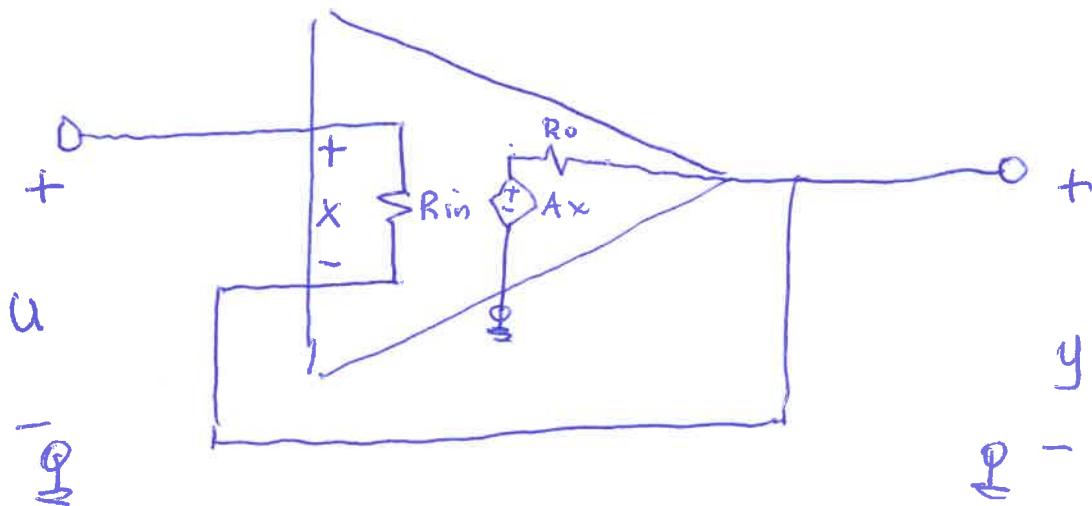
Standard Model For an Op-Amp



Note =
Typically,
 R_{in} large
 R_o small
 A large

R_{in} - op-amp input resistance (impedance)
 R_o - " " output " " " " gain

Buffer/Follower Amplifier with Standard Model



Lets redraw the above.

Typical 741
Numbers =

$$R_{in} = 2M\Omega$$

$$R_o = 75\Omega$$

$$A = 200K$$

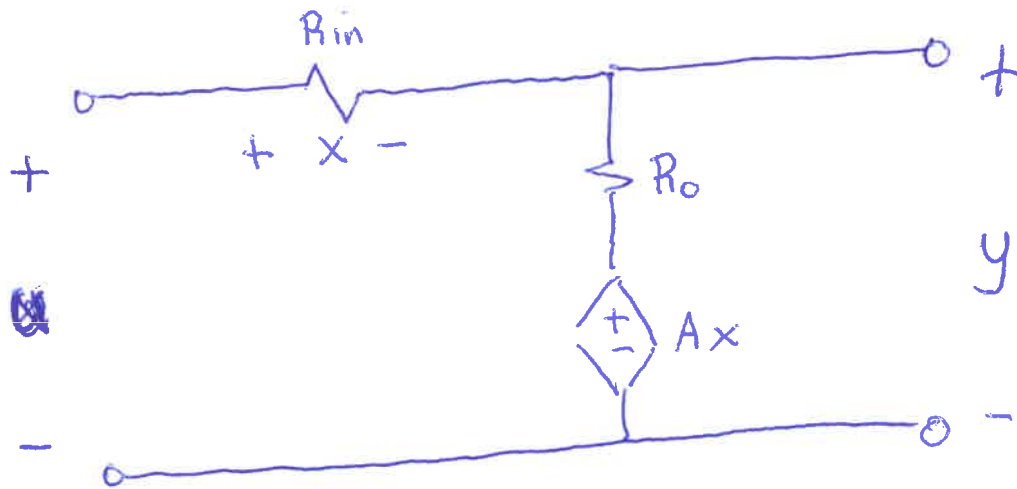
741 Reference = www.electronicshub.org/ic-741-op-amp-basics/

Example 20

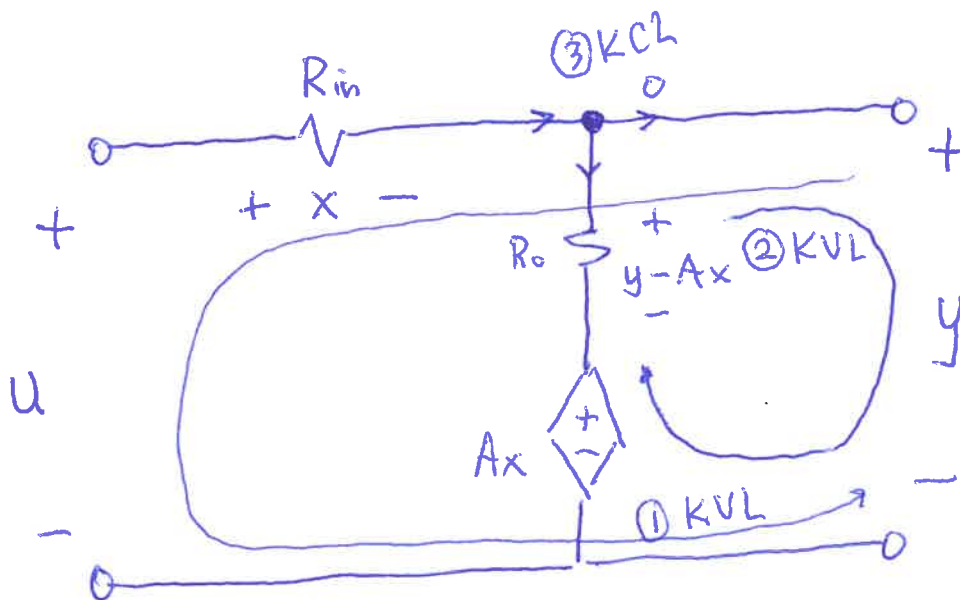
(Analysis of Buffer/Follower...)

720

Buffer/Follower Amplifier with Standard Model



b Relate y to u using standard op-amp model



$$\textcircled{1} \text{ KVL} = y = -x + u$$

$$\textcircled{3} \text{ KCL} \quad (+0\text{nm})$$

$$\left(\frac{x}{R_{in}}\right) = \left(\frac{y-Ax}{R_o}\right) + 0$$

Example 20

(Analysis of Buffer/Follower...)

730

We have

$$y = -x + u$$

$$\downarrow$$
$$x = u - y$$

$$x \left[\frac{1}{R_{in}} + \frac{A}{R_o} \right] = \frac{y}{R_o}$$

get rid of x
to solve for y

$$[u - y] \left[\frac{1}{R_{in}} + \frac{A}{R_o} \right] = \frac{y}{R_o}$$

$$\Rightarrow u \left[\frac{1}{R_{in}} + \frac{A}{R_o} \right] = y \left[\frac{1}{R_{in}} + \frac{A}{R_o} + \frac{1}{R_o} \right]$$

$$\times R_{in} R_o \Rightarrow u [R_o + A R_{in}] = y [R_o + A R_{in} + R_{in}]$$

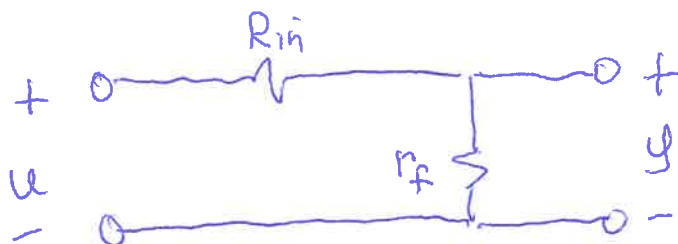
$$\Rightarrow \boxed{\frac{y}{u} = \left[\frac{A R_{in} + R_o}{R_{in} + A R_{in} + R_o} \right]}$$

Cool

Observation:

I/O relation for Buffer/Follower
Amplifier with standard op-amp model

The above input-output relation has a simple voltage divider interpretation =



where

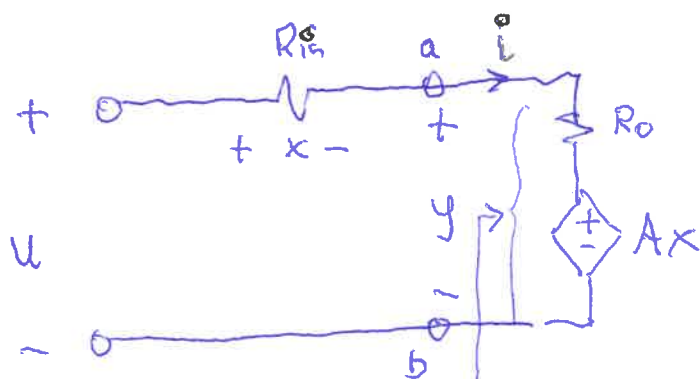
$$\boxed{r_f = A R_{in} + R_o}$$

Example 20

(Analysis of Buffer/Follower...)

740

Let try to understand why $r_f = A R_{in} + R_o$.



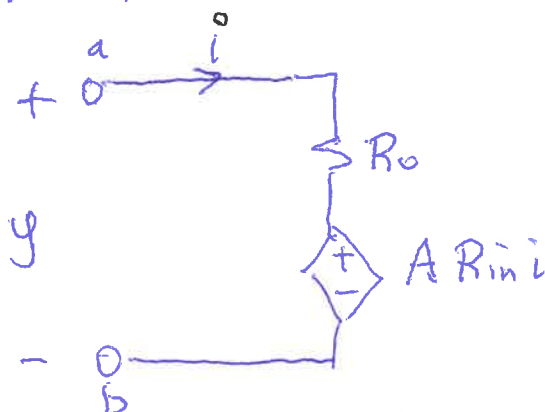
Why is it that this looks like

$$r_f = A R_{in} + R_o$$

Lets find a Thevenin equivalent between terminals a & b looking rightward.

We need to relate y to i!

By Ohm, $x = R_{in} i$ & we have



Hence, by KVL (or Ohm) we have

$$\begin{aligned} y &= R_o i + A R_{in} i \\ &= (A R_{in} + R_o) i \quad \text{where} \\ &= r_f i \quad r_f \triangleq A R_{in} + R_o \end{aligned}$$

Example 20

(Analysis of Buffer/Follower...)

750

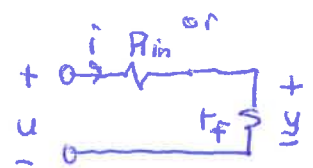
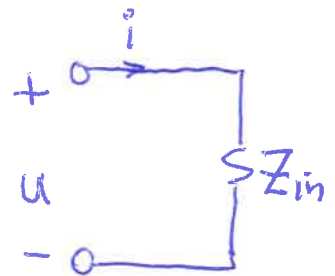
- c Determine Input Impedance (resistance) Z_{in} at a looking rightward

From the above analysis

$$Z_{in} = R_{in} + r_f$$

where

$$r_f = R_o + A R_{in}$$



- d Let examine the I/O relationship derived in (b) as $R_{in} \rightarrow \infty$, $R_o \rightarrow 0$, & $A \rightarrow \infty$

From (b) $H \triangleq \frac{y}{u} = \left[\frac{A R_{in} + R_o}{R_{in} + A R_{in} + R_o} \right]$, it follows that $H(R_{in}, R_o, A)$

$$\lim_{R_o \rightarrow 0} H(R_{in}, R_o, A) = \frac{A R_{in}}{R_{in} + A R_{in}}$$

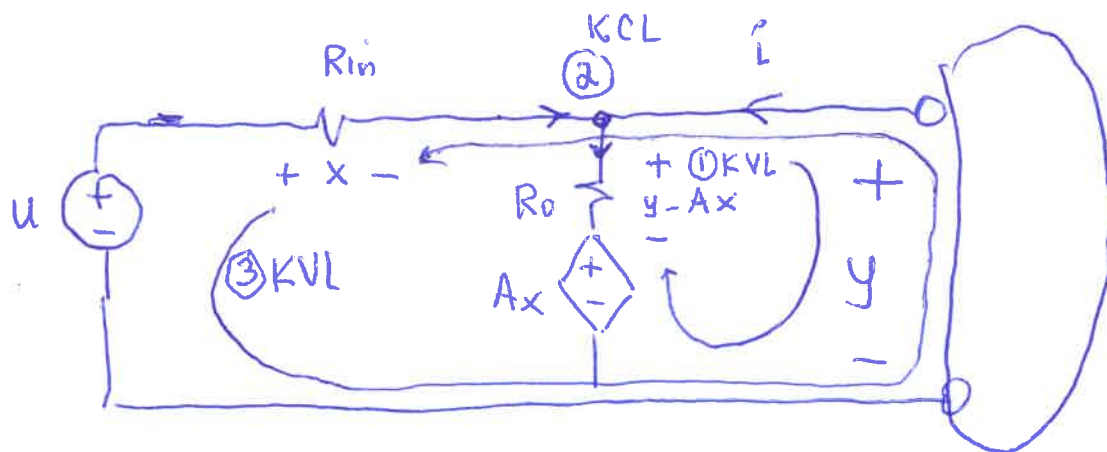
$$\lim_{\substack{R_{in} \rightarrow \infty \\ \text{or } A \rightarrow \infty}} H(R_{in}, R_o, A) = 1 \quad \leftarrow \quad \begin{array}{l} \text{As } R_{in} \text{ and/or } A \rightarrow \infty, \\ H \rightarrow 1 \text{ (the ideal buffer} \\ \text{I/O relation!)} \end{array}$$

Example 20

(Analysis of Buffer/Follower ...)

760

e Find a thevenin equivalent at y looking leftward



i.e. we wish to relate y to i :

$$y = \boxed{R_{th_{out}}} i + \boxed{V_{th_{out}}}$$

$$\textcircled{2} \text{ KCL (+ Ohm)} = \left(\frac{x}{R_{in}} \right) + i = \left(\frac{y - Ax}{R_o} \right)$$

$$\text{or } x \left[\frac{1}{R_{in}} + \frac{A}{R_o} \right] + i = \frac{y}{R_o}$$

$$\textcircled{3} \text{ KVL: } x = u - y \rightarrow [u - y] \left[\frac{1}{R_{in}} + \frac{A}{R_o} \right] + i = \frac{y}{R_o}$$

$$\text{algebra} \Rightarrow u \left[\frac{1}{R_{in}} + \frac{A}{R_o} \right] + i = y \left[\frac{1}{R_{in}} + \frac{A}{R_o} + \frac{1}{R_o} \right]$$

Example 20

(Analysis of Buffer/Follower...)

770

$$\overset{\times R_{in} R_o}{\Rightarrow} u [R_o + A R_{in}] + R_{in} R_o i^o = y [R_o + A R_{in} + R_{in}]$$

$$\Rightarrow y = \left[\frac{R_{in} R_o}{R_{in} + R_o + A R_{in}} \right] i^o + \left[\frac{R_o + A R_{in}}{R_{in} + R_o + A R_{in}} \right] u$$

$$\overset{\text{algebra}}{=} \left[\frac{R_{in} R_o}{R_{in}(1+A) + R_o} \right] i^o + "$$

$$= \left[\frac{R_{in} \left(\frac{R_o}{1+A} \right)}{R_{in} + \left(\frac{R_o}{1+A} \right)} \right] i^o + "$$

$$y = \left[R_{in} \parallel \frac{R_o}{1+A} \right] i^o + \left[\frac{r_f}{R_{in} + P_f} \right] u$$

Thevenin equivalent at output y looking leftward



$$R_{th\ out} = Z_{out} = R_{in} \parallel \frac{R_o}{1+A}$$

"output impedance (resistance)"

$V_{th\ out}$
= I/O relation obtained in [b] (see page 730)

Lets try to understand why $R_{th\ out}$ at output has this $R_{in} \parallel \frac{R_o}{1+A}$ form!

↓
Rth can be found by setting $u=0$ & finding R_{th} ---

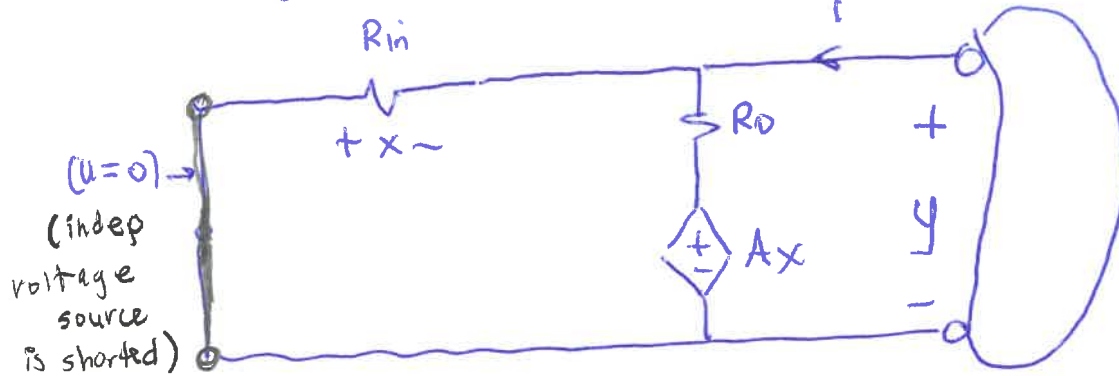
Note: \swarrow y open circuit
 $V_{th\ out} = y_{oc}$
 $\triangleq y |_{i^o=0}$
= I/O relation from [b] on page 730

Example 20

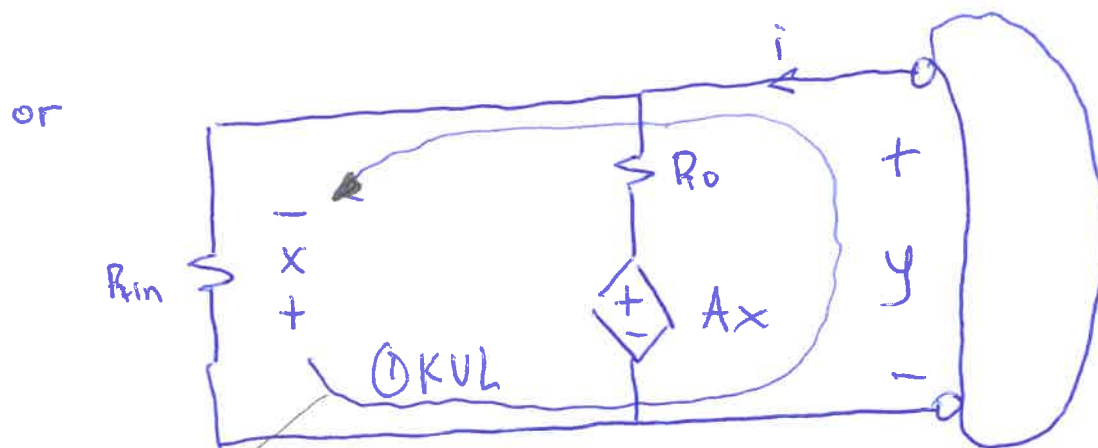
(Analysis of Buffer/Follower...)

780

Setting $u=0$, yields the following



Finding $R_{th_{out}}$ at y looking leftward (by 1st setting $u=0$)



From this we see that

$R_{th_{out}} = Z_{out} = R_{in}$ in parallel with some resistance r_o that we need to find (we expect $r_o = \frac{R_o}{1+A}$ from page 770 !!!)

① KVL =

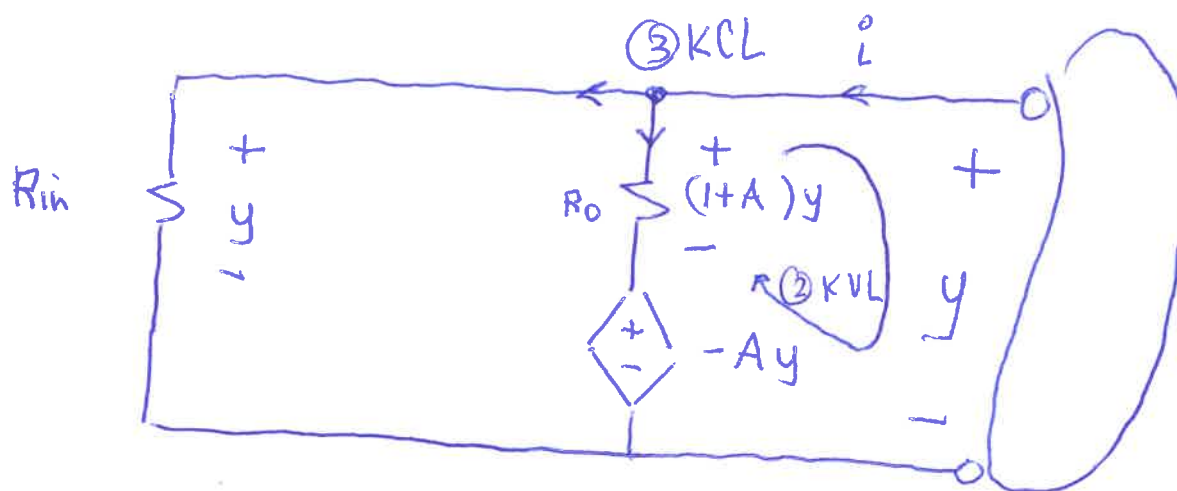
By KVL, we note that $x = -y$.

Applying this to the above circuit yields =

Example 20

(Analysis of Buffer/Follower...)

790



③ KCL : (1 ohm)

$$i = \frac{y}{R_{in}} + \frac{(1+A)y}{R_o}$$

$$= y \left[\frac{1}{R_{in}} + \frac{1}{\frac{R_o}{1+A}} \right]$$

$$= y \left[\frac{1}{R_{in} \parallel \frac{R_o}{1+A}} \right]$$

$$\Rightarrow y = (R_{in} \parallel \frac{R_o}{1+A}) i$$

$r_o = \frac{R_o}{1+A}$

Hence,

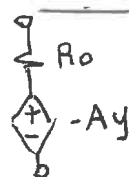
$$R_{in} = Z_{out} = (R_{in} \parallel r_o)$$

output

where

$$r_o = \frac{R_o}{1+A}$$

r_o has replaced

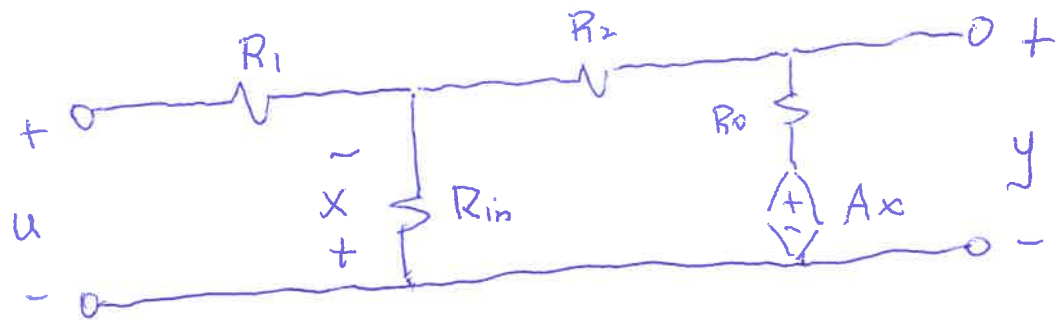


Problem 20

Analysis of Inverting & Non-Inverting Amplifiers with Standard Op-Amp Model

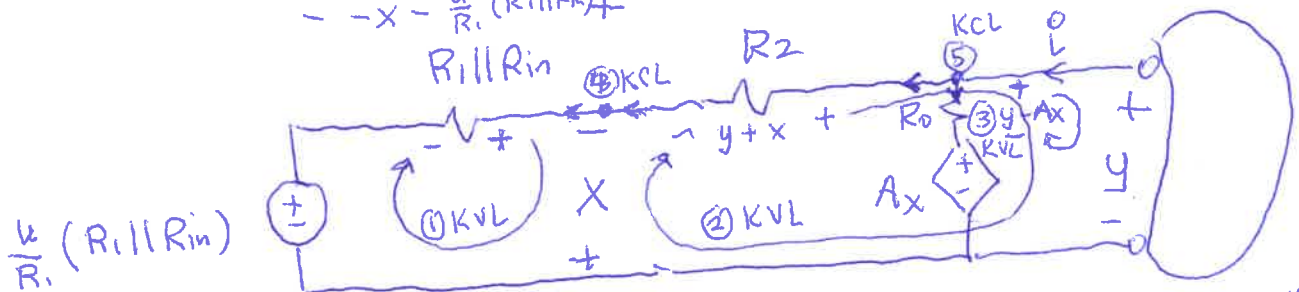
800

I Consider the following inverting amplifier circuit with a standard op-amp model:



a Find a Thevenin equivalent at output y looking leftward

Hint: Do 2 source transformations on u to get
 $-x = \frac{u}{R_1} (R_1 \parallel R_{in})$
 (v to i then i to v)

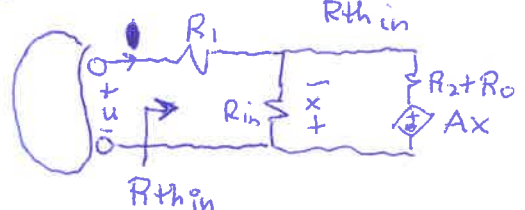


Hints: Use KCL & Ohm at (4) to get 1st eq
 " " " " " (5) " " 2nd eq
 Get rid of x to relate y to i:

$$y = \boxed{} i + \boxed{} V_{th}$$

b Find a thevenin equivalent at input u looking rightward

Hint: Consider



Problem 20

(... Inverting & Non-Inverting - ...)

810

From the previous circuit, we see that

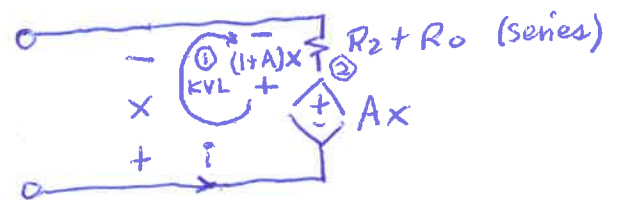
$$R_{th_{in}} = R_1 + R_{in} \parallel r_o \quad \text{where } r_o \text{ needs to be found}$$

Also $V_{th_{in}} = 0$ since there are no indep sources in our circuit!

How can you find r_o ?

$$\textcircled{2} \text{ Ohm: } (1+A)x = (R_2 + R_o)i$$

$$r_o = \frac{x}{i} = ?$$



c) How do your results in a) & b) change as

$$R_o \rightarrow 0$$

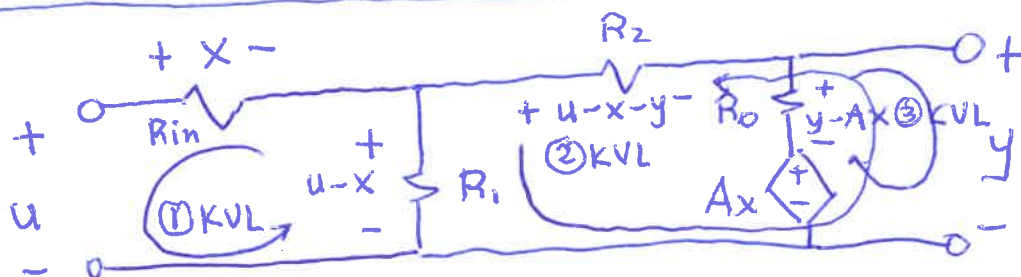
$$R_{in} \rightarrow \infty$$

$$A \rightarrow \infty$$

Individually & then collectively

II

Consider the following non-inverting amplifier circuit with a standard op-amp model =

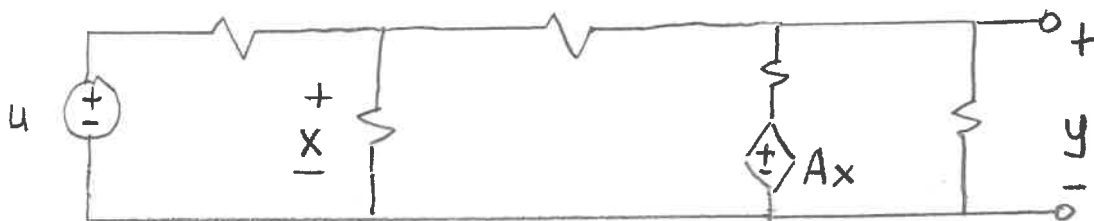


Repeat a, b, c for this circuit.

d
e
f

Problem 20 (Circuits with Dependent Sources) 820

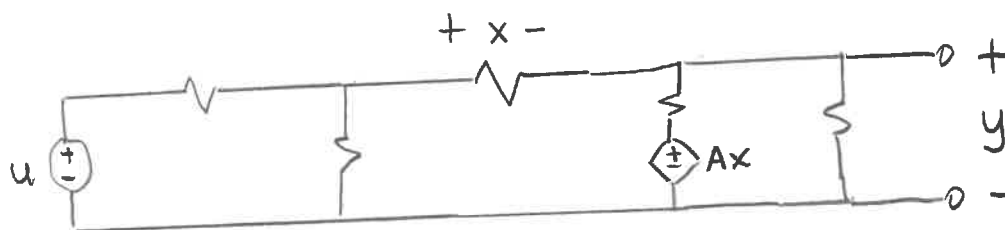
Consider the following circuit with all $R_i = 1$ ($A > 0$):



[a] Use KVL, KCL, Ohm to relate y to u ; (i.e. $y = Hu$)
Find H ...

[b] For what values of A is $H < 0$?

Now suppose we have the following circuit (All $R_i = 1$, $A > 0$):



[c], [d] Repeat [a], [b] for this circuit.

Happy
Circuiting!

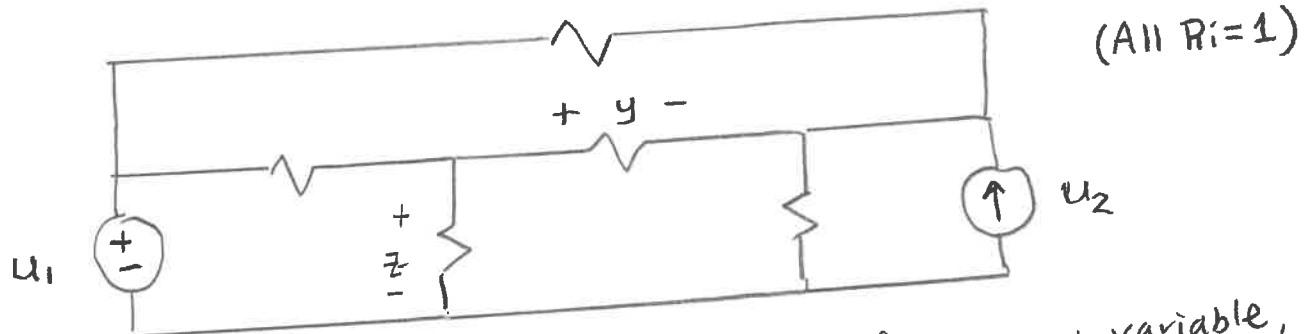


Example 21

(Need Another Variable)

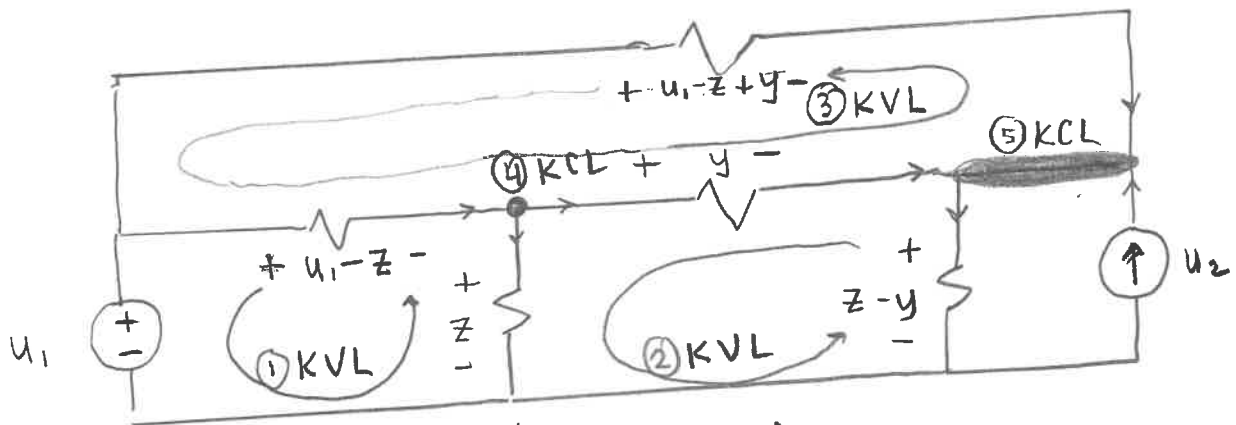
830

Consider the following circuit where the variable z has been introduced so that basic KVL, KCL, Ohm can be used to propagate y & z through the circuit =



Note: Without introducing a new variable, in addition to y , we cannot propagate y around !!!

Relate y to u_1, u_2



$$\textcircled{4} \text{ KCL} : \left(\frac{u_1 - z}{1} \right) = \left(\frac{z}{1} \right) + \left(\frac{y}{1} \right) \xrightarrow{\text{algebra}} u_1 = 2z + y$$

$$2z = u_1 - y$$

$$\left(\frac{u_1 - z}{1} \right) \rightarrow \left(\frac{y}{1} \right)$$

$$\left(\frac{y}{1} \right) + \left(\frac{u_1 - z + y}{1} \right) + u_2 = \left(\frac{z - y}{1} \right)$$

$$\textcircled{5} \text{ KCL} = \left(\frac{u_1 - z + y}{1} \right)$$

$$\Rightarrow 3y + u_1 + u_2 = 2z$$

$$2z = 3y + u_1 + u_2 = u_1 - y$$

$$\frac{y}{1} \rightarrow \left(\frac{z - y}{1} \right)$$

$$4y = -u_2$$

Why is y indep of u_1 ?

$$\Rightarrow y = -\left(\frac{1}{4} \right) u_2$$

Example 21

(Need Another Variable)

840

Lets compute all voltages in circuit:

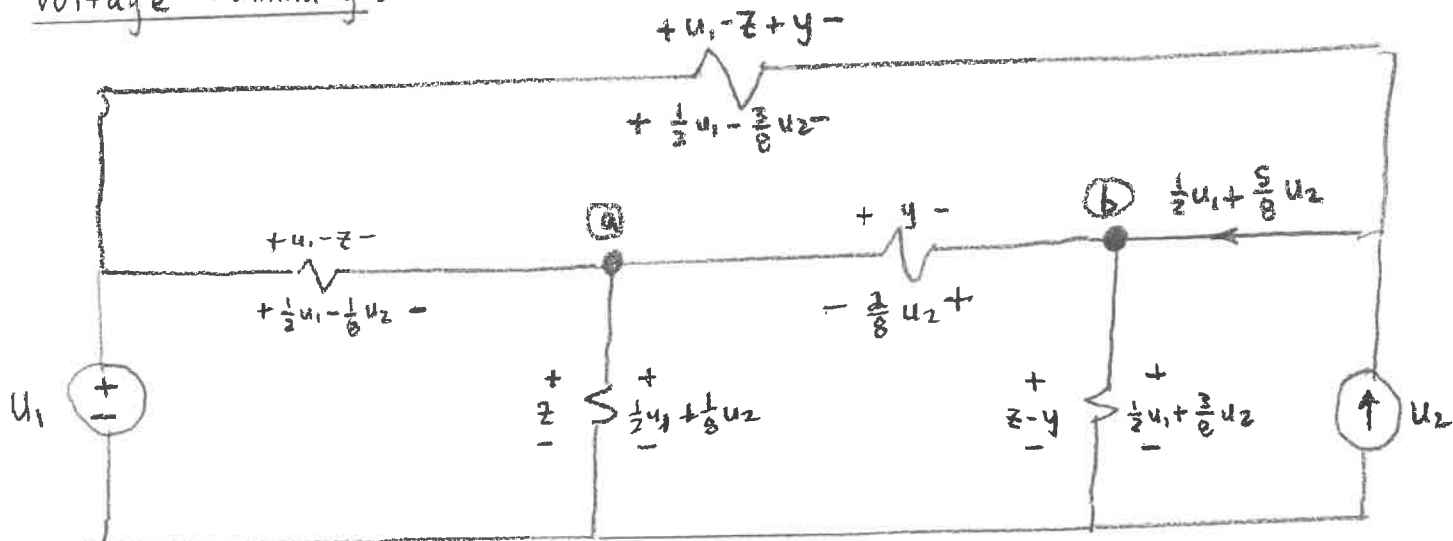
$$\Rightarrow z = \frac{1}{2}u_1 - \frac{1}{2}y = \frac{1}{2}u_1 + \frac{1}{8}u_2 \Rightarrow z = \frac{1}{2}u_1 + \frac{1}{8}u_2$$

$$u_1 - z = u_1 - \frac{1}{2}u_1 - \frac{1}{8}u_2 \Rightarrow u_1 - z = \frac{1}{2}u_1 - \frac{1}{8}u_2$$

$$z - y = \frac{1}{2}u_1 + \frac{1}{8}u_2 + \left(\frac{1}{4}\right)u_2 \Rightarrow z - y = \frac{1}{2}u_1 + \frac{3}{8}u_2$$

$$u_1 - z + y = \frac{1}{2}u_1 - \frac{1}{8}u_2 - \left(\frac{1}{4}\right)u_2 \Rightarrow u_1 - z + y = \frac{1}{2}u_1 - \frac{3}{8}u_2$$

Voltage Summary:



Note: The above shows that KVL is satisfied around each loop & KCL is satisfied at each node.

A simple KCL at nodes (a) & (b) shows why y is indep of u_1 !

- the $\frac{1}{2}u_1$ flowing rightward into (a) gets completely directed downward
- none of it reaches y!
- the $\frac{1}{2}u_1$ flowing leftward into (b) gets completely directed downward
- none of it reaches y!

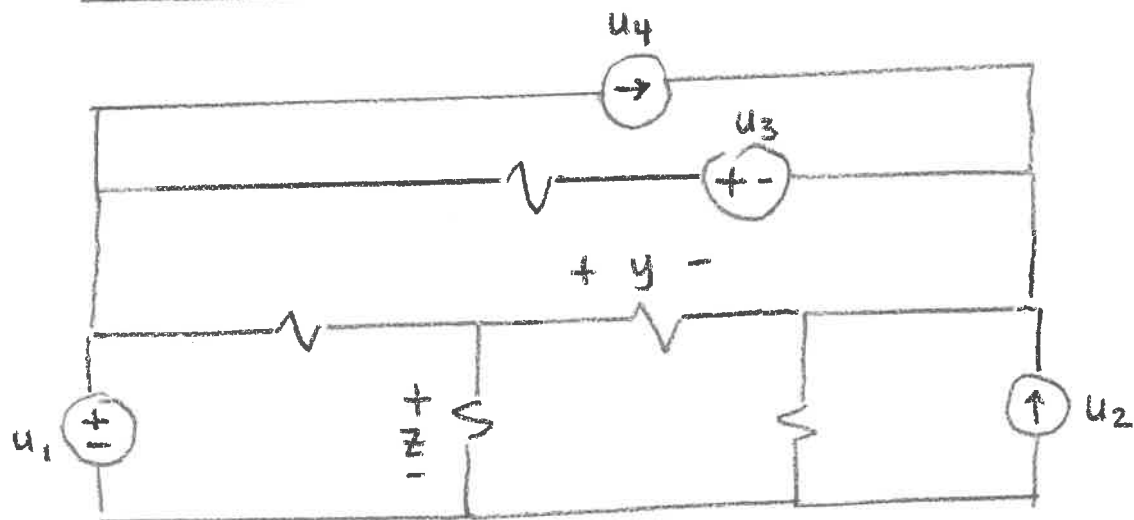
Note: Summaries like above can show us that KVL & KCL are in fact satisfied everywhere. They can also shed light on what is actually going on in the circuit.

Problem 21

(Need Another Variable)

850

Relate y to $u_1, 2, 3, 4$ (assume all $R_i = 1$)



Introduction to Impedance Concepts

Impedance generalizes the concept of resistance.

860

Impedance of a Resistor

$$V_R = R I_R$$

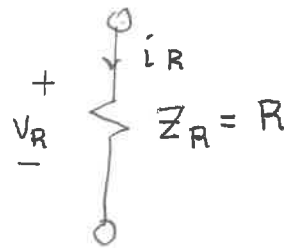
(time-domain representation)



$$V_R = R I_R$$

$$Z_R = \frac{V_R}{I_R} = R$$

(impedance or Laplace s-domain representation)



Note =

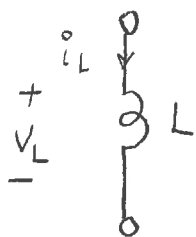
Capital letters are often used for voltages & currents when working in the "impedance domain".

(Laplace s-domain)

- We now introduce the impedance of an inductor & a capacitor.

- With such concepts, we will be able to treat inductors & capacitors (algebraically) just like they were resistors!

Impedance of an Inductor



$$V_L = L \frac{di_L}{dt}$$

(time-domain representation)

$$\frac{d}{dt} \longleftrightarrow s$$

$$V_L = L (s I_L) = (sL) I_L$$

we are simply replacing $\frac{d}{dt}$ with s !

$$Z_L = \frac{V_L}{I_L} = sL$$

(impedance or Laplace s-domain representation)

This is an s-domain equivalent (notational) representation for $V_L = L \frac{di_L}{dt}$

Note:

Capital letters are often used for voltages & currents when working in the "impedance domain";

(i.e. Laplace s-domain)

Note: 1) Z_L is "small" (near short; little "resistance" to current flow) when s is "small".

2) Z_L is "large" (nearly open; large "resistance" to current flow) when s is "large".

s should be thought of as representing a frequency.

3) Current i_L through an inductor cannot jump! (real)

Think of (angular) frequency ω_0 in a sinusoid =

$$A \sin(\omega_0 t + \theta)$$

More on this later!!!

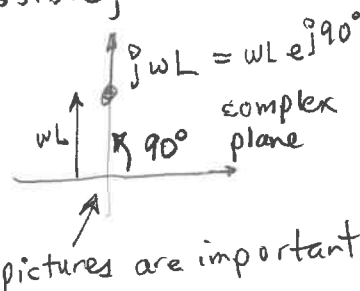
Why? Such a jump would result in an infinite (∞) voltage V_L .

This is NOT possible in the real world!

A "large" V_L is possible, but NOT ∞V_L !

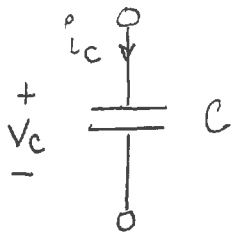
Note:

When $s = j\omega$, $Z_L = j\omega L = \underbrace{\omega L e^{j90^\circ}}_{\substack{\text{polar form} \\ |Z_L| = \omega L}} = |Z_L| e^{j\angle Z_L}$ $\angle Z_L = 90^\circ$



pictures are important!

Impedance of a Capacitor



$$i_c = C \frac{dv_c}{dt}$$

(time-domain representation)

$$I_c = C (s V_c) \\ = (sC) V_c$$

$$\frac{d}{dt} \longleftrightarrow s$$

We are simply replacing $\frac{d}{dt}$ with s !

$$Z_c = \frac{V_c}{I_c} = \frac{1}{sC}$$

Note:
Capital letters are often used for voltages & currents when working in the "impedance domain"; (i.e., Laplace s -domain).
(impedance or Laplace s -domain representation)

Note: 1) Z_c is large (nearly open; large "resistance" to current flow) when s is large.

2) Z_c is small (near short; small "resistance" to current flow) when s is small.

3) voltage v_c across a capacitor cannot jump! (real)

Think of (angular) frequency ω in a sinusoid =

$$A \sin(\omega t + \theta)$$

More on this later!!!

Notes: When $s = j\omega$,

rectangular form ωC $\nearrow 90^\circ$ polar form

$$j\omega C = \omega C e^{j90^\circ} \quad Z_c = \frac{1}{j\omega C} = \frac{1}{\omega C e^{j90^\circ}} = \frac{1}{\omega C} e^{-j90^\circ}$$

Why?

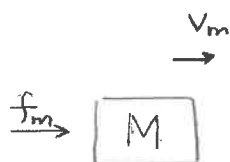
Such a jump would result in an infinite^(∞) current i_c .

This is NOT possible in the real world!

A "large" i_c is possible, but NOT ∞ i_c !

Impedance of a Mass

Newton's 2nd law for a mass



$$f_m = M \frac{dv_m}{dt}$$

(time-domain representation)

Note:

Just like

$$V_L = L \frac{di_L}{dt}$$

for an inductor!



$$F_m = M (s V_m)$$

$$= (sM) V_m$$

$$\frac{d}{dt} \longleftrightarrow s$$

we are simply relating

$\frac{d}{dt}$ with s !

like voltage

$$Z_M = \frac{F_m}{V_m} = sM$$

like current

(impedance or Laplace s-domain representation)

(like inductor sL !)

Note:

capital letters are often used for forces & velocities when working in the "impedance domain"; (i.e. Laplace s-domain).

Note:

- 1) Z_M is "small" (near short; little "resistance") to velocity flow when s is "small".
- 2) Z_M is "large" (nearly open; large "resistance") to velocity flow when s is "large".

s should be thought of as representing a "frequency".

- 3) velocity v_m of a ^(real) mass cannot jump!

Think of (angular) frequency ω in a sinusoid:

$$A \sin(\omega t + \theta)$$

More on this later!

Why? Such a jump would result in an infinite (∞) force f_m .

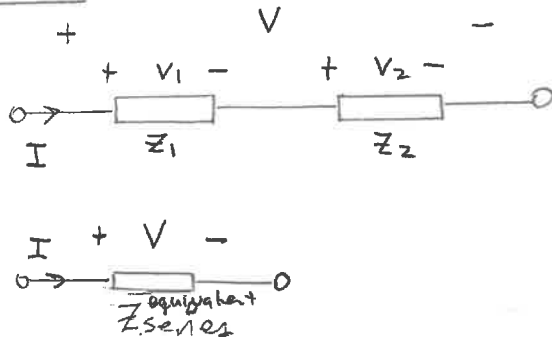
This is NOT possible in the real world!

A "large" f_m is possible, but NOT ∞ f_m !

Impedances = In Series & Parallel

900

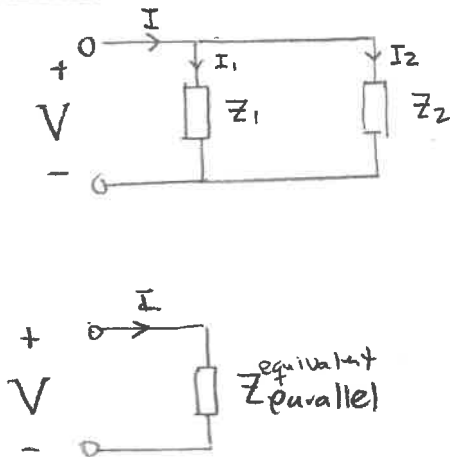
Series



$$\begin{aligned} V &= V_1 + V_2 & (\text{KVL}) \\ &= Z_1 I + Z_2 I & (\text{Ohm}) \\ &= (Z_1 + Z_2) I & (I \text{ pass through } Z_1, Z_2) \\ &= Z_{series}^{equivalent} I \end{aligned}$$

$$Z_{series}^{equivalent} = Z_1 + Z_2$$

Parallel



$$\begin{aligned} I &= I_1 + I_2 & (\text{KCL}) \\ &= \left(\frac{V}{Z_1} \right) + \left(\frac{V}{Z_2} \right) & (\text{Ohm}) \\ &= \left(\frac{1}{Z_1} + \frac{1}{Z_2} \right) V & (V \text{ is across } Z_1 \& Z_2) \\ &= \frac{1}{Z_{parallel}^{equivalent}} V \end{aligned}$$

$$V = Z_{parallel}^{equivalent} I$$

$$\begin{aligned} \frac{1}{Z_{parallel}^{equivalent}} &= \frac{1}{Z_1} + \frac{1}{Z_2} \\ &= \frac{Z_1 + Z_2}{Z_1 Z_2} \end{aligned}$$

$$\begin{aligned} Z_{parallel}^{equivalent} &= Z_1 \parallel Z_2 \\ &\triangleq \frac{Z_1 Z_2}{Z_1 + Z_2} \end{aligned}$$

1000

Impedance (s-) Domain Methodology

- 1) Replace all R, L, C s with their impedances

$$Z_R = R$$

$$Z_L = sL$$

$$Z_C = \frac{1}{sC}$$

- 2) Apply circuit laws (KVL, KCL, Ohm, etc...) treating all of the impedances (algebraically) as if they were "resistances" Z_i .

- 3) When all of the algebra is done (see examples that follow), you will be able to read off the system (circuit) differential equation!

--- This is a VERY VERY
BIG DEAL
FOLKS!

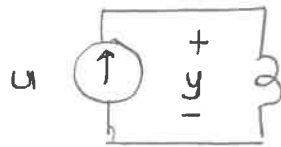
Example 22

Introduction to RLC Circuits Using Impedance Concepts

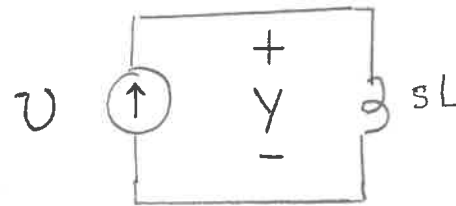
1010

A

Single Inductor



\Rightarrow



$$\stackrel{\text{ohm}}{\Rightarrow} Y = (sL) U$$

$$\Rightarrow H_{uy} = \frac{Y}{U} = Z_L = sL$$

is called the
"transfer function"
from u to y

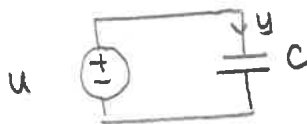
$$\begin{aligned} &\downarrow H_{uy} \\ Y &= (sL) U \\ &= L (sU) \end{aligned} \Rightarrow$$

$$y = L \frac{du}{dt}$$

Note: This diff eq
can be read
off from
Huy!

B

Single Capacitor



\Rightarrow



$\stackrel{\text{ohm}}{\Rightarrow}$

$$U = \left(\frac{1}{sC}\right) Y$$

\Rightarrow

$$Y = (sC) U$$

\Rightarrow

$$H_{uy} = \frac{Y}{U} = \frac{1}{Z_C} = sC$$

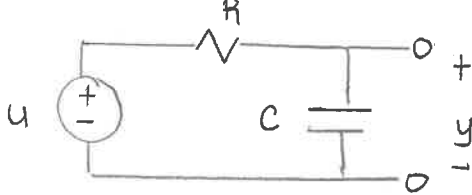
is called the
"transfer function"
from u to y.

$$\begin{aligned} &\downarrow H_{uy} \\ Y &= (sC) U = C (sU) \end{aligned} \Rightarrow y = C \frac{du}{dt}$$

Note: This diff eq
can be read
off from Huy!

Example 22

c - simple RC circuit

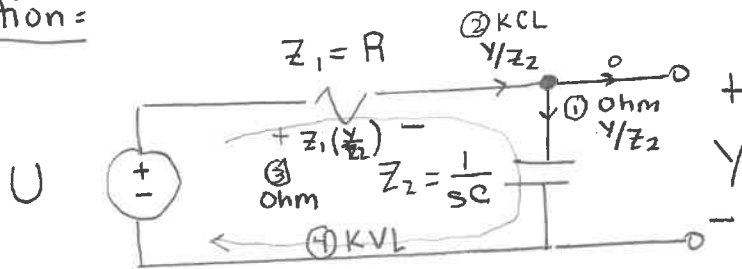


(Simple RC circuit)

3 New Questions:

- 1 Relate y to u (in the s-domain)
- 2 Find transfer function H_{uy} from u to y
- 3 Find differential equation relating u to y .

solution =



$$\begin{aligned}
 \textcircled{4} \text{ KVL} = \quad U &= Z_1 \left(\frac{Y}{Z_2} \right) + Y \\
 &= \left(\frac{Z_1}{Z_2} + 1 \right) Y \\
 &= \left(\frac{Z_1 + Z_2}{Z_2} \right) Y
 \end{aligned}$$

$$\begin{aligned}
 \Rightarrow Y &= \left(\frac{Z_2}{Z_1 + Z_2} \right) U \\
 &= \left(\frac{\frac{1}{sC}}{R + \frac{1}{sC}} \right) U
 \end{aligned}$$

$$= \left[\frac{\frac{1}{RC}}{s + \frac{1}{RC}} \right] U \quad \leftarrow \text{This is the desired relationship between } s \text{ and } U \text{ (in the s-domain)}$$

Note: I multiplied top & bottom by $\frac{s}{R}$ so that this leading coefficient in the denominator is 1!

$$\Rightarrow H_{uy} = \left[\frac{\frac{1}{RC}}{s + \frac{1}{RC}} \right] \text{ is the transfer function from } u \text{ to } y$$

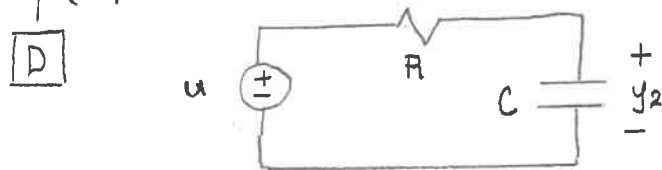
$$\text{Since } H_{uy} = \frac{Y}{U} \Rightarrow (s + \frac{1}{RC})Y = \frac{1}{RC}U \Rightarrow sY + \frac{1}{RC}Y = \frac{1}{RC}U$$

$$\Rightarrow \dot{y} + \frac{1}{RC}y = \frac{1}{RC}u \text{ is the diff eq relating } y \text{ to } u! \text{ (1st order diff eq!)}$$

Example 22

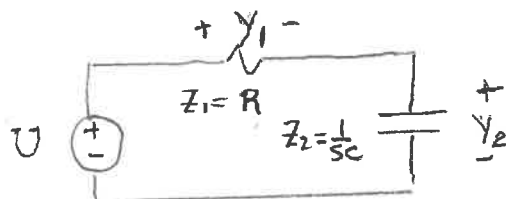
1030

(Simple RC circuit) y_1 -



1 energy storage element C
 \Rightarrow 1st order system

1 Relate $y_{1,2}$ to u in the s-domain



By voltage division:

$$\begin{aligned} y_1 &= \left(\frac{Z_1}{Z_1 + Z_2} \right) U \\ &= \left(\frac{R}{R + \frac{1}{sC}} \right) U \\ &= \left(\frac{s}{s + \frac{1}{RC}} \right) U \end{aligned}$$

$$\begin{aligned} y_2 &= \left(\frac{Z_2}{Z_1 + Z_2} \right) U \\ &= \left(\frac{\frac{1}{sC}}{R + \frac{1}{sC}} \right) U \\ &= \left(\frac{\frac{1}{RC}}{s + \frac{1}{RC}} \right) U \end{aligned}$$

2 Find transfer functions H_R & H_C (from u to y_1 & from u to y_2)

$$H_R = \frac{s}{s + \frac{1}{RC}}$$

$$H_C = \frac{\frac{1}{RC}}{s + \frac{1}{RC}}$$

Note: $H_R + H_C = \frac{y_1}{U} + \frac{y_2}{U} = \frac{y_1 + y_2}{U} = \frac{U}{U} = 1$ (by KVL)

3 Find the differential eqs that relate y_1 to u & y_2 to u

$$H_R = \frac{y_1}{U} = \frac{s}{s + \frac{1}{RC}}$$

$$H_C = \frac{y_2}{U} = \frac{\frac{1}{RC}}{s + \frac{1}{RC}}$$

$$(s + \frac{1}{RC}) y_1 = sU$$

$$s y_1 + \frac{1}{RC} y_1 = sU$$

$$(s + \frac{1}{RC}) y_2 = \frac{1}{RC} U$$

$$s y_2 + \frac{1}{RC} y_2 = \frac{1}{RC} U$$

$$\Rightarrow \ddot{y}_1 + \frac{1}{RC} y_1 = \dot{u}$$

$$\Rightarrow \ddot{y}_2 + \frac{1}{RC} y_2 = \frac{1}{RC} u$$

Note: These are 1st order diff eqs (Why? Because we have only 1 energy storage element C.)

Example 22

1040

[D] - (simple RC circuit)

[4] Determine the characteristic equation $\Phi(s)$ of the system.

↙ equals by definition

$\Phi(s) \triangleq$ denominator of any system transfer function

$$= s + \frac{1}{RC}$$

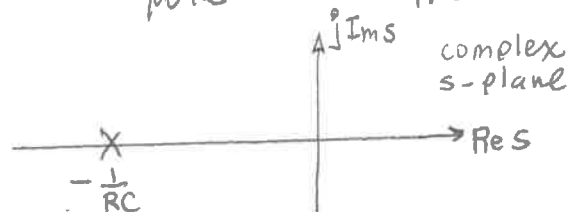
This is sometimes referred to as the characteristic polynomial of the system!

[5] Determine the poles (or characteristic roots) of the system.

The poles (or characteristic roots) of a system are found by finding the roots of the system's characteristic equation (polynomial): $\Phi(s) = 0$

$$\Phi(s) = s + \frac{1}{RC} = 0 \Rightarrow \text{system pole} = -\frac{1}{RC}$$

Note: Our system has only 1 pole because it only has 1 energy storage element (C)...
... it's a 1st order system!

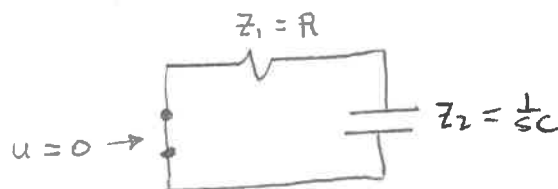


Here is another way to find the poles of the system.

Find the impedance (after setting all inputs to zero):

Note:

This was found without any KVL, KCL, or Ohm!



$$\begin{aligned} Z &= Z_1 + Z_2 \\ &= R + \frac{1}{sC} = \frac{RCs + 1}{sC} = R \left[\frac{s + \frac{1}{RC}}{s} \right] \end{aligned}$$

Now solve $Z = 0 \Rightarrow s = -\frac{1}{RC}$ (as obtained earlier!)

Example 22

1050

① - (simple RC circuit)

⑥ Is the system stable, marginally stable, or unstable?

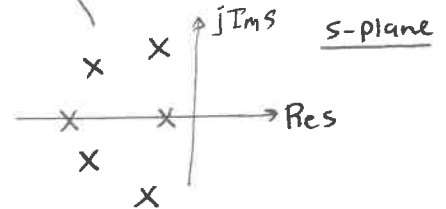
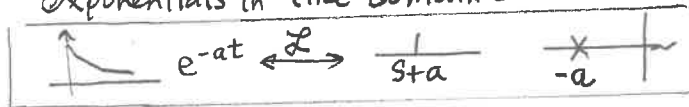
if and only if

System is stable \iff All system poles lie in open left half plane ($\text{Re pole} < 0$)

Remember !!

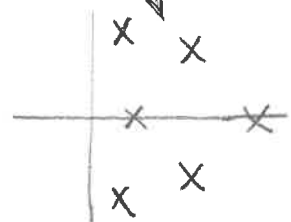
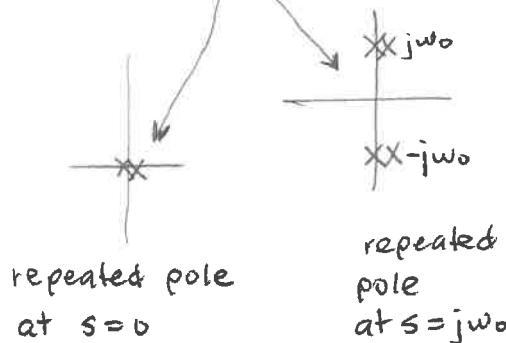
Reason =

(we'll see that) \rightarrow Such poles are associated with decaying exponentials in time domain !!!

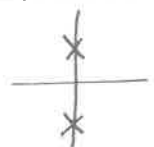
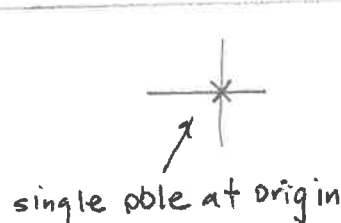


Note: These are "Laplace Transform pairs!" (will learn later!!!)

System is unstable \iff ① One or more system poles lie in open right half plane ($\text{Re pole} > 0$) and/or ② system has repeated poles on the imaginary axis



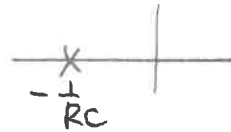
System is marginally stable \iff All system poles lie in open left half plane ($\text{Re} s < 0$) except for single (non-repeated) poles on the imaginary axis



Example 22

1060

D (simple RC circuit)

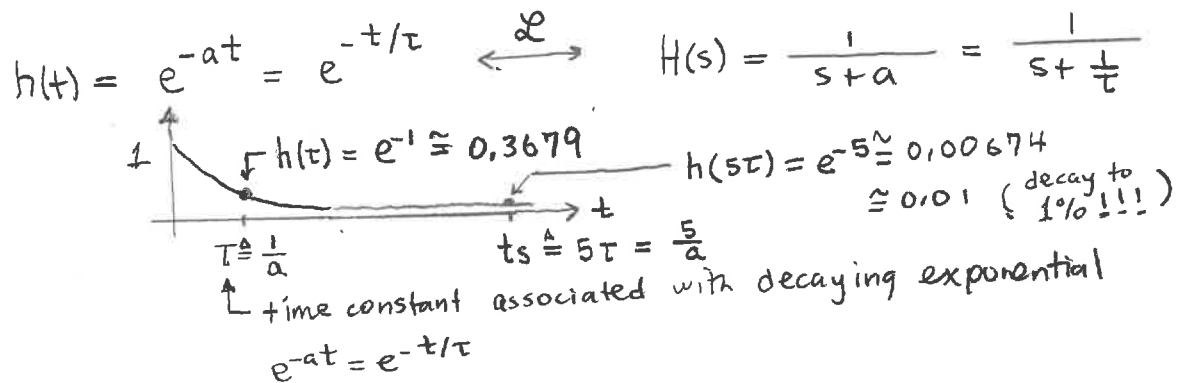


For our system, pole = $-\frac{1}{RC} < 0$

\Rightarrow System is stable

7 What is the associated (1% or 5 time constant) settling time?

The following are associated with one another (they are Laplace transform pairs) =



For our system, $a = \frac{1}{RC} = \frac{1}{\tau}$

$$\Rightarrow \tau = RC$$

$$\Rightarrow t_s \triangleq 5\tau = \frac{5}{a} = 5RC$$

Note:

When we have complex poles $-\sigma_0 \pm j\omega_0$ the associated 1% or 5 time constant settling time

$$t_s = \frac{5}{|\text{Re poles}|} = \frac{5}{|\text{Re}(-\sigma_0 \pm j\omega_0)|} = \frac{5}{|-\sigma_0|} = \frac{5}{\sigma_0}$$

Example 22

1070

D (Simple RC circuit)

8. Consider a stable system H .

Suppose $u(t) = A + B \sin(\omega t + \theta)$.

Determine $y_{ss} = \lim_{t \rightarrow \infty} y(t)$.

i.e. steady state output = output after a sufficiently long time so that the transients have run their course;

i.e. decaying exponentials
have effectively reached
zero - - -

∴ $t \geq t_s$!
 ↑
 system settling time

Answer =

For a stable system H ,

if
$$u(t) = A + B \sin(\omega_0 t + \theta)$$

the n

$$y_{ss} = A H(0) + \frac{B |H(j\omega_0)|}{\cos} \sin(\omega_0 t + \theta + \angle H(j\omega_0))$$

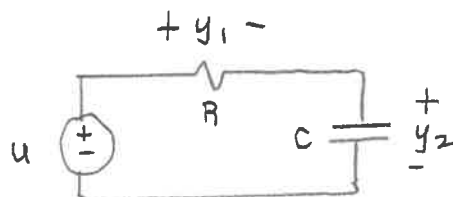
Remember!
(FOR EVER!)

This result shall be referred to as the Method of the Transfer Function (MOTF).

Example 22

1080

D - (simple RC circuit)
For our system



we have

$$H_1 = H_R = \frac{y_1}{u} = \frac{s}{s + \frac{1}{RC}} \quad H_2 = H_C = \frac{y_2}{u} = \frac{\frac{1}{RC}}{s + \frac{1}{RC}}$$

These transfer functions are stable with poles at $s = -\frac{1}{RC}$

$$\tau = t_s = 5\tau = 5RC$$

Using the MOTF, we have the following:

$$\text{if } u(t) = A + B \sin(\omega_0 t + \theta) \cos$$

then

$$y_{1ss} = A H_1(0) + B |H_1(j\omega_0)| \sin(\omega_0 t + \theta + \underbrace{|H_1(j\omega_0)|}_{\cos})$$

$$y_{2ss} = A H_2(0) + B |H_2(j\omega_0)| \sin(\omega_0 t + \theta + \underbrace{|H_2(j\omega_0)|}_{\cos})$$

\uparrow dc gains of $H_{1,2}$ \uparrow Magnitude Response of $H_{1,2}$ \uparrow Phase Response of $H_{1,2}$

Make sure that you write this on an exam.

Note:

You can write this before computing H_1 & H_2 !



Example 22

1090

D - (simple RC circuit)

For our system

$$H_1 = \frac{s}{s + \frac{1}{RC}}$$

$$H_2 = \frac{\frac{1}{RC}}{s + \frac{1}{RC}}$$

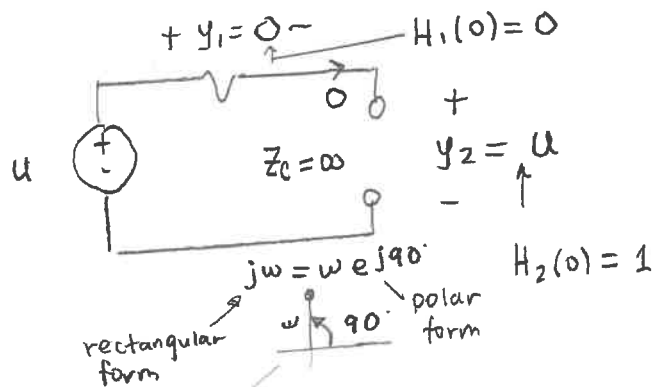
Hence, we have dc gains =

$$H_1(0) = 0$$

$$H_2(0) = 1$$

Why? At dc ($s=0$), $Z_C = \frac{1}{sC} \Big|_{s=0} = \infty$ (cap is open! no current flows)

∴ our circuit looks like =



rectangular form \downarrow polar form \downarrow

$$\frac{1}{RC} = \frac{1}{RC} e^{j0^\circ}$$

We also have

$$H_1(j\omega) = \frac{j\omega}{j\omega + \frac{1}{RC}}$$

magnitude of bottom = $\sqrt{(\frac{1}{RC})^2 + \omega^2}$

angle of bottom = $\tan^{-1}(\frac{\omega}{\frac{1}{RC}})$

$$H_2(j\omega) = \frac{\frac{1}{RC}}{j\omega + \frac{1}{RC}}$$

rectangular form \uparrow polar form \uparrow

$$\frac{1}{RC} + j\omega = \sqrt{(\frac{1}{RC})^2 + \omega^2} e^{j\tan^{-1}(\frac{\omega}{\frac{1}{RC}})}$$

$$|H_1(j\omega)| = \frac{\text{mag of top}}{\text{mag of bottom}} = \frac{\omega}{\sqrt{(\frac{1}{RC})^2 + \omega^2}}$$

$$|H_2(j\omega)| = \frac{\text{mag of top}}{\text{mag of bottom}} = \frac{\frac{1}{RC}}{\sqrt{(\frac{1}{RC})^2 + \omega^2}}$$

$$\angle H_1(j\omega) = \angle \text{top} - \angle \text{bottom} = 90^\circ - \tan^{-1}(\frac{\omega}{\frac{1}{RC}})$$

$$\angle H_2(j\omega) = \angle \text{top} - \angle \text{bottom} = 0 - \tan^{-1}(\frac{\omega}{\frac{1}{RC}}) = -\tan^{-1}(\frac{\omega}{\frac{1}{RC}})$$

SUMMARY

magnitude \downarrow angle \downarrow

$$j\omega = \omega e^{j90^\circ}$$

$$\frac{1}{RC} = \frac{1}{RC} e^{j0^\circ}$$

angle = 0

magnitude = $\frac{1}{RC}$

$$\frac{1}{RC} + j\omega = \sqrt{(\frac{1}{RC})^2 + \omega^2} e^{j\tan^{-1}(\frac{\omega}{\frac{1}{RC}})}$$

magnitude = $\sqrt{(\frac{1}{RC})^2 + \omega^2}$

Angle = $\tan^{-1}(\frac{\omega}{\frac{1}{RC}})$

Example 22

1100

— (Simple RC circuit)

D For our system

$$H_1 = \frac{s}{s + \frac{1}{RC}}$$

$$H_2 = \frac{\frac{1}{RC}}{s + \frac{1}{RC}}$$

$$H_1(j\omega) = \frac{j\omega}{j\omega + \frac{1}{RC}}$$

$$H_2(j\omega) = \frac{\frac{1}{RC}}{j\omega + \frac{1}{RC}}$$

Magnitude &
Phase Response
for H_1

$$|H_1(j\omega)| = \frac{\omega}{\sqrt{(\frac{1}{RC})^2 + \omega^2}}$$

$$|H_2(j\omega)| = \frac{\frac{1}{RC}}{\sqrt{(\frac{1}{RC})^2 + \omega^2}}$$

Magnitude &
Phase Response
for H_2

$$\angle H_1(j\omega) = 90^\circ - \tan^{-1}\left(\frac{\omega}{\frac{1}{RC}}\right)$$

$$\angle H_2(j\omega) = -\tan^{-1}\left(\frac{\omega}{\frac{1}{RC}}\right)$$

If $u(t) = A + B \begin{matrix} \sin \\ \cos \end{matrix} (\omega_0 t + \theta)$
↑ sin or cos

by the MTF

$$\begin{aligned} y_{1ss} &= H_1(0)A + B |H_1(j\omega_0)| \begin{matrix} \sin \\ \cos \end{matrix} (\omega_0 t + \theta + \angle H_1(j\omega_0)) \\ &= (0)A + B \frac{\omega_0}{\sqrt{\omega_0^2 + (\frac{1}{RC})^2}} \begin{matrix} \sin \\ \cos \end{matrix} (\omega_0 t + \theta + 90^\circ - \tan^{-1}\left(\frac{\omega_0}{\frac{1}{RC}}\right)) \end{aligned}$$

$$\begin{aligned} y_{2ss} &= H_2(0)A + B |H_2(j\omega_0)| \begin{matrix} \sin \\ \cos \end{matrix} (\omega_0 t + \theta + \angle H_2(j\omega_0)) \\ &= (1)A + B \frac{\frac{1}{RC}}{\sqrt{\omega_0^2 + (\frac{1}{RC})^2}} \begin{matrix} \sin \\ \cos \end{matrix} (\omega_0 t + \theta - \tan^{-1}\left(\frac{\omega_0}{\frac{1}{RC}}\right)) \end{aligned}$$

Note: On an exam, it is not necessary to make the above substitutions --- computing the essential quantities suffices!

Example 22

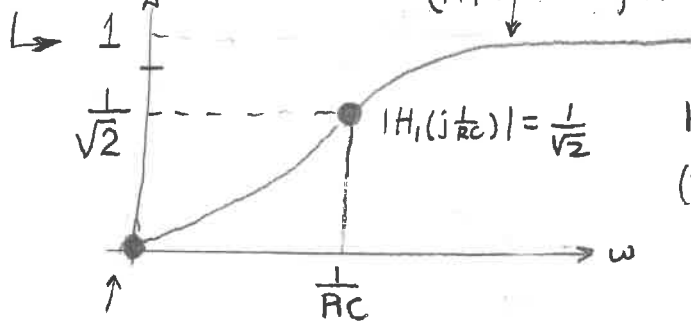
1110

□ (simple RC circuit)

It is useful, & highly instructive, to plot $\left\{ \frac{|H_1(j\omega)|, |H_2(j\omega)|}{|H_1(j\omega)|, |H_2(j\omega)|} \right\}$ vs ω !!!!

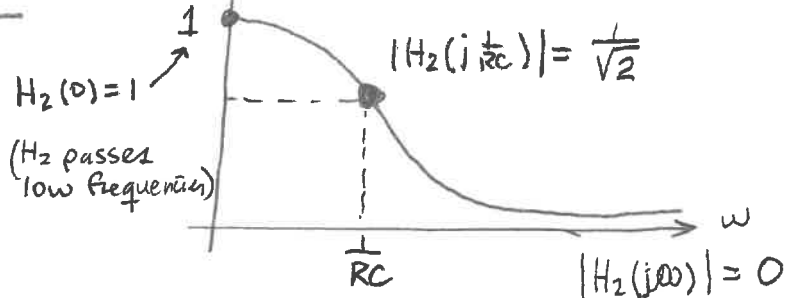
$$|H_1(j\omega)| = \frac{\omega}{\sqrt{\omega^2 + (\frac{1}{RC})^2}}$$

$$|H_1(j\infty)| = 1$$



(H_1 attenuates low frequencies)

$$|H_2(j\omega)| = \frac{\frac{1}{RC}}{\sqrt{\omega^2 + (\frac{1}{RC})^2}}$$



(H_2 attenuates high frequencies)

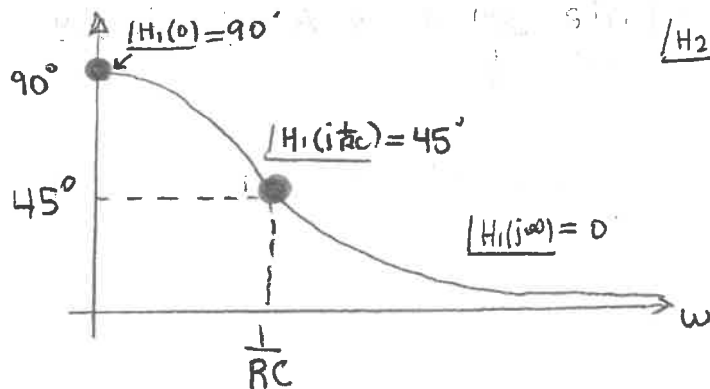
Because of the above magnitude response shapes =

H_1 is called a High Pass Filter (HPF)

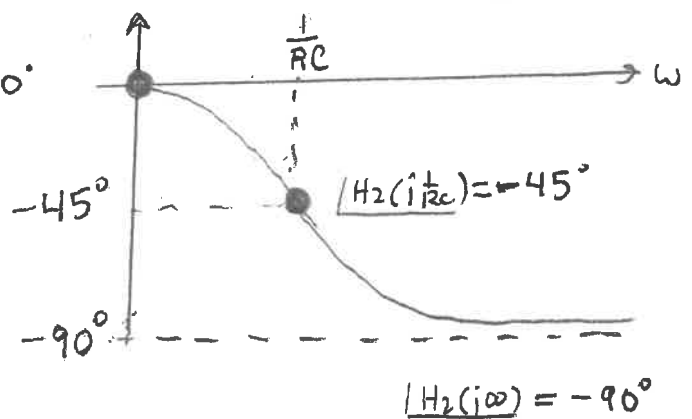
H_2 is called a Low Pass Filter (LPF)

We also have

$$\angle H_1(j\omega) = 90^\circ - \tan^{-1}\left(\frac{\omega}{\frac{1}{RC}}\right)$$



$$\angle H_2(j\omega) = -\tan^{-1}\left(\frac{\omega}{\frac{1}{RC}}\right)$$



④

Example 22

1120

(Simple RC circuit)

The following is a 3 frequency summary for

$$u(t) = A + B \frac{\sin(\omega_0 t + \theta)}{\cos}$$

$$H_2 \approx 1$$

ω_0 small

($\omega_0 \ll \frac{1}{RC}$)

$$H_1 \approx \frac{s}{\frac{1}{RC}}$$

$$y_{1ss} \approx (0)A + B \left(\frac{\omega_0}{\frac{1}{RC}} \right) \frac{\sin(\omega_0 t + \theta + 90^\circ - \tan^{-1}(\frac{\omega_0}{\frac{1}{RC}}))}{\cos}$$

$$y_{2ss} \approx (1)A + B (1) \frac{\sin(\omega_0 t + \theta - \tan^{-1}(\frac{\omega_0}{\frac{1}{RC}}))}{\cos}$$

$\omega_0 = \frac{1}{RC}$

$$y_{1ss} \approx (0)A + B \frac{1}{\sqrt{2}} \frac{\sin(\omega_0 t + \theta + 90^\circ - \tan^{-1}(1))}{\cos}$$

$$y_{2ss} \approx (1)A + B \frac{1}{\sqrt{2}} \frac{\sin(\omega_0 t + \theta - \tan^{-1}(1))}{\cos}$$

ω_0 large

($\omega_0 \gg \frac{1}{RC}$)

$$H_1 \approx 1e^{j0^\circ}$$

$$H_2 \approx \frac{1}{s}$$

$$y_{1ss} \approx (0)A + B (1) \frac{\sin(\omega_0 t + \theta + 0^\circ)}{\cos}$$

$$y_{2ss} \approx (1)A + B \frac{\frac{1}{RC}}{\omega_0} \frac{\sin(\omega_0 t + \theta - 90^\circ)}{\cos}$$

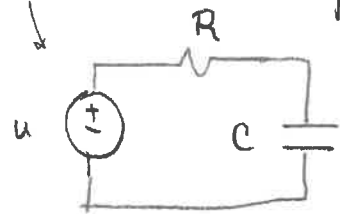
Example 22

(Simple RC circuit)

1130

(Simple RC circuit)

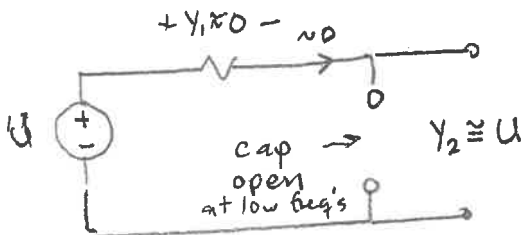
Here is how our circuit



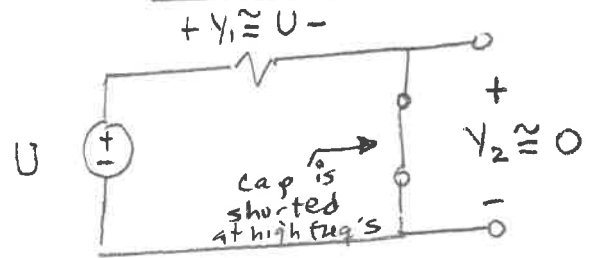
looks for a sinusoidal input:

$$u(t) = B \sin(\omega_0 t + \theta)$$

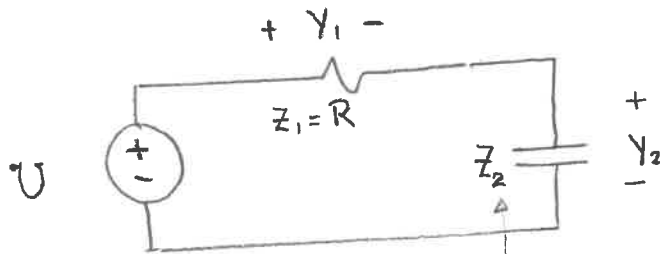
$\omega_0 \approx 0$ (Cap ~ open)



$\omega_0 \approx \infty$ (Cap ~ shorted)



$$\omega_0 = \frac{1}{RC}$$



$$y_1 = \left(\frac{Z_1}{Z_1 + Z_2} \right) U = \left(\frac{R}{R - jR} \right) U = \left(\frac{1}{1 - j} \right) U$$

$$= \frac{1}{\sqrt{2} e^{-j45^\circ}} U = \frac{1}{\sqrt{2}} e^{j45^\circ} U$$

$$y_2 = \left(\frac{Z_2}{Z_1 + Z_2} \right) U = \left(\frac{-jR}{R - jR} \right) U = \left(\frac{-j}{1 - j} \right) U = \frac{1 e^{-j90^\circ}}{\sqrt{2} e^{-j45^\circ}} U = \frac{1}{\sqrt{2}} e^{-j45^\circ} U$$

$$Z_2 = \frac{1}{j\omega_0 C} = \frac{1}{j(\frac{1}{RC})} = \left[\frac{1}{j(\frac{1}{R})} \right] \left[\frac{x(-j)}{x(-j)} \right]$$

$$= \left(-\frac{R}{j} \right) \left(\frac{-j}{-j} \right)$$

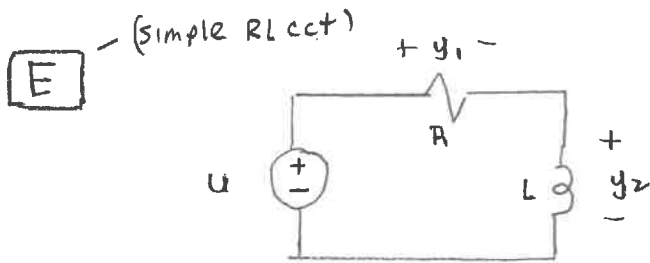
$$= \frac{-jR}{-(-j)(j)}$$

$$= \frac{-jR}{-(-1)}$$

$$= -jR$$

Example 22

1140



(Simple RL Circuit)

1 Relate $y_{1,2}$ to u (in s -domain)

$$y_1 = \left(\frac{z_1}{z_1 + z_2} \right) U = \left(\frac{-R}{R + sL} \right) U = \left[\frac{-\frac{R}{L}}{s + \frac{R}{L}} \right] U$$

$$y_2 = \left(\frac{z_2}{z_1 + z_2} \right) U = \left(\frac{sL}{R + sL} \right) U = \left[\frac{s}{s + \frac{R}{L}} \right] U$$

2 Find transfer functions $H_{1,2}$ from u to $y_{1,2}$.

$$H_1 = \frac{\frac{R}{L}}{s + \frac{R}{L}}$$

$$H_2 = \frac{s}{s + \frac{R}{L}}$$

3 Find diff eqs relating $y_{1,2}$ to u

$$\dot{y}_1 + \frac{R}{L} y_1 = \left(\frac{R}{L} \right) u$$

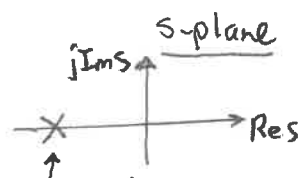
$$\dot{y}_2 + \frac{R}{L} y_2 = u$$

4 Find characteristic eq (polynomial) of system.

$$\Phi(s) = \text{denominator of } H_1 \text{ or } H_2 = s + \frac{R}{L}$$

5 Determine pole (characteristic root) of system.

$$\text{Solve } \Phi(s) = 0 \Rightarrow \Phi(s) = s + \frac{R}{L} = 0 \Rightarrow s = -\frac{R}{L}$$



6 Determine 1% (or 5 time constant) settling time t_s of system

$$t_s = 5\tau = \frac{5}{|\text{Re pole}|} = \frac{5}{|-\frac{R}{L}|} = 5 \frac{L}{R}$$

7 Is system stable, marginally stable, or unstable?

System is stable iff all poles lie in open LHP (Re pole < 0)

\Rightarrow Our system has pole at $s = -\frac{R}{L}$ (in LHP)
 \Rightarrow stable

Example 22

simple RL circuit

for (simple RL circuit)

1150

[E] [8] Find $y_{i,ss}$ when $u = A + B \sin(\omega t + \theta)$
cos

MOTF

\Rightarrow

$$y_{i,ss} = H_i(0) A + B |H_i(j\omega)| \sin(\omega t + \theta + \angle H_i(j\omega))$$

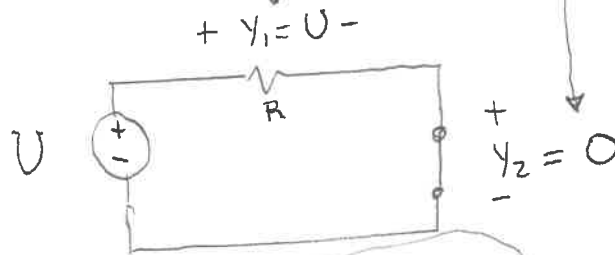
cos

Since $H_1(s) = \frac{\frac{R}{L}}{s + \frac{R}{L}}$ $\quad \quad \quad H_2(s) = \frac{s}{s + \frac{R}{L}}$

$$H_1(0) = 1$$

$$H_2(0) = 0$$

(since inductor looks like a short at dc & all the voltage U appears across R !)



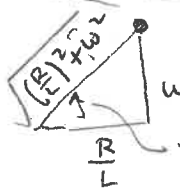
$$\frac{R}{L} = \frac{R}{L} e^{j0^\circ}$$

$$H_1(j\omega) = \frac{\frac{R}{L}}{j\omega + \frac{R}{L}}$$

$$H_2(j\omega) = \frac{j\omega}{j\omega + \frac{R}{L}}$$

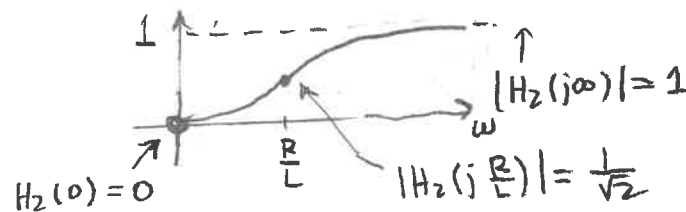
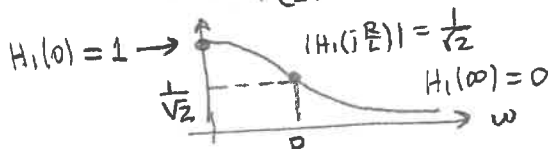
$$j\omega = \omega e^{j90^\circ}$$

$$\frac{R}{L} + j\omega = \sqrt{\left(\frac{R}{L}\right)^2 + \omega^2} e^{j \tan^{-1}\left(\frac{\omega}{\frac{R}{L}}\right)}$$



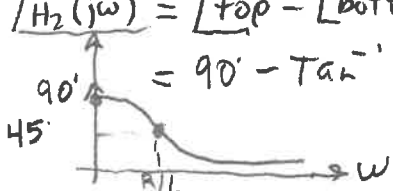
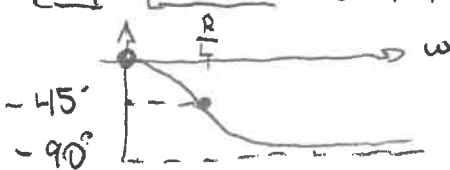
$$|H_1(j\omega)| = \frac{|top|}{|bottom|} = \frac{\frac{R}{L}}{\sqrt{\left(\frac{R}{L}\right)^2 + \omega^2}}$$

$$|H_2(j\omega)| = \frac{|top|}{|bottom|} = \frac{\omega}{\sqrt{\left(\frac{R}{L}\right)^2 + \omega^2}}$$



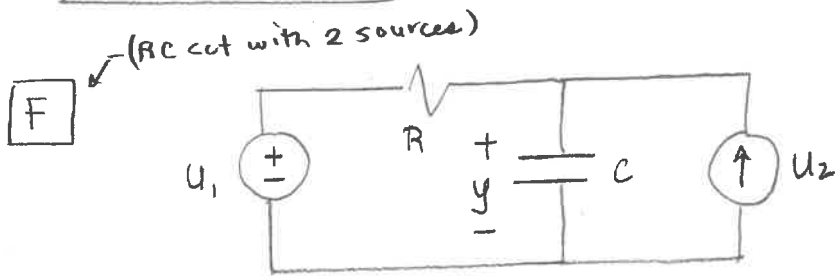
$$\angle H_1(j\omega) = \angle top - \angle bottom = 0^\circ - \tan^{-1}\left(\frac{\omega}{\frac{R}{L}}\right)$$

$$\angle H_2(j\omega) = \angle top - \angle bottom = 90^\circ - \tan^{-1}\left(\frac{\omega}{\frac{R}{L}}\right)$$

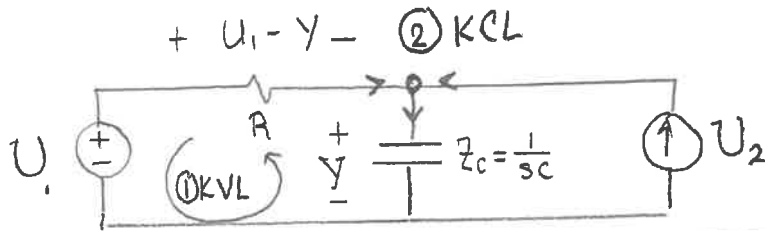


Example 22

1160



1 Relate y to $u_{1,2}$ (in s-domain)



② KCL (+Ohm) =

$$\left(\frac{u_1 - y}{R} \right) + (u_2) = \left(\frac{y}{Z_c} \right) = sC y$$

algebra $\Rightarrow Y \left[sC + \frac{1}{R} \right] = \left[\frac{1}{R} \right] u_1 + [1] u_2$

$\Rightarrow Y \left[s + \frac{1}{RC} \right] = \left[\frac{1}{RC} \right] u_1 + \left[\frac{1}{C} \right] u_2$

$\Rightarrow Y = \left[\frac{\frac{1}{RC}}{s + \frac{1}{RC}} \right] u_1 + \left[\frac{\frac{1}{C}}{s + \frac{1}{RC}} \right] u_2$

2 Find transfer functions $H_{1,2}$ from u to y .

$$H_1 = \frac{Y}{u_1} = \frac{\frac{1}{RC}}{s + \frac{1}{RC}}$$

$$H_2 = \frac{Y}{u_2} = \frac{\frac{1}{C}}{s + \frac{1}{RC}}$$

3 Find diff eq relating y to $u_{1,2}$. $\dot{y} + \frac{1}{RC} y = \frac{1}{RC} u_1 + \frac{1}{C} u_2$

4 Characterist eq (poly) = $\Phi(s) = \text{denominator of } H_1 \text{ or } H_2$
 $= s + \frac{1}{RC}$

5 Poles (Characteristic roots) = $\Phi(s) = s + \frac{1}{RC} = 0 \Rightarrow s = -\frac{1}{RC}$

6 Stability = All poles lie in LHP \Rightarrow System is stable

7 t_s : $t_s = \frac{5}{|Re \text{ pole}|} = \frac{5}{|Re(-\frac{1}{RC})|} = 5RC$

Example 22

1170

[F] — RC ckt with 2 sources

[B] Find y_{ss} when $U_1 = A_1 + B_1 \sin(\omega_1 t + \theta_1)$ & $U_2(t) = A_2 + B_2 \sin(\omega_2 t + \theta_2)$

MOTF

\Rightarrow

$$y_{ss} = y_{1ss} + y_{2ss}$$

$$y_{1ss} = H_1(0) A_1 + B_1 |H_1(j\omega_1)| \sin(\omega_1 t + \theta_1 + \angle H_1(j\omega_1))$$

$$H_1(s) = \frac{\frac{1}{RC}}{s + \frac{1}{RC}} \quad H_1(0) = 1$$

$$H_1(j\omega_1) = \frac{\frac{1}{RC}}{j\omega_1 + \frac{1}{RC}} \Rightarrow$$

$$|H_1(j\omega_1)| = \frac{\frac{1}{RC}}{\sqrt{\omega_1^2 + (\frac{1}{RC})^2}}$$

$$\angle H_1(j\omega_1) = -\tan^{-1}\left(\frac{\omega_1}{\frac{1}{RC}}\right)$$

$$H_2(s) = \frac{\frac{1}{C}}{s + \frac{1}{RC}}$$

$$H_2(0) = R$$

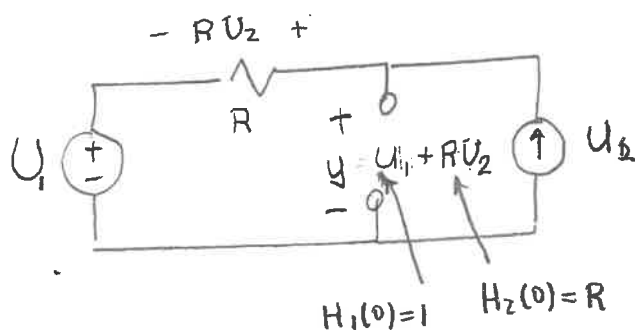
$$H_2(j\omega_2) = \frac{\frac{1}{C}}{j\omega_2 + \frac{1}{RC}} \Rightarrow$$

$$|H_2(j\omega_2)| = \frac{\frac{1}{C}}{\sqrt{\omega_2^2 + (\frac{1}{RC})^2}}$$

$$\angle H_2(j\omega_2) = -\tan^{-1}\left(\frac{\omega_2}{\frac{1}{RC}}\right)$$

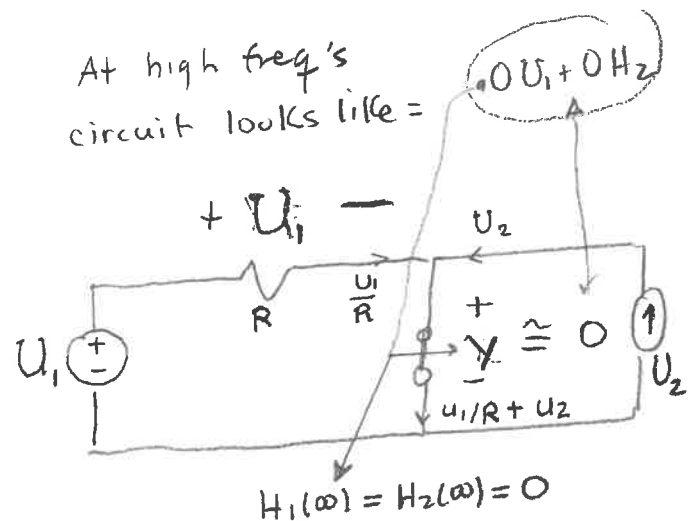
Note =

At dc (low freq)
circuit looks like =



(cap looks like an open ckt
at low freq's > dc)

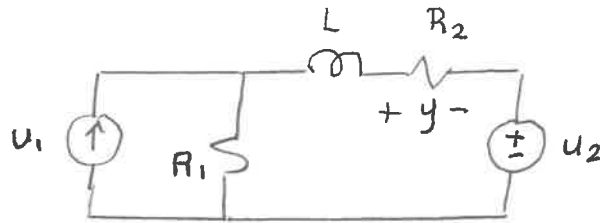
At high freq's
circuit looks like =



(cap looks like a short ckt
at high freq's)

Problem 22

1180



- 1 Determine the system pole, time constant $\tau = \frac{1}{|\text{pole}|}$
 & (1% or 5 time constant) settling time $t_s = 5\tau = \frac{5}{|\text{pole}|}$

without any KVL, KCL, Ohm!

Hint: Set $u_1 = 0$ (open)
 $u_2 = 0$ (short)

Compute impedance =

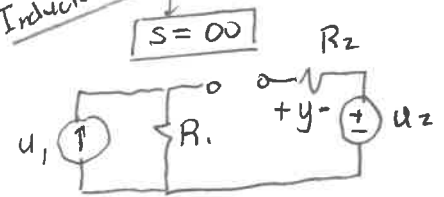
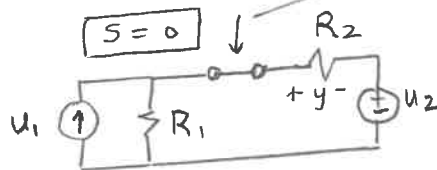
$$Z = R_1 + sL + R_2$$

& see when $Z = 0$.

- 2 Determine $H_1(0), H_2(0)$ & $H_1(\infty), H_2(\infty)$
 by shorting or opening L

Hint =

Inductor $Z_L = sL$ looks like a short at $s=0$
 Inductor $Z_L = sL$ looks like an open at $s=\infty$



- 3 Relate y to u_1, u_2 (in s -domain)
 4 Determine transfer functions H_1, H_2 from u_1 to y & from u_2 to y
 5 Determine diff eq relating y to u_1, u_2 .
 6 Determine characteristic polynomial $\Phi(s)$.
 7 Determine pole of system (characteristic root).
 8 Is system stable, marginally stable, or unstable?
 9 Determine system time constant τ & settling time t_s .
 10 For $R_1 = R_2 = L = 1$, determine y_{ss} when

$$u_1 = 10 + \cos(2t + 45^\circ)$$

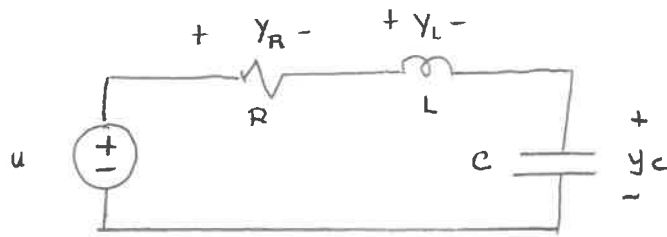
$$u_2 = 100 \sin(200t + 90^\circ)$$

Hint: $-\frac{1}{j200+2} \approx -\frac{1}{200} e^{-j90^\circ} = \frac{1}{200} e^{j(180-90)} = \frac{1}{200} e^{j90}$

Example 23

Intro. to (RLC Circuits)

1190



← 2 energy storage elements = L, C

1 Relate y_R, y_L, y_C to u (in s-domain)

$$\begin{aligned} \text{Ohm} \Rightarrow I &= \frac{U}{Z_{\text{total}}} = \frac{U}{Z_R + Z_L + Z_C} \\ &= \frac{U}{R + sL + \frac{1}{sC}} \quad \left(\begin{array}{l} \text{Multiply} \\ \text{top \& bottom} \\ \text{by } s/L \end{array} \right) \\ &= \left[\frac{\frac{s}{L}}{s^2 + \frac{R}{L}s + \frac{1}{LC}} \right] U \end{aligned}$$

Note: $H_U = \frac{s}{s^2 + \frac{R}{L}s + \frac{1}{LC}}$

↑
Transfer function from u to i

$$\Rightarrow y_R = (R)I = \left[\frac{\frac{R}{L}s}{s^2 + \frac{R}{L}s + \frac{1}{LC}} \right] U$$

$$y_L = (sL)I = \left[\frac{s^2}{s^2 + \frac{R}{L}s + \frac{1}{LC}} \right] U$$

$$y_C = \left(\frac{1}{sC} \right) I = \left[\frac{\frac{1}{LC}}{s^2 + \frac{R}{L}s + \frac{1}{LC}} \right] U$$

2 Find transfer functions from u to y_R, y_L, y_C .

$$H_R = \frac{\frac{R}{L}s}{s^2 + \frac{R}{L}s + \frac{1}{LC}}$$

$$H_L = \frac{s^2}{s^2 + \frac{R}{L}s + \frac{1}{LC}}$$

$$H_C = \frac{\frac{1}{LC}}{s^2 + \frac{R}{L}s + \frac{1}{LC}}$$

Note:

$$\begin{aligned} H_R + H_L + H_C &= \frac{y_R}{U} + \frac{y_L}{U} + \frac{y_C}{U} \\ &= \frac{U}{U} \quad (\text{by KVL}) \\ &= 1 \end{aligned}$$

Example 23

1200

3 Find diff eqs relating y_R, y_L, y_C to u

$$H_R = \frac{y_R}{U} = \frac{\frac{R}{L}s}{s^2 + \frac{R}{L}s + \frac{1}{LC}} \Rightarrow {}^{\infty}y_R + \frac{R}{L} \dot{y}_R + \frac{1}{LC} y_R = \frac{R}{L} \dot{u}$$

$$H_L = \frac{y_L}{U} = \frac{s^2}{s^2 + \frac{R}{L}s + \frac{1}{LC}} \Rightarrow {}^{\infty}y_L + \frac{R}{L} \dot{y}_L + \frac{1}{LC} y_L = \dot{u}$$

$$H_C = \frac{y_C}{U} = \frac{\frac{1}{LC}}{s^2 + \frac{R}{L}s + \frac{1}{LC}} \Rightarrow {}^{\infty}y_C + \frac{R}{L} \dot{y}_C + \frac{1}{LC} y_C = \frac{1}{LC} u$$

4 Char eq (poly) = $\Phi(s)$ = denominator of any system tf
 $= s^2 + \frac{R}{L}s + \frac{1}{LC}$

5 System Poles (Characteristic Roots) =

$$\Phi(s) = s^2 + \frac{R}{L}s + \frac{1}{LC} = 0$$

$$\begin{array}{l} \text{Quadratic} \\ \Rightarrow \\ \text{Formula} \end{array} \quad \begin{array}{l} as^2 + bs + c = 0 \\ s_{1,2} = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} \end{array}$$

$$= \frac{-\left(\frac{R}{L}\right) \pm \sqrt{\left(\frac{R}{L}\right)^2 - 4(1)\left(\frac{1}{LC}\right)}}{2(1)}$$

$$= -\frac{R}{2L} \pm \sqrt{\left(\frac{R}{2L}\right)^2 - \frac{1}{LC}}$$

Lets try to use some basics from quadratics ---

$$\begin{array}{l} \text{Discriminant} \triangleq b^2 - 4ac \\ = \left(\frac{R}{L}\right)^2 - 4(1)\left(\frac{1}{LC}\right) \end{array}$$

Example 23

1210

For what critical value of resistance R_c , is discriminant zero?

$$\text{Discriminant} = \left(\frac{R}{L}\right)^2 - 4\left(1\right)\left(\frac{1}{LC}\right) = 0$$

$$\Rightarrow \left(\frac{R}{L}\right)^2 = \frac{4}{LC}$$

$$\Rightarrow \frac{R}{L} = \frac{2}{\sqrt{LC}}$$

$$\Rightarrow R = \frac{2L}{\sqrt{LC}}$$

$$\text{Discriminant} = 0 \Leftrightarrow R = \boxed{R_c = 2\sqrt{\frac{L}{C}}}$$

From this, we know that there are 3 cases of interest:

Overdamped \rightarrow Discriminant > 0

Critically Damped \rightarrow " " $= 0$

Underdamped \rightarrow " " < 0

$(R > R_c)$ Roots Real, stable, Distinct
resistance "large"

$(R = R_c)$ Roots Real, stable, Repeated

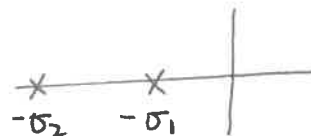
$(0 < R < R_c)$ Roots Complex, stable, Conjugate

For $R = 0$, Roots purely Imaginary, marginally stable, conjugate
"resistance small"

Overdamped

$(\text{Disc} > 0, R > R_c)$ - "large" resistance

$$\begin{aligned} \text{(poles)} \text{ Roots} &= -\frac{R}{2L} \pm \sqrt{\left(\frac{R}{2L}\right)^2 - \frac{1}{LC}} \\ &= -\sigma_1, -\sigma_2 \end{aligned}$$



Fact: We'll see that (unforced)

time solutions look like

decaying exponentials $A_1 e^{-\sigma_1 t}, A_2 e^{-\sigma_2 t}$

roots are real stable distinct

$$\begin{aligned} t_s &= \frac{5\tau}{1} \\ &= \frac{5}{|\text{Re slowest pole}|} \\ &= \frac{5}{\sigma_2} \end{aligned}$$

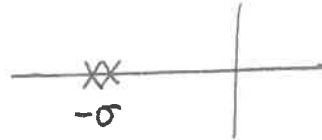


Example 23

1220

Critically Damped ($\text{Disc} = 0, R = R_c$) — "critical" resistance

(poles)
 $\text{Roots} = -\frac{R}{2L} \pm \frac{R}{2L}$
 $= -\sigma, +\sigma$



Fact:

We'll see that (unforced) time solutions look like decaying exponentials
 $A_1 e^{-\sigma t} + A_2 e^{-\sigma t}$



roots are real
stable
repeated

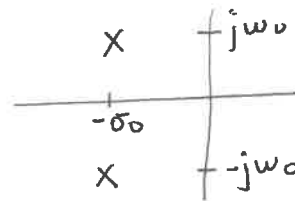
$$t_s = 5\tau$$

$$= \frac{5}{|\text{Re}(\text{slowest pole})|}$$

$$= \frac{5}{\sigma}$$

Underdamped ($\text{Disc} < 0, 0 < R < R_c$) — "small" resistance

(poles)
 $\text{roots} = -\frac{R}{2L} \pm j \sqrt{\frac{1}{LC} - \left(\frac{R}{2L}\right)^2}$
 $= -\sigma_0 \pm j \omega_0$



Fact:

We'll see that (unforced) time solutions look like decaying exponential

Sinusoid:

$$|A_1| e^{-\sigma_0 t} \sin(\omega_0 t + \angle A_1)$$



roots are complex
stable
conjugates

$$t_s = 5\tau$$

$$= \frac{5}{|\text{Re}(\text{poles})|}$$

$$= \frac{5}{|\text{Re}(-\sigma_0 \pm j\omega_0)|}$$

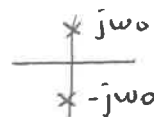
$$= \frac{5}{|-\sigma_0|}$$

$$= \frac{5}{\sigma_0}$$

Note:

For $R = 0$ (No resistance),

(poles)
 $\text{roots} = \pm j \frac{1}{\sqrt{LC}}$

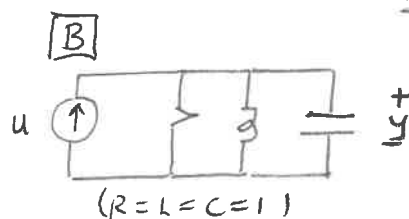
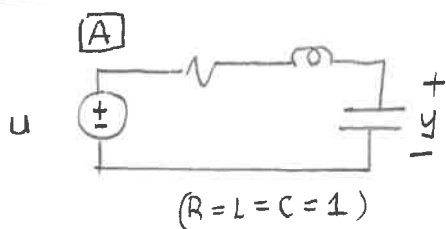


roots are purely imaginary
marginally stable
conjugates

In such a case, we say that the system is Undamped.

Problem 23

1230



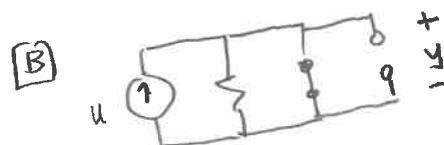
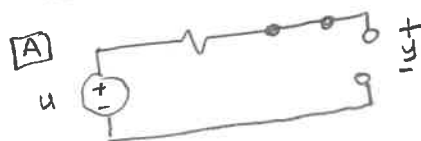
For each circuit:

- 1) Relate y to u (in s-domain)
- 2) Determine transfer function H from u to y
- 3) Determine diff eq relating y to u .
- 4) Determine system characteristic polynomial, poles, time constant τ , settling time t_s . (Is system stable, marginally stable, or unstable?)

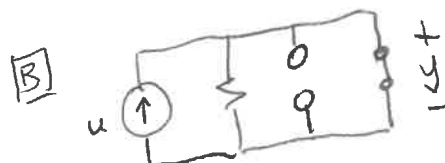
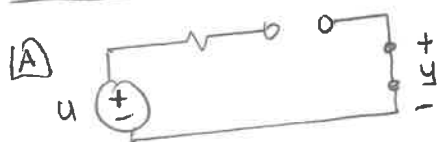
5) Determine y_{ss} when $u(t) = A + B \sin(0.01t - 90^\circ) - C \cos(t + 45^\circ) + D \sin(100t - 30^\circ)$

- 6) Compute $H(0)$ & $H(\infty)$ by shorting or opening L & C .
 Compare what you get here with that using H found in [2] -
 Hint: Use the following
 You MUST get the same answer!

For $s=0$ we have



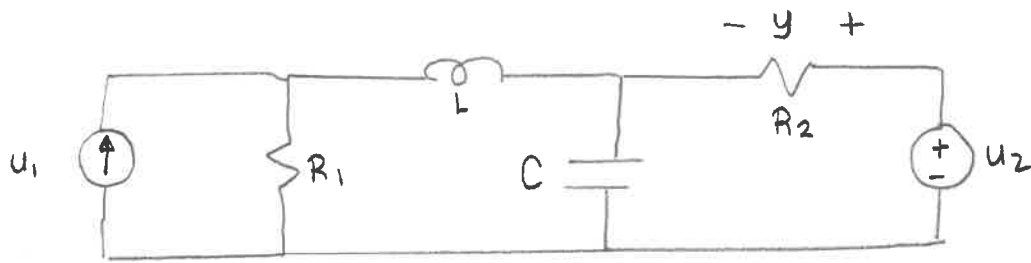
For $s=\infty$ we have



Example 24

(2nd Order RLC Ckt with 2 Sources)

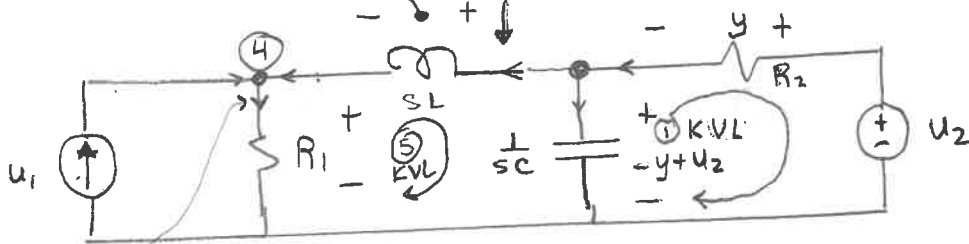
1240



1 Relate y to $u_{1,2}$ (in s -domain)

③ Ohm = $sL \left\{ \frac{y}{R_2} - sc[-y+u_2] \right\}$ ② KCL (+ohm)

Note: Here, I shall use a straight KVL, KCL, Ohm approach.



④ KCL = $u_1 + \left\{ \frac{y}{R_2} - sc[-y+u_2] \right\}$

⑤ KVL = (+ohm)

$$R_1 \left[u_1 + \left\{ \frac{y}{R_2} - sc[-y+u_2] \right\} \right] = -sL \left\{ \frac{y}{R_2} - sc[-y+u_2] \right\} + [-y+u_2]$$

$$y \left[\frac{R_1}{R_2} + R_1 sc + \frac{sL}{R_2} + s^2 LC + 1 \right] = u_1 [-R_1] + u_2 [R_1 sc + s^2 LC + 1]$$

$$LC y \left[\frac{R_1}{R_2 LC} + \frac{R_1 C}{L} s + \frac{sL}{R_2 LC} + \frac{s^2 LC}{LC} + \frac{1}{LC} \right] = u_1 [-R_1] + u_2 LC \left[\frac{R_1 C}{LC} s + \frac{s^2 LC}{LC} + \frac{1}{LC} \right]$$

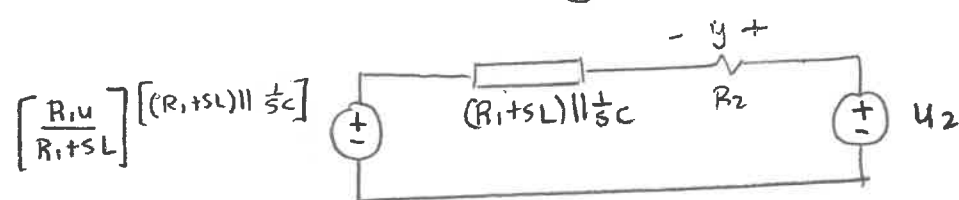
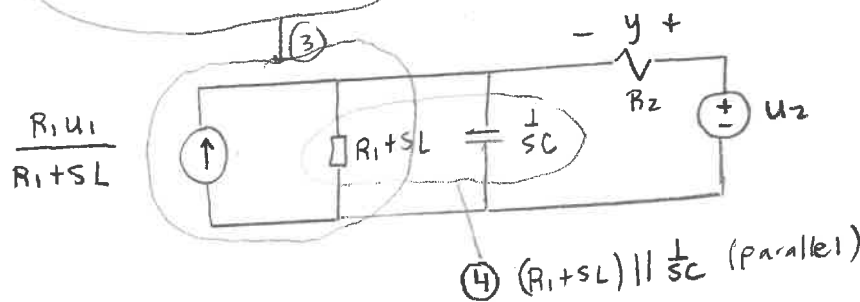
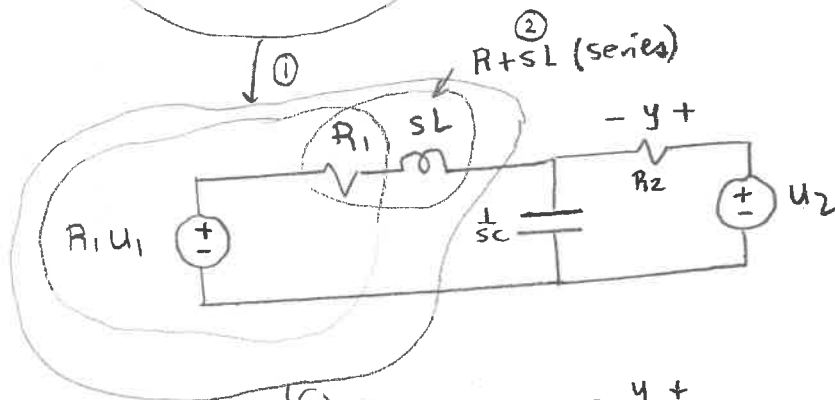
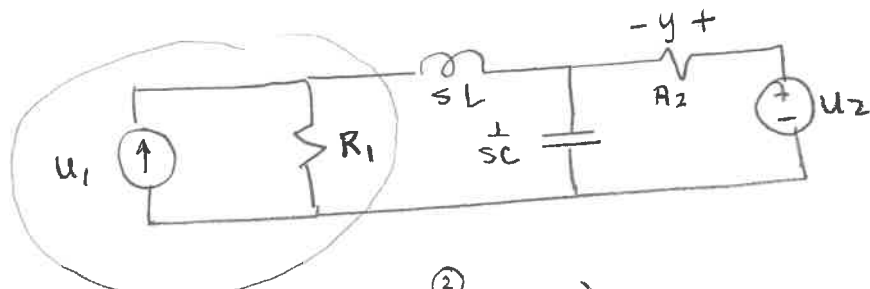
$$y \left[\frac{R_1}{R_2 LC} + \frac{R_1}{L} s + \frac{s}{R_2 C} + s^2 + \frac{1}{LC} \right] = u_1 \left[-\frac{R_1}{LC} \right] + u_2 \left[\frac{R_1}{L} s + s^2 + \frac{1}{LC} \right]$$

Example 24

1250

$$Y = \left[\frac{-\frac{R_1}{LC}}{s^2 + \left(\frac{R_1}{L} + \frac{1}{R_2 C}\right)s + \left(1 + \frac{R_1}{R_2}\right)\frac{1}{LC}} \right] U_1 + \left[\frac{s^2 + \frac{R_1}{L}s + \frac{1}{LC}}{s^2 + \left(\frac{R_1}{L} + \frac{1}{R_2 C}\right)s + \left(1 + \frac{R_1}{R_2}\right)\frac{1}{LC}} \right] U_2$$

Now let's approach the above using source transformations.



← source transformations have permitted us to show precisely what y "directly sees"!

From this KVL (+ ohm) yields

$$\left[\frac{R_1 U}{R_1 + sL} \right] \left[(R_1 + sL) \parallel \frac{1}{sC} \right] = - \left[(R_1 + sL) \parallel \frac{1}{sC} \right] \frac{y}{R_2} - y + U_2$$

After a little algebra, we get:

$$y \left[\frac{(R_1 + SL) \parallel \frac{1}{SC}}{R_2} + 1 \right] = - \left\{ \frac{[(R_1 + SL) \parallel \frac{1}{SC}] R_1}{R_1 + SL} \right\} u_1 + u_2$$

or

$$y = - \left[\frac{\frac{R_1 [(R_1 + SL) \parallel \frac{1}{SC}]}{R_1 + SL}}{1 + \frac{(R_1 + SL) \parallel \frac{1}{SC}}{R_2}} \right] u_1 + \left[\frac{1}{1 + \frac{(R_1 + SL) \parallel \frac{1}{SC}}{R_2}} \right] u_2$$

↑
This is the cleanest form of the relationship between y, u_1, u_2, \dots because it is fundamentally based on what y "directly sees."

Lets do some algebra ---

$$(R_1 + SL) \parallel \frac{1}{SC} = \frac{\frac{R_1 + SL}{SC}}{R_1 + SL + \frac{1}{SC}}$$

$$y = \left[\frac{\frac{-\frac{R_1}{SC}}{R_1 + SL + \frac{1}{SC}}}{1 + \frac{\frac{R_1 + SL}{R_2 SC}}{R_1 + SL + \frac{1}{SC}}} \right] u_1 + \left[\frac{1}{1 + \frac{\frac{R_1 + SL}{R_2 SC}}{R_1 + SL + \frac{1}{SC}}} \right] u_2$$

$$= \left[\frac{-\frac{R_1}{SC}}{R_1 + SL + \frac{1}{SC} + \frac{R_1 + SL}{R_2 SC}} \right] u_1 + \left[\frac{R_1 + SL + \frac{1}{SC}}{R_1 + SL + \frac{1}{SC} + \frac{R_1 + SL}{R_2 SC}} \right] u_2$$

Example 24

1270

Multiplying top & bottom by s/L yields =

$$y = \left[\frac{-\frac{R_1}{LC}}{\frac{R_1}{L}s + s^2 + \frac{1}{LC} + \frac{R_1 + sL}{R_2 LC}} \right] u_1 + \left[\frac{\frac{R_1}{L}s + s^2 + \frac{1}{LC}}{\frac{R_1}{L}s + s^2 + \frac{1}{LC} + \frac{R_1 + sL}{R_2 LC}} \right] u_2$$

$$= \left[\frac{-\frac{R_1}{LC}}{s^2 + \left(\frac{R_1}{L} + \frac{1}{R_2 C}\right)s + \left(1 + \frac{R_1}{R_2}\right)\frac{1}{LC}} \right] u_1 + \left[\frac{s^2 + \frac{R_1}{L}s + \frac{1}{LC}}{s^2 + \left(\frac{R_1}{L} + \frac{1}{R_2 C}\right)s + \left(1 + \frac{R_1}{R_2}\right)\frac{1}{LC}} \right] u_2$$

This is what we got earlier via KVL, KCL, Ohm!



2 Find transfer functions $H_{1,2}$ from $u_{1,2}$ to y .

$$H_1 = \frac{-\frac{R_1}{LC}}{s^2 + \left(\frac{R_1}{L} + \frac{1}{R_2 C}\right)s + \left(1 + \frac{R_1}{R_2}\right)\frac{1}{LC}}$$

$$H_2 = \frac{s^2 + \frac{R_1}{L}s + \frac{1}{LC}}{s^2 + \left(\frac{R_1}{L} + \frac{1}{R_2 C}\right)s + \left(1 + \frac{R_1}{R_2}\right)\frac{1}{LC}}$$

3 Determine the differential eq relating y to $u_{1,2}$.

$$\overset{00}{y} + \left(\frac{R_1}{L} + \frac{1}{R_2 C}\right) \overset{0}{y} + \left(1 + \frac{R_1}{R_2}\right) \frac{1}{LC} y = -\frac{R_1}{LC} u_1 + \overset{00}{u_2} + \frac{R_1}{L} \overset{0}{u_2} + \frac{1}{LC} u_2$$

4 Characteristic eq (polynomial) =

$$\begin{aligned}\Phi(s) &= \text{denominator of } H_1 \text{ or } H_2 \\ &= s^2 + \left(\frac{R_1}{L} + \frac{1}{R_2 C}\right)s + \left(1 + \frac{R_1}{R_2}\right)\frac{1}{LC}\end{aligned}$$

Note =

Any 2nd order characteristic polynomial may be written as

$$\Phi(s) = s^2 + 2\zeta\omega_n s + \omega_n^2$$

where

$\omega_n \triangleq$ undamped natural frequency

$\zeta \triangleq$ damping factor

For our characteristic polynomial

$$\omega_n^2 = \left(1 + \frac{R_1}{R_2}\right)\frac{1}{LC} \Rightarrow \omega_n = \sqrt{1 + \frac{R_1}{R_2}} \left(\frac{1}{\sqrt{LC}}\right)$$

$$2\zeta\omega_n = \frac{R_1}{L} + \frac{1}{R_2 C} \Rightarrow \zeta = \frac{\frac{R_1}{L} + \frac{1}{R_2 C}}{2\sqrt{1 + \frac{R_1}{R_2}} \left(\frac{1}{\sqrt{LC}}\right)}$$

5 poles (characteristic roots) =

$$\begin{aligned}s_{1,2} &= \frac{-2\zeta\omega_n \pm \sqrt{(2\zeta\omega_n)^2 - 4\omega_n^2}}{2} \\ &= -\zeta\omega_n \pm \omega_n \sqrt{\zeta^2 - 1}\end{aligned}$$

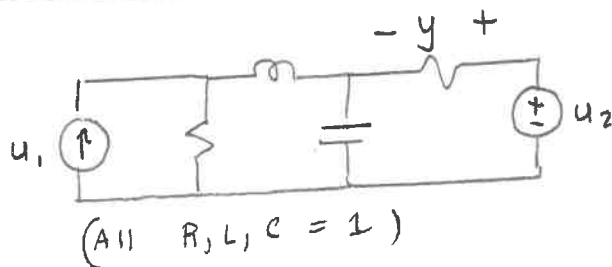
This will now get some special attention!



Problem 24

(2nd order RLC Ckt with 2 Sources)

1290



- 1) Relate y to u_1, u_2 (in s -domain).
- 2) Determine transfer functions H_1, H_2 from u_1 to y , & from u_2 to y .
- 3) Determine diff eq relating y to u_1, u_2 .
- 4) Determine system characteristic equation, poles, stability of system, time constant τ , settling time t_s .
- 5) Determine y_{ss} when $u_1 = 10 - 3 \cos(\sqrt{2}t + 90^\circ) + \sin(0.01t)$
 $u_2 = -4 + \sin t - \cos(200t + 45^\circ)$

Example 25 (2nd order systems & damping factor)

(RLC Series Cct)

1300

As stated above,

Any 2nd order characteristic polynomial may be written as =

$$\Phi(s) = s^2 + 2\zeta \omega_n s + \omega_n^2$$

where

$\omega_n \triangleq$ undamped natural frequency

$\zeta \triangleq$ damping factor

The associated characteristic roots (system poles)

are =

$$s_{1,2} = -\zeta \omega_n \pm \omega_n \sqrt{\zeta^2 - 1}$$

3 Special Cases Are Universally Considered.
... lets examine the 3 special cases ---

Case 1 =

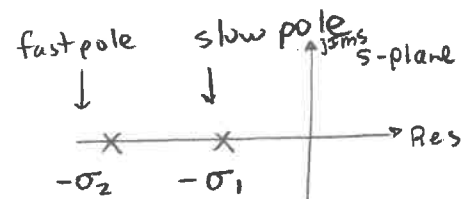
Overdamped ($\zeta > 1$)

For this case, the poles are

$$-\sigma_2 = -\zeta \omega_n - \omega_n \sqrt{\zeta^2 - 1}, \quad -\sigma_1 = -\zeta \omega_n + \omega_n \sqrt{\zeta^2 - 1}$$

As such, the poles are

real
stable
distinct



The associated settling time is $t_s = \frac{5}{\sigma_1}$ (associated with the slow pole)

Example 25

1310

Case 2 =

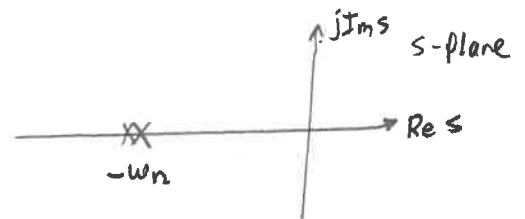
Critically Damped ($\zeta = 1$)

For this case, the poles are

$$-w_n, -w_n$$

As such, the poles are

real
stable
repeated



The associated settling time is $t_s = \frac{5}{w_n}$

Case 3 :

Under Damped ($0 < \zeta < 1$)

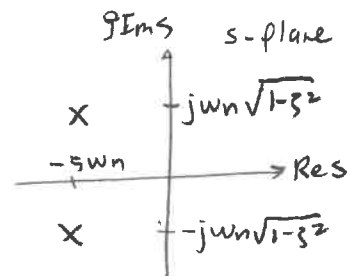
For this case, the poles are

$$s_{1,2} = -\zeta w_n \pm j w_n \sqrt{1-\zeta^2}$$

$$= -\sigma_0 \pm j \omega_0$$

$$\sigma_0 = \zeta w_n$$

$$\omega_0 = w_n \sqrt{1-\zeta^2}$$



As such, the poles are

complex
stable
conjugate

This is why ζ is called the undamped natural frequency of the system.

The associated settling time is

$$t_s = \frac{5}{|Re \text{ poles}|} = \frac{5}{|-\sigma_0|} = \frac{5}{\sigma_0} = \frac{5}{\zeta w_n}$$

Notes:

For $\zeta = 0$, the system is undamped, the poles are purely imaginary

$$s_{1,2} = \pm j w_n$$

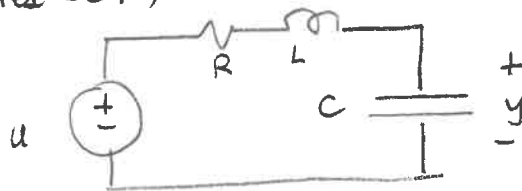
\Rightarrow the system is marginally stable!

Example 25

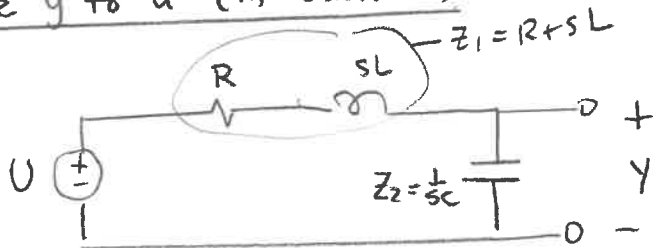
(RLC Series Ckt)

1320

Consider the RLC ckt =



1) Relate y to u (in s -domain)



$$Y = \left(\frac{Z_2}{Z_1 + Z_2} \right) U = \left(\frac{\frac{1}{sC}}{(R + sL) + \frac{1}{sC}} \right) U \quad \frac{s}{L} \left[\frac{\frac{1}{LC}}{s^2 + \frac{R}{L}s + \frac{1}{LC}} \right] U$$

2) What is transfer function^H from u to y ?

$$H = \frac{\frac{1}{LC}}{s^2 + \frac{R}{L}s + \frac{1}{LC}}$$

3) Determine diff eq relating y to u

$$y'' + \frac{R}{L}y' + \frac{1}{LC}y = \frac{1}{LC}u$$

4) Char eq (poly) =

$$\begin{aligned} \Phi(s) &= \text{denominator of } H \\ &= s^2 + \frac{R}{L}s + \frac{1}{LC} \end{aligned}$$

If we write $\Phi(\cdot)$ as

$$\Phi(s) = s^2 + 2\zeta\omega_n s + \omega_n^2$$

determine ω_n, ζ -

$$\omega_n^2 = \frac{1}{LC} \Rightarrow \omega_n = \frac{1}{\sqrt{LC}}$$

$$2\zeta\omega_n = \frac{R}{L} \Rightarrow \zeta = \frac{R}{2L\omega_n} = \frac{R}{2L} \sqrt{LC} = \frac{R}{2} \sqrt{\frac{C}{L}}$$

Note:
 $\zeta = 1$ for
 $R = R_c = 2\sqrt{\frac{L}{C}}$

Example 25

(RLC Series Cct)

1330

5 poles (characteristic roots) =

$$s_{1,2} = -\zeta \omega_n \pm \omega_n \sqrt{\zeta^2 - 1}$$

We now consider 3 cases for our circuit =

occurs for
↓
(R > R_c)

Case 1: Overdamped ($\zeta > 1$)

For this case, the poles are

$$-\sigma_2 = -\zeta \omega_n - \omega_n \sqrt{\zeta^2 - 1}, \quad -\sigma_1 = -\zeta \omega_n + \omega_n \sqrt{\zeta^2 - 1}$$

fast pole
slow pole
↓
↓

⇒ The poles are real, stable, & distinct (different)

The associated settling time is

$$t_s = \frac{5}{\sigma_1}$$

↳ is associated with the system's

"slow pole"

$$R_c = 2\sqrt{\frac{L}{C}} = 2\sqrt{\frac{1}{2}} = 2\sqrt{2} < R = 3$$

Here are representative numbers =

$$R = 3 \quad L = 1 \quad C = \frac{1}{2}$$

$$H = \frac{\frac{1}{C}}{s^2 + \frac{R}{L}s + \frac{1}{LC}} = \frac{2}{s^2 + 3s + 2} = \frac{2}{(s+1)(s+2)}$$

$\omega_n = \sqrt{2} \Rightarrow \zeta = \frac{3/2}{\omega_n} = \frac{1.5}{\sqrt{2}} > 1$
 $t_s = 5 \text{ sec}$

23 $\omega_n = 3$

Example 25

(RLC Series Ckt)

1340

Case 2 =

Critically Damped ($\zeta = 1$)

occurs for
($R = R_c$)

For this case, the poles are

$$-\omega_n, -\omega_n$$



\Rightarrow The poles are real, stable, & repeated (identical).

The associated settling time is

$$t_s = \frac{5}{\omega_n}$$

Here are representative numbers =

$$R = 2 \quad L = C = 1$$

$$R_c = 2\sqrt{\frac{L}{C}} = 2 = R$$

$$\Rightarrow H = \frac{\frac{1}{LC}}{s^2 + \frac{R}{L}s + \frac{1}{LC}} = \frac{1}{s^2 + 2s + 1} = \left[\frac{1}{s+1} \right]^2$$

$$\omega_n = 1$$

$$2\zeta\omega_n = 2 \Rightarrow \zeta = 1$$



Example 25

(RLC Series Ckt)

1350

Case 3 =

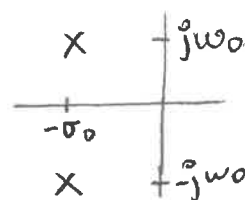
Under Damped ($0 < \zeta < 1$)

Occurs
for
↓
($0 < R < R_c$)

For this case, the poles are

$$s_{1,2} = -\zeta \omega_n \pm j \omega_n \sqrt{1-\zeta^2}$$

$$= -\sigma_0 \pm j \omega_0$$



As such, the poles are complex, stable, & conjugates of one another.

The associated settling time is

$$t_s = \frac{5}{|\text{Re poles}|} = \frac{5}{\sigma_0}$$

Here are representative numbers =

$$R = L = C = 1$$

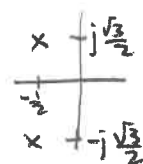
$$R_c = 2\sqrt{\frac{L}{C}} = 2 > R = 1$$

$$H = \frac{\frac{1}{LC}}{s^2 + \frac{R}{L}s + \frac{1}{LC}} = \frac{1}{s^2 + s + 1}$$

$$\omega_n = 1$$

$$2\zeta \omega_n = 1 \Rightarrow \zeta = \frac{1}{2} < 1$$

$$\text{poles} = \frac{-1 \pm \sqrt{1-4(1)(1)}}{2} = -\frac{1}{2} \pm j \frac{\sqrt{3}}{2}$$

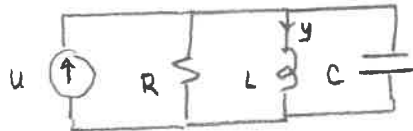


$$t_s = \frac{5}{|\text{Re poles}|} = \frac{5}{\frac{1}{2}} = 10 \text{ sec}$$

Problem 25

(RLC Parallel Ckt)

1360



- 1) Relate y to u (in s -domain)
- 2) Find transfer function H from u to y & diff eq relating y to u
- 3) Determine system characteristic polynomial, poles, stability.

Let $L = C = 1$

- 4) Determine R such that

a) poles = $-\frac{1}{2}, -2$

b) poles = $-1, -1$

c) poles = $-1 \pm j1$

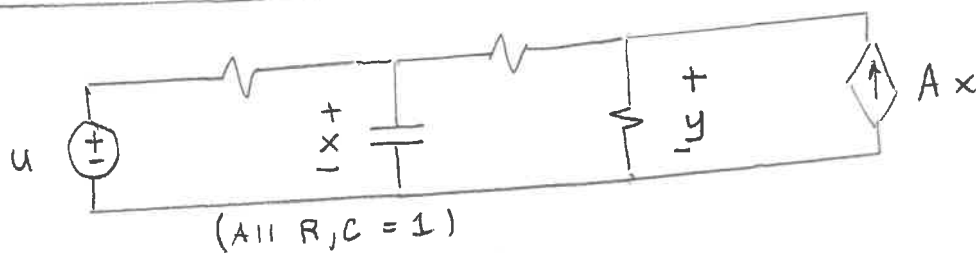
Let R be that for case c.

- 5) Determine y_{ss} when $u(t) = A + B \cos(0.01t + 5^\circ)$
 $- C \sin(t + 190^\circ)$
 $+ D \cos(100t + 135^\circ)$

Example 26

(RC Cct with Dependent Source)

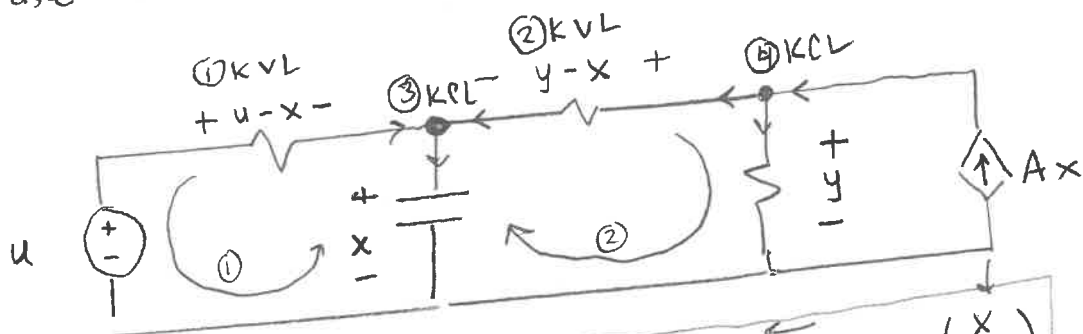
1370



① Relate y to u (in s -domain)

Need 2 eqs in 2 unknowns (x, y)

Use one to eliminate x & ~~then~~ solve for y !



③ KCL =
(+Ohm)

$$\left(\frac{u-x}{1} \right) + \left(\frac{y-x}{1} \right) = \left(\frac{x}{1/s} \right)$$

$$u+y = x[s+2]$$

④ KCL =
(+Ohm)

$$Ax = \left(\frac{y-x}{1} \right) + \left(\frac{y}{1} \right)$$

$$\Rightarrow (A+1)x = 2y$$

$$\Rightarrow x = \left(\frac{2}{A+1} \right) y$$

$$\Rightarrow u+y = \left(\frac{2}{A+1} \right) y [s+2]$$

$$\Rightarrow \left(\frac{A+1}{2} \right) u + \left(\frac{A+1}{2} \right) y = y[s+2]$$

$$\Rightarrow y \left[s+2 - \frac{A+1}{2} \right] = \left(\frac{A+1}{2} \right) u$$

$$\Rightarrow y [2s+4-A-1] = (A+1)u$$

$$y [2s+3-A] = (A+1)u$$

Example 26 (RC Cct with Dependant Source) 1380

$$\Rightarrow y = \left[\frac{\left(\frac{A+1}{2}\right)}{s + \left(\frac{3-A}{2}\right)} \right] u$$

[2] Determine transfer function H from u to y.

$$H(s) = \frac{\frac{A+1}{2}}{s + \left(\frac{3-A}{2}\right)}$$

[3] Determine diff eq relating y to u.

$$\dot{y} + \left(\frac{3-A}{2}\right)y = \left(\frac{A+1}{2}\right)u$$

[4] Determine ^{system} characteristic eq & pole.

$$\Phi(s) = s + \left(\frac{3-A}{2}\right) = 0$$

$$\Rightarrow \text{pole} = - \left[\frac{3-A}{2} \right]$$

Note = System is stable $\iff A < 3$ (so that pole < 0)
marginally stable $\iff A = 3$ (so that pole $= 0$)
unstable $\iff A > 3$ (so that pole > 0)

Lets suppose that $A < 3$ so that our system
pole $= - \left(\frac{3-A}{2}\right) < 0$ } hence the system is stable!

Example 26

(RC Cct with Dependent Source)

1390

5 Determine the system time constant τ & settling time t_s .

$$\begin{aligned}\tau &= \frac{1}{|\operatorname{Re}(\text{slowest pole})|} = \frac{1}{|\operatorname{Re}(-(\frac{3-A}{2}))|} \\ &= \frac{1}{|-(\frac{3-A}{2})|} \\ &= \frac{2}{3-A} \\ &= \frac{2}{3-A} \quad (>0 \text{ since } A < 3)\end{aligned}$$

$$t_s = 5\tau = \frac{5}{|\operatorname{Re}(\text{slowest pole})|} = \frac{10}{3-A}$$

Note: One could choose A in order to achieve a specific t_s !

... that is design!!! 😊

Now let $A=2$.

This yields

$$H(s) = \frac{\frac{A+1}{2}}{s + (\frac{3-A}{2})} = \frac{\frac{2+1}{2}}{s + (\frac{3-2}{2})} = \frac{\frac{3}{2}}{s + \frac{1}{2}}$$

stable LHP pole
↓
-1/2

$$\Rightarrow \tau = 2$$

$$t_s = 5\tau = 10 \text{ sec}$$

Example 26 (RC Ckt with Dependent Source)

1400

6 Determine y_{ss} when $u = A + B \sin(0.05t + 25^\circ) + C \cos(\frac{1}{2}t + 135^\circ) + D \sin(50t + 120^\circ)$

By MOTF =

$$y_{ss} = AH(0) + B|H(j0.05)| \sin(0.05t + 25^\circ + \angle H(j0.05)) + C|H(j\frac{1}{2})| \cos(\frac{1}{2}t + 135^\circ + \angle H(j\frac{1}{2})) + D|H(j50)| \sin(50t + 120^\circ + \angle H(j50))$$

Recalling that

$$H(s) = \frac{3/2}{s + 1/2}$$

We now compute each of the quantities (involving H), required above.

$$H(0) = \frac{3/2}{1/2} = 3$$

$$H(j0.05) = \frac{3/2}{j0.05 + 1/2} \approx \frac{3/2}{0 + 1/2} = 3 = 3e^{j0}$$

Magnitude = 3
Angle = 0 (\pm integer multiple of 360°)
... convention is to take 0° as angle of any positive real #!

$$H(j50) = \frac{3/2}{j50 + 1/2} \approx \frac{3/2}{j50} = \frac{3/2}{50e^{j90^\circ}} = 0.03e^{-j90^\circ}$$

$j0.05$ - 10 times smaller than 0.5 (hence negligible)
 $\frac{1}{2} = 0.5$
 $50 = 100$ times larger than $0.5 = \frac{1}{2}$
 $j50 = 50e^{j90^\circ}$
polar form
rectangular form

Example 26

1410

$$H(j\frac{1}{2}) = \frac{3/2}{j\frac{1}{2} + \frac{1}{2}} = \frac{\cancel{\frac{1}{2}} (3)}{\cancel{\frac{1}{2}} (j1+1)} = \frac{3}{1+j1} = \frac{3}{\sqrt{2}e^{j45^\circ}} = \frac{3}{\sqrt{2}}e^{-j45^\circ}$$

Diagram illustrating the conversion of $1+j1$ to polar form:

- Rectangular form: $1+j1$ (represented by a right triangle with sides 1 and 1, and hypotenuse $\sqrt{2}$ at 45°)
- Polar form: $\sqrt{2}e^{j45^\circ}$

On an exam, the above suffices!

Here, for completeness, I shall show where everything we computed goes:

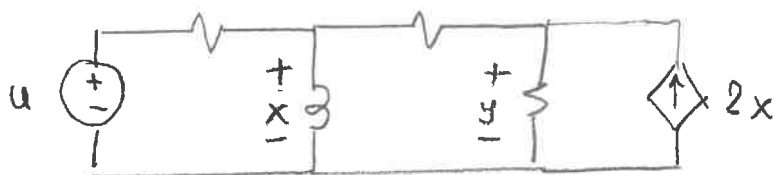
$$y_{ss} = A \overset{\sim 3}{H(0)} + B \overset{\sim 3}{|H(j0.05)|} \sin(0.05t + 25^\circ + \overset{\sim 0^\circ}{|H(j0.05)|}) + C \overset{\frac{3}{\sqrt{2}}}{|H(j\frac{1}{2})|} \cos(\frac{1}{2}t + 135^\circ + \overset{-45^\circ}{|H(j\frac{1}{2})|}) + D \overset{\sim 0.03}{|H(j50)|} \sin(50t + 120^\circ + \overset{\sim -90^\circ}{|H(j50)|})$$

Please review your complex arithmetic!

Problem 26

(RL Cct with Dependent Source)

1420

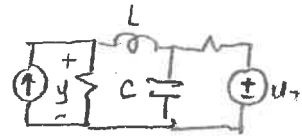
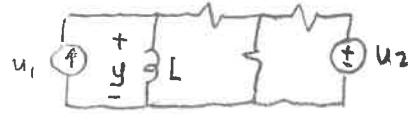
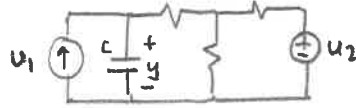


(All $R = L = 1$)

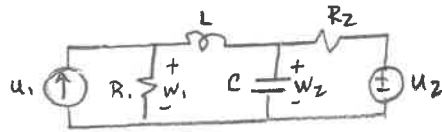
- 1 Relate y to u (in s -domain)
- 2 Determine transfer function[†] from u to y & diff eq
- 3 Determine system characteristic polynomial, pole, stability, time constant τ , & settling time t_s
- 4 Determine y_{ss} when $u = A - B \cos(0.02t + 30^\circ) + C \sin(2t + 45^\circ) - D \cos(300t + 90^\circ)$

Circuits You Should Examine

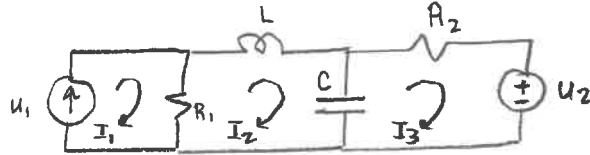
[10] Pg 270



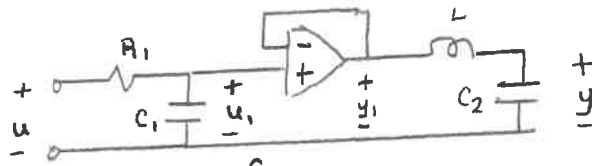
[11] Nodal
Pg 310



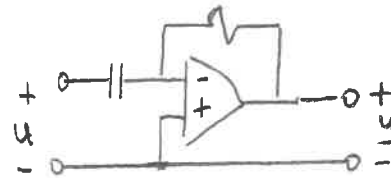
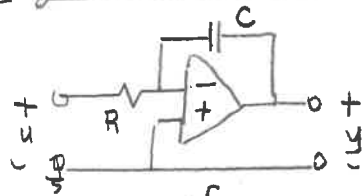
[12] Mesh
Pg 340



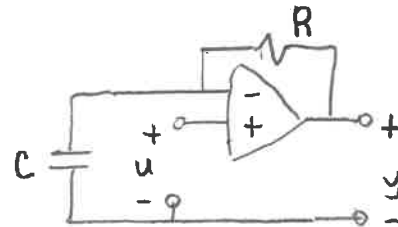
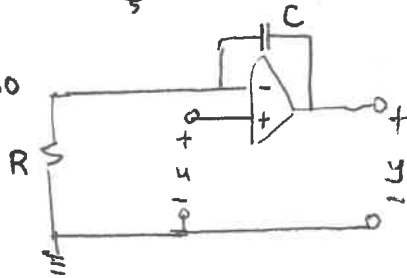
[13] Pg 410



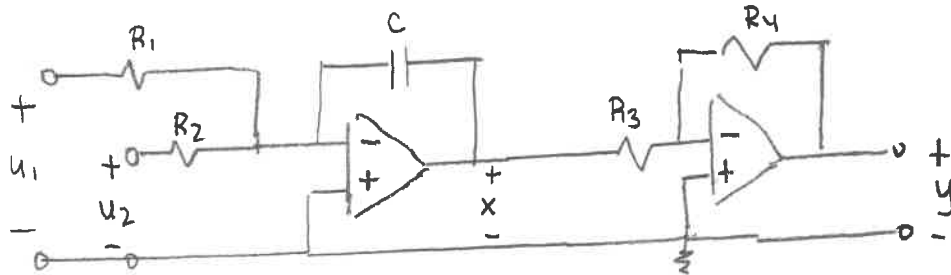
[14] Pg 430



[15] Pg 460

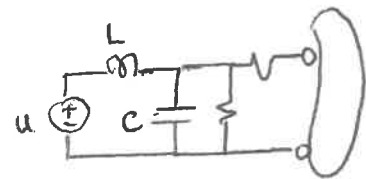
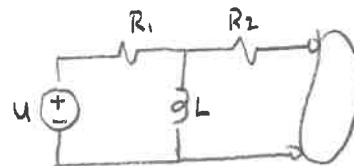
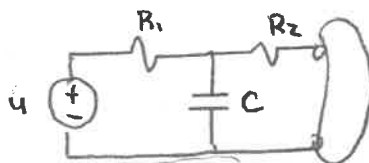


[16] Pg 480

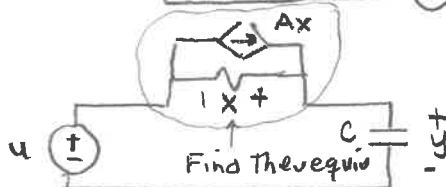


[17] Pg 510 Source Transformations (see [7] s pg 170)

[18] Thevenin
Pg 540



[19] Pg 610

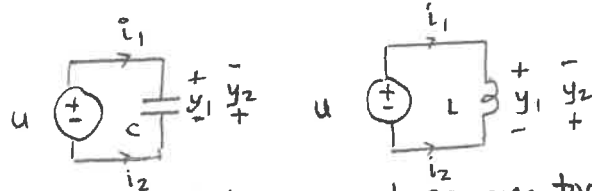


$$A = \frac{1}{R} - \frac{1}{R_{eq}}$$

Circuits You Should Examine

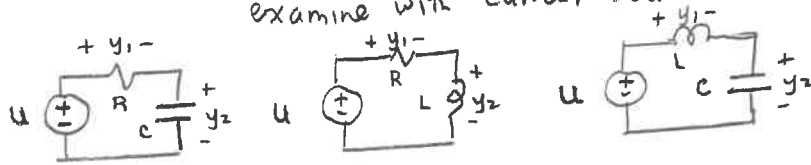
Like Example 1

[1] pg 20

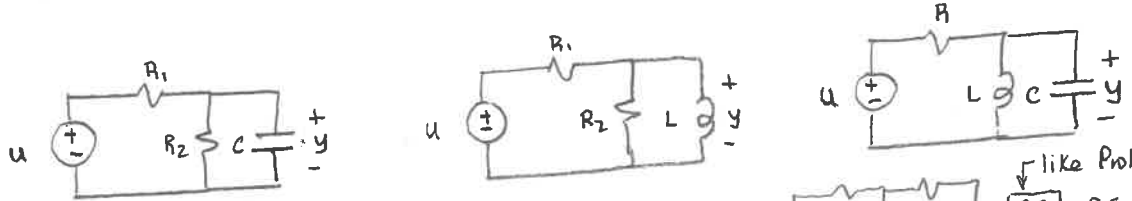


examine with current sources too!

[2] pg 50



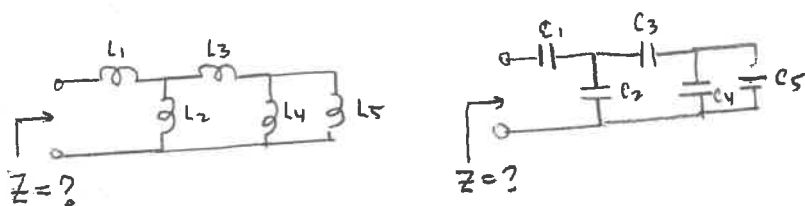
[3] pg 70



... can move L & C around!

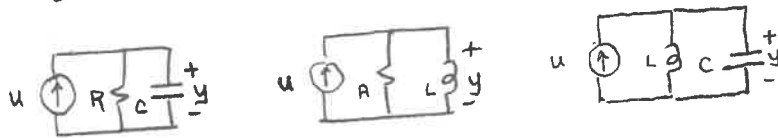
like Problem 3
[P3] pg 100
(sub c with L too!)

[4] pg 110



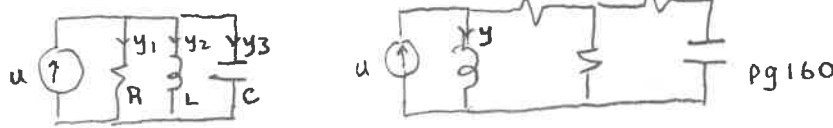
Z = ?
Z = ?
Z = ?

[5] pg 130

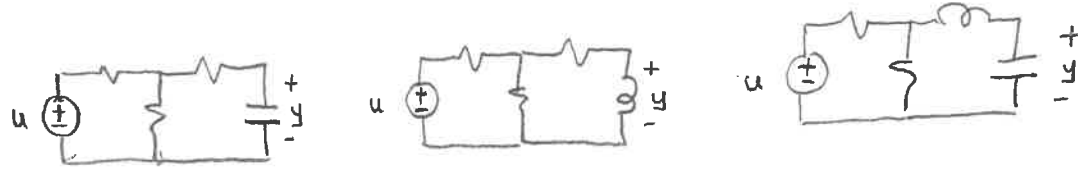


[P5] pg 140
Z = ?
Z = ?
Z = ?

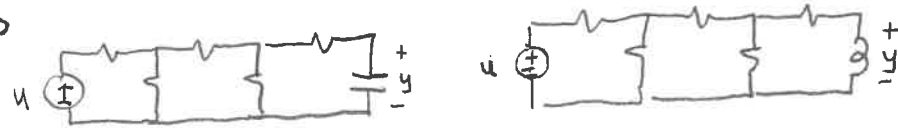
[6] pg 150



[7] pg 170

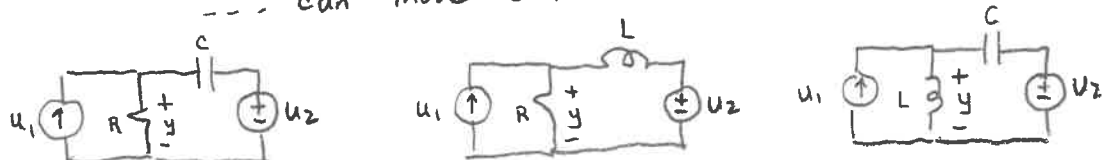


[8] pg 220



... can move C & L ground too!

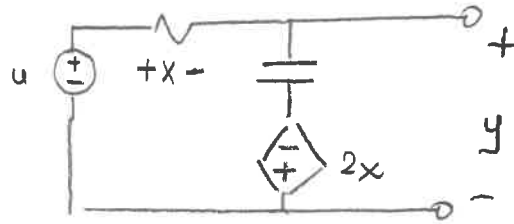
[9] pg 240



... can move C & L around too!

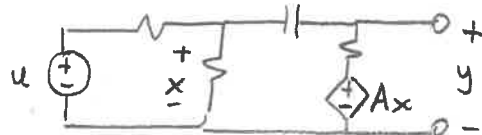
Circuits You Should Examine

[20] pg 720

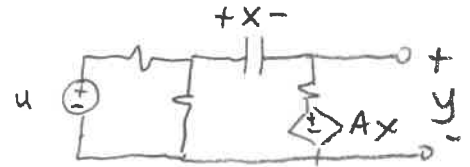


$$R=C=1$$

[P20] pg 820



$$R_i = C = 1 \text{ (relate } y \text{ to } u)$$



$$R_i = C = 1 \text{ (relate } y \text{ to } u)$$

[21] pg 830

